

AD-A102 841

GENERAL ELECTRIC CO PITTSFIELD MA ORDNANCE SYSTEMS
ELECTRICAL CHARACTERIZATION AND SPECIFICATION OF PERIPHERAL DRI--ETC(U)
MAY 81 J S KULPINSKI, T HACK, T SIMONSEN F30602-80-C-0057

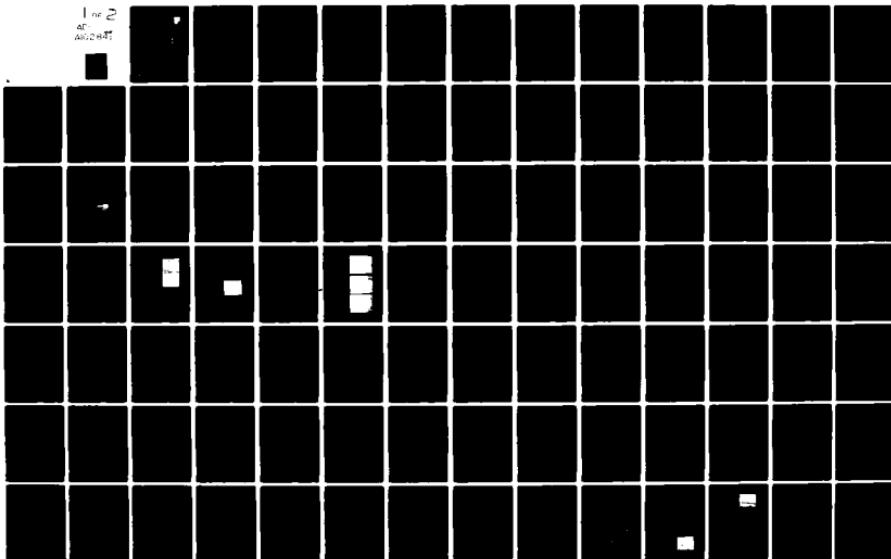
F/6 9/5

RADC-TR-81-72

NL

UNCLASSIFIED

1 of 2
AF
AMZ:AT



AD A102841

RADC-TR-81-72
Final Technical Report
May 1981

LEVEL II

12



ELECTRICAL CHARACTERIZATION AND SPECIFICATION OF PERIPHERAL DRIVERS, CORE DRIVERS AND MULTIPLYING DACs

General Electric Ordnance Systems

John S. Kulpinski, et al

DTIC
ELECTE
S D
AUG 14 1981
E

APPROVED FOR PUBLIC RELEASE; DISTRIBUTION UNLIMITED

DTIC FILE COPY

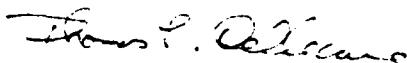
ROME AIR DEVELOPMENT CENTER
Air Force Systems Command
Griffiss Air Force Base, New York 13441

818 14 055

This report has been reviewed by the RADC Public Affairs Office (PA) and is releasable to the National Technical Information Service (NTIS). At NTIS it will be releasable to the general public, including foreign nations.

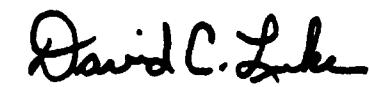
RADC-TR-81-72 has been reviewed and is approved for publication.

APPROVED:



THOMAS L. DELLECAVE
Project Engineer

APPROVED:



DAVID C. LUKE, Colonel, USAF
Chief, Reliability & Compatibility Division

FOR THE COMMANDER:



JOHN P. HUSS
Acting Chief, Plans Office

If your address has changed or if you wish to be removed from the RADC mailing list, or if the addressee is no longer employed by your organization, please notify RADC (RBRA) Griffiss AFB NY 13441. This will assist us in maintaining a current mailing list.

Do not return this copy. Retain or destroy.

UNCLASSIFIED

SECURITY CLASSIFICATION OF THIS PAGE When Data Entered)

1 / REPORT DOCUMENTATION PAGE		READ INSTRUCTIONS BEFORE COMPLETING FORM
1 REPORT NUMBER RADC TR-81-72	2 GOVT ACCESSION NO. <i>AD-A102 842</i>	3 RECIPIENT'S CATALOG NUMBER
4. TITLE (and Subtitle) ELECTRICAL CHARACTERIZATION AND SPECIFICATION OF PERIPHERAL DRIVERS, CORE DRIVERS AND MULTIPLYING DACS.		5. TYPE OF REPORT & PERIOD COVERED Final Technical Report, Jan 80 - Jan 81
7 AUTHOR(s) John S. Kulpinski, et al.		6. PERFORMING ORG REPORT NUMBER N/A
9. PERFORMING ORGANIZATION NAME AND ADDRESS General Electric Ordnance Systems Electroic Systems Division Pittsfield MA 01201		10. PROGRAM ELEMENT PROJECT TASK AREA & WORK UNIT NUMBERS 62702F 23380186
11. CONTROLLING OFFICE NAME AND ADDRESS Rome Air Development Center (RBRA) Griffiss AFB NY 13441		12. REPORT DATE May 1981
14. MONITORING AGENCY NAME & ADDRESS (if different from Controlling Office) Same		13. NUMBER OF PAGES 120
		15. SECURITY CLASS. OF THIS REPORT UNCLASSIFIED
		15A. DECLASSIFICATION DOWNGRADING SCHEDULE IN/A
16. DISTRIBUTION STATEMENT (of this Report) Approved for public release; distribution unlimited.		
17. DISTRIBUTION STATEMENT (of the abstract ente) John S. /Kulpinski Thomas /Hack Theodore /Simonsen Larry /Deluca John /Dunn Same		
18. SUPPLEMENTARY NOTES RADC Project Engineer: Thomas L. DeLeece (RBRA)		
19. KEY WORDS (Continue on reverse side if necessary and identify by block number) Reliability Interface Microcircuit Characterization		
20. ABSTRACT (Continue on reverse side if necessary and identify by block number) This report covers the work performed by General Electric Ordnance Systems Division pertaining to the electrical characterization and specification of interface types of microcircuits. The period of report is January 1980 to January 1981. The main thrust of this electrical characterization effort was directed at high military usage peripheral and core drivers and multiplying CMOS digital to analog converters. The		

UNCLASSIFIED

SECURITY CLASSIFICATION OF THIS PAGE(When Data Entered)

following device types were evaluated:

Peripheral Drivers - 55450 and 55460 family,

Core Drivers - 55325/6/7; and

Multiplying CMOS DACs - 7520 family.

Data obtained during device characterization is published in handbook form and is available under separate cover from this document. However, samples of data sheets, histograms and plots are included in this report.

UNCLASSIFIED

SECURITY CLASSIFICATION OF THIS PAGE(When Data Entered)

PREFACE

This report was prepared by General Electric Ordnance Systems, 100 Plastics Avenue, Pittsfield, Massachusetts, for Rome Air Development Center, Griffiss Air Force Base, Rome, New York, under contract F30602-80-C-0057. It covers the period from January 1980 to January 1981.

The work on this project was performed by the Electronic Circuits Engineering Operation of Ordnance Systems. Project responsibility was held by Mr. John Kulpinski of Circuit Design Engineering. Key individuals who made significant contributions to this work effort were Messrs. Thomas Hack and Theodore Simonsen of Circuit Design Engineering and Messrs. Larry Deluca, John Dunn, Robert Mossman and Jamie Schwehr of Circuit Test Engineering.

Mr. Thomas Dellecave, RBRA, is the Project Engineer at RADC for this contract.

Accession For	
NTIS GRAFI	<input checked="" type="checkbox"/>
DTIC TAB	<input type="checkbox"/>
Unrestricted	<input type="checkbox"/>
Justification	
By	
Distribution	
Available to Allies	
Available to Non- Belligerent Nations	
Distr	Approved
A	

ELECTRICAL CHARACTERIZATION AND SPECIFICATION OF
PERIPHERAL DRIVERS, CORE DRIVERS, AND MULTIPLYING DACs

List of Sections

SECTION	TITLE	PAGE NUMBER
I.	INTRODUCTION	I-i
II.	AUTOMATIC TEST DEVELOPMENT	II-i
III.	CHARACTERIZATION OF PERIPHERAL DRIVERS MIL-M-38510/129	III-i
IV.	CHARACTERIZATION OF CORE DRIVERS, MIL-M-38510/130	IV-i
V.	CHARACTERIZATION OF CMOS MDACs, MIL-M-38510/127	V-i

SECTION I
INTRODUCTION

TABLE OF CONTENTS

	Page
Objectives	I- 1
Scope of Applied Effort	I- 2
Background	I- 2
Development of Slash Sheets	I- 3
Characterization Data	I- 4
Formal Meetings Attended	I- 4

SECTION I

INTRODUCTION

Objectives

The overall objective of this work effort is to characterize and specify MIL-M-38510 ("General Specification for Microcircuits") detailed slash sheets.

Generally, "characterization" of a device type includes several related tasks:

- o Assessment of test parameters, limits, and test conditions.
- o Development of test procedures and test circuits compatible with automatic test systems.
- o Analysis of limits and verification of test circuits via sample device testing and data evaluation.
- o Assessment of device performance, identification of anomalies.
- o Generation and verification of detailed burn-in life test circuits

Concurrent with characterization, detailed MIL-M-38510 slash sheet development includes:

- o Formulation of Table I, Electrical Performance Characteristics selection of test parameters required by military users and determination of test conditions and limits, compatible with automatic test methods and with device yield.
- o Formulation of Table II, Electrical Test Requirements; Table III, Group A Inspection; Table IV, Group C End Point Electrical parameters.
- o Design of static and dynamic test circuits, terminal connection diagrams, steady-state power and reverse bias burn-in circuits, accelerated burn-in and life test circuits.

All of the above activity is either guided by or reviewed by the manufacturers of the devices involved, and by Rome Air Development Center (RADC).

All of the characterization and specification effort performed is based upon the fundamental objectives of the JAN 38510 program - namely quality, reliability, interchangeability, and standardization.

Scope of Applied Effort

The specific tasks included in this effort are the characterization and specification of the following generic device types:

- o Peripheral Drivers
- o Core Drivers
- o Multiplying DACs

Originally, sense amplifiers and line drivers were also planned for characterization. Lack of vendor interest and support plus discontinued production by one vendor, led to cancellation of that effort and addition of the multiplying DAC effort.

Background

General Electric Ordnance Systems, one of 166 operating product departments of the General Electric Company, develops and produces precision electromechanical and electronic military systems. Current activities include development, design and production of fire control and guidance systems for the Navy's TRIDENT Fleet Ballistic Missile program, the MK 73 Gun and Guided Missile Director (TARTAR), the MK 80 Director (AEGIS), the PHALANX close-in weapon system, MK 45 Gun Mounts, turret drive and stabilization systems for the Army's Infantry Fighting Vehicle, advanced torpedo propulsion, and jet engine controls.

As users of microcircuits for military systems, Ordnance Systems has also performed electrical characterization of certain linear, digital, and interface microcircuits for MIL-M-38510 specification under previous contracts to Rome Air Development Center. These specification activities date back to 1971 and include seventeen separate contracts.

General Electric began this current effort in MIL-M-38510 microcircuits on January of 1980, having previously completed similar characterization and specification contracts in 1976 - 1979. Philosophies for establishing parameters, limits, and test circuits for conventional devices like op amps, comparators, logic devices and data converters were developed and coordinated with RADC, DESC, and the device manufacturers.

This current effort extended past efforts to a new class of devices, peripheral drivers and memory core drivers, and thus established important groundwork in the development of automatic tests and specifications for high-speed, high-voltage/current logic drivers.

Currently there are approximately thirty completed and in-process linear/interface slash sheets in the MIL-M-38510 program. Six slash sheets are devoted to op amps including the bipolar "standards", followers, BIFETs, quads, high-slew-rate, and lo-power and lo-noise BIFETs. Comparators, transistor arrays, and precision timers are contained in four slash sheets, as are CMOS and JFET analog switches. Voltage regulators are specified in six

separate slash sheets, and precision voltage reference in two others. Three slash sheets are devoted to D/A converters, and one each to A/D converters, sample/hold circuits, peripheral drivers, memory core drivers, and line drivers and line receivers.

Development of Slash Sheets

A procedure for developing new slash sheets to MIL-M-3851D has evolved through negotiations among all concerned parties. Device selection is influenced by user needs, which is determined from the marketplace and from organized committees, such as the Military Parts Control Group (MPCAG) at DESC, the G12 Solid State EIA Device Committee, and the Microelectronics Project Group of the Electronics Systems Committee of AIA. These recommendations are balanced with manufacturer recommendations obtained via the JC-41 Committee on Linear Microcircuits. Devices of recent vintage, having high usage, multiple application potential in military systems, proven performance, and two or more sources are given priority. Single-sourced devices are acceptable, especially for hybrid devices, although multiple sources are preferred. Availability of devices, and expressed manufacturer interest in supporting slash sheet development are additional important considerations. Manufacturers typically recommend devices for slash sheet action in JC-41 Committees, and then chair a JC-41 Subcommittee for preparation of slash sheet parameters, limits, and test circuits.

The industry data sheet forms the basis for the military specification parameters and limits. Typically, such data sheets do not specify all of the necessary parameters over the military temperature range and over the common mode voltage range. The JC-41 Subcommittee, or the device manufacturer, usually prepares a proposed spec which contains more information than the industry data sheet. Conflicting items are negotiated in committees or via direct contact with manufacturers.

Data provides another base for determining parameters and limits. Devices for test are purchased from distributors and are also obtained from manufacturers via RADC request. Test circuits, compatible with automatic test systems, are developed. The devices are tested on a Tektronix S3263 Automatic Test System at GE Ordnance Systems Electronic Test Center. Data obtained at -55°C, +25°C, and +125°C ambient is correlated to bench or vendor test data, analyzed, reduced and documented in data handbooks. Recommended limits are compared to the statistical sample data; parameter limits which are grossly inconsistent with the data are readily identified.

Specification additions, changes, and alternate approaches are discussed at the committee level. Device anomalies are identified in lab bench tests. Failure modes are also identified. User caution notes are added to the specification if it is deemed appropriate.

Burn-in circuits are usually recommended by the manufacturer and evaluated by RADC and/or GEOS on the available test samples. An objective is to minimize the number of external components while stressing the device near its limits.

Rough draft copies of the final slash sheet are prepared at GEOS and are forwarded to RADC for review. DESC distributes copies of this spec to manufacturers and users for final comments. Following assessment of the comments by all concerned parties, DESC prepares and issues the slash sheet.

Characterization Data

Data obtained during device characterization is usually published in handbook form separate from this document. Samples of the data sheets, histograms, and plots, are included in this report. The following data handbooks were published during this contract effort:

Characterization Data for MIL-M-38510/129, Peripheral Drivers
(Commercial Types 55450 - 454, 55460 - 464) Jan 81

Characterization Data for MIL-M-38510/127, CMOS Multiplying DACs
(Commercial Types 7520, 7521, 7523, 7541) Jan 81

Formal Meetings Attended (GE internal meetings not included)

JC-41 Committee on Linear ICs
Feb. 5, 6, 1980 - Phoenix, AZ
June 10, 11, 1980 - Washington, DC
Oct. 7, 8, 1980 - Burlington, MA

RAB/C/GE Meetings

Jan. 25, 1980	Contract Plans	Pittsfield, MA
Mar. 4, 1980	Contract Status & Plans	Rome, NY
Aug. 13, 1980		

SECTION II

AUTOMATIC TEST DEVELOPMENT.

TABLE OF CONTENTS

2.1	Introduction	PAGE II-1
2.2	Tektronix S3270 Test System Features	II-1
2.3	Tektronix System Accuracies	II-2
2.4	Correlation	II-3
2.5	Data Reduction	II-4

SECTION II AUTOMATIC TEST DEVELOPMENT

2.1 Introduction

The Interface Microcircuits & linear characterization efforts required the accumulation and subsequent reduction of vast amounts of test data. For both of these tasks, GE made extensive use of a Tektronix S-3270 test system and a Tektronix software development system. This section will describe the test system and the general approach to expanding its capabilities. A few displays of raw and of reduced data, which have been developed for the device evaluations, will also be shown. Although several of the data displays are somewhat standardized, many of the linear device types required the development of unique data displays in order to effectively illustrate device performance in an easily digestible form.

2.2 Tektronix S-3270 Test System Features

The test system is fully equipped to provide a state-of-the-art engineering tool for device characterization. The CP1162 System Controller has the Date/Time Option that gives the ability to store date and time information in the directory and data files. System peripherals include a 4014 Graphics Display Terminal, two CP110 Disk Drives, a CP220 Reader/Punch, and LA180 Decprinter I and a 4631 Hard Copy Unit.

For voltage and current measurement and device stimulation, the system contains:

1394 Test Station, which contains many test functions and all electronics to interface the device under test (DUT) to the system.

2943/44 Clock Generators, which provide 10 driving and 4 comparing programmable phases.

Option 20th Waveform Digitizer, which provides the capability of converting 1000 points on a waveform to 10-bit digital values.

Once the waveform is thus stored in memory, software can be used to determine such things as rise time, overshoot, settling time, etc.

Six programmable voltage sources.

Two programmable current sources.

Temptronix 450A Temperature Chamber, which allows programmable DUT temperatures from -60 deg C to + 160 deg C.

IEEE Bus Interface Card, which allows the addition of IEEE 488 compatible equipment to the system.

With these hardware components, the test system has the following features:

Accommodates up to 128 active pins (64 input, 64 output)
Functional testing at 20 MHz; force, compare, mask and store at 20 MHz

DC Tests: Differential voltage measurements; force V, measure I;
force I, measure V

Dynamic Testing: Repetitive and one-shot time measurements;
functional preconditioning

GO/NO-GO and analytical test capability

On-line interactive program development

Digital waveform analysis (1 sample/picosecond)

DUT environmental control (-60 deg C to 160 deg C)

Data logging and reduction. Computer graphics display

2.3 Tektronix System Accuracy

The linear test programs were developed to utilize the internal Tektronix measurement/stimulus hardware as much as possible. However, for many measurements, the Tektronix system could not provide the required accuracy. In these cases, more accurate external equipment was utilized via the IEEE 488 Bus. Two disadvantages in using external equipment are:

- 1) additional core is required to store the 488 bus control routines and,
- 2) execution time for external functions is significantly longer than time to execute internal Tektronix functions.

Table 2.1 lists instruments which are available for use with the S-3260/70.

Table 2.1 IEEE-488 Interfaced Instruments.

Manufacturer	Model	Description
Fluke	8502A	Precision Digital Multimeter
Hewlett Packard	3455A	Precision Digital Voltmeter
Hewlett Packard	4262A	LCR Meter
Hewlett Packard	5328A	Universal Counter
Fluke	5100A	Calibrator
Kepco	488-122	Power Supply Programmer
TCS Electronics	4880	Instrument Coupler
Hewlett Packard	2240A	Measurement and Control Processor
North Atlantic	225	Phase Angle Voltmeter

Figures 2-1 through 2-13 illustrate the accuracies of the internal Tektronix measurement and stimulus functions. Also, for certain internal functions, the accuracy of the external equipment that provides the same function, is displayed for comparison.

On many occasions, neither the internal Tektronix equipment nor the external equipment had sufficient accuracy, or response time. These cases required test adapter circuitry to interface the device under test (DUT) to the test equipment. These cases will be described in the appropriate chapters covering the individual linear device types.

2.4 Correlation

Testing linear devices on the Tektronix system has required the implementation of many new test techniques. Each new technique, whether in the form of adapter circuitry or software, must be verified as accurate. In general, the first step of verification was to determine that the technique is designed to provide a measurement that is at least 10 to 1 times more accurate than the tolerance of the parameters. For instance a parameter of 5.0 volts plus or minus 10% must be measured by a meter that is at least accurate to plus or minus 1% when measuring 5.0 volts.

Verification of accuracy also included comparison of data taken by the new technique to data taken by an alternate method - usually on a bench circuit. When data from the two techniques did not agree, an analysis of error contributions was performed and corrections made if it was felt that the error was significant.

Correlation of Tektronix test data for peripheral driver devices to bench data uncovered some discrepancies. One discrepancy involved the inaccurate specification of worst case test conditions for output switching times. Correlation uncovered the discrepancy and led to recommended changes to the slash sheet.

2.5 Data Reduction

The presentation of test results is extremely important in any characterization effort. Raw data printouts are required for record, but are usually not organized in a manner that enables one to scan them to assess general parameter trends.

Data Tables

For the linear devices, the first step in data reduction was organizing raw data into tables. Figure 2-14 and 2-15 illustrate two variations of data tables. Figure 2-14 illustrates data taken from multiplying D/A devices. Figure 2-15 is the form of table used for the Peripheral Driver devices. The left hand entries indicate the test parameters and test conditions. In Figure 2-14 the data from a particular device is entered in the column beneath the temperature at which the data was taken. In Figure 2-15, the data taken for five devices at a particular temperature, is entered in columns. Note that in both figures the low test specification limit for each parameter is on the left of the device data and the high specification limit is on the right hand side of the data. This enables the reader to more easily determine if a measurement on a device lies mathematically between the specification limits.

Data Summaries, Line Graphs

Data tables, for the multiplying D/A with its large number of data points are too voluminous for a reader to mentally reduce and detect trends. Therefore the large quantities of data must also be presented in a summarized form.

Figure 2-16 is a plot of linearity error (in LSBs) for all codes between 0 and 800. The plot is one of five sheets developed for each 7520 multiplying D/A device. The linearity plots were very instrumental in verifying the effectiveness of an abbreviated linearity test for 7520 multiplying D/A devices. Although two separate sheets were required for each device under each set of operating conditions, one set of sheets allows one to quickly assess qualitatively, the linearity error of 1024 codes.

Histograms

Tektronix software included a basic histogram routine which was modified by GE to provide the variations shown in Figures 2-17 and 2-18. Figure 2-18 has grouped thirty devices according to hFE. The histogram differs from the basic Tektronix histogram in that the bars are filled in and are separated by a narrow non-darkened region. Figure 2-18, another histogram variation, groups the codes from a single multiplying D/A device, according to the magnitude of each code's error. This type of plot is very useful in comparing general linearity error characteristics of one device to another.

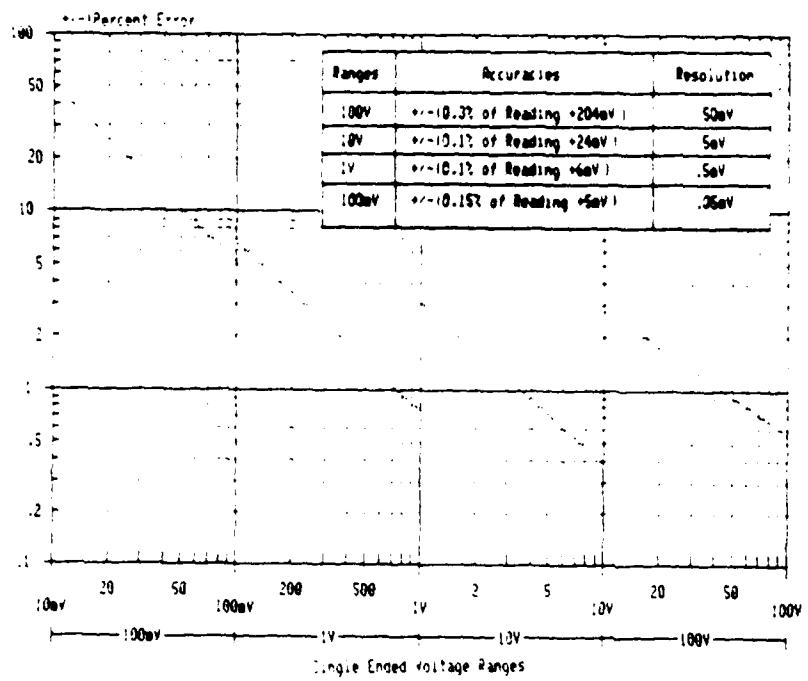


Figure 2-1. 33260/70 - Single Ended Voltage Accuracies

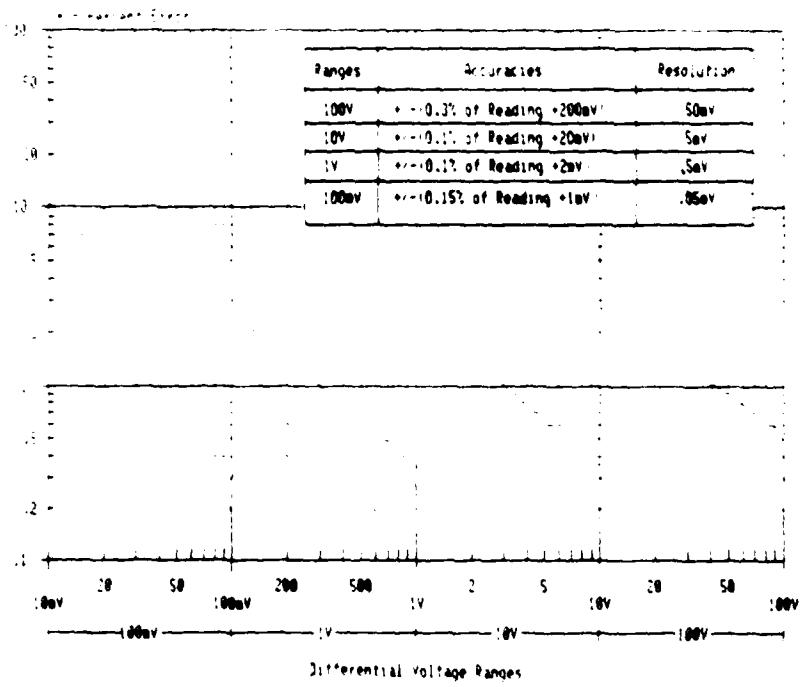


Figure 2-2. 33260/70 - Differential Voltage Accuracies

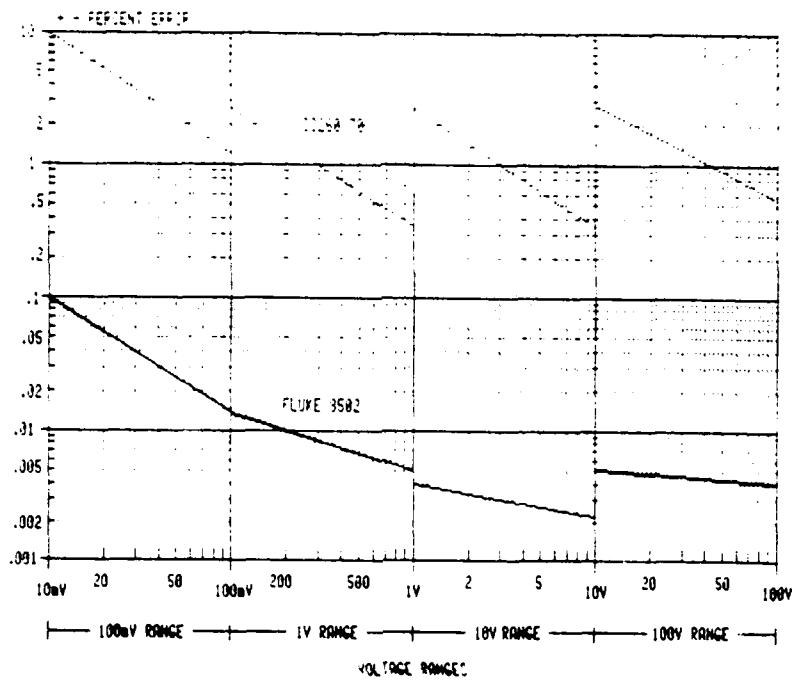


Figure 2-3a. S3260/70 - Diff. Meas. vs. Fluke 8502 DVM Accuracies

FLUKE DMM 8502A				
Range	Full Scale	Accuracies	Resolution	Settling time
100mV	31.2mV	0.005% of Reading +90uV	1uV	2mS
1V	3.12V	0.004% of Reading +9uV	1uV	2mS
10V	31.2V	0.002% of Reading +90uV	10uV	2mS
100V	312V	0.004% of Reading +900uV	100uV	2mS

TEKTRONIX S3260/70 DIFF. VOLTAGE MEASUREMENTS				
Range	Full Scale	Accuracies	Resolution	Settling time
100mV	102.2mV	+/-0.15% of Reading +10uV	0.05uV	4mS
1V	1.022V	+/-0.1% of Reading +20uV	0.5uV	.6mS
10V	10.22V	+/-0.1% of Reading +60uV	5uV	.6mS
100V	102.2V	+/-0.3% of Reading +200uV	50uV	1.2mS

Figure 2-3b. S3260/70 - 8502 DVM Specification Comparison

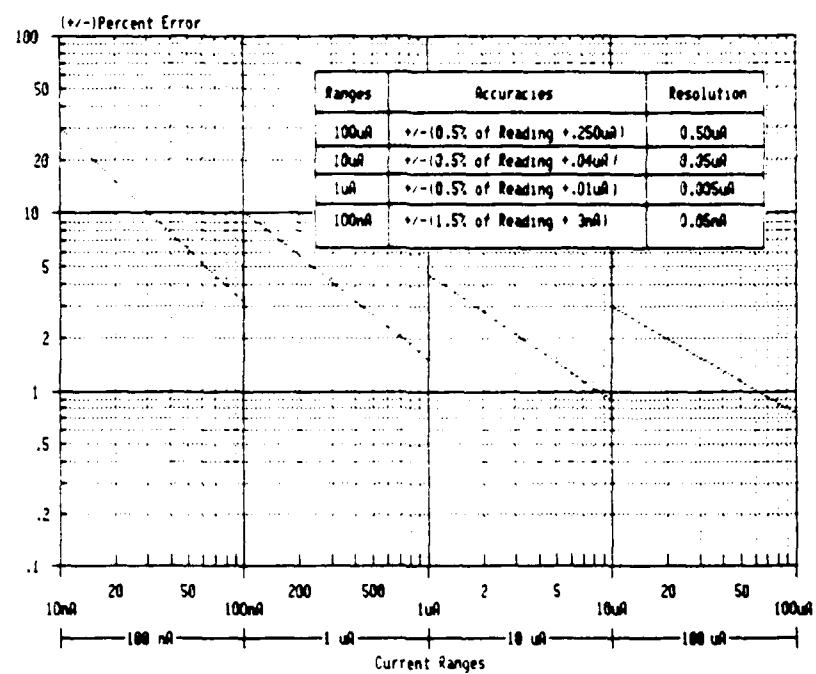


Figure 2-4. S3260/70 - Current Measurement Accuracies

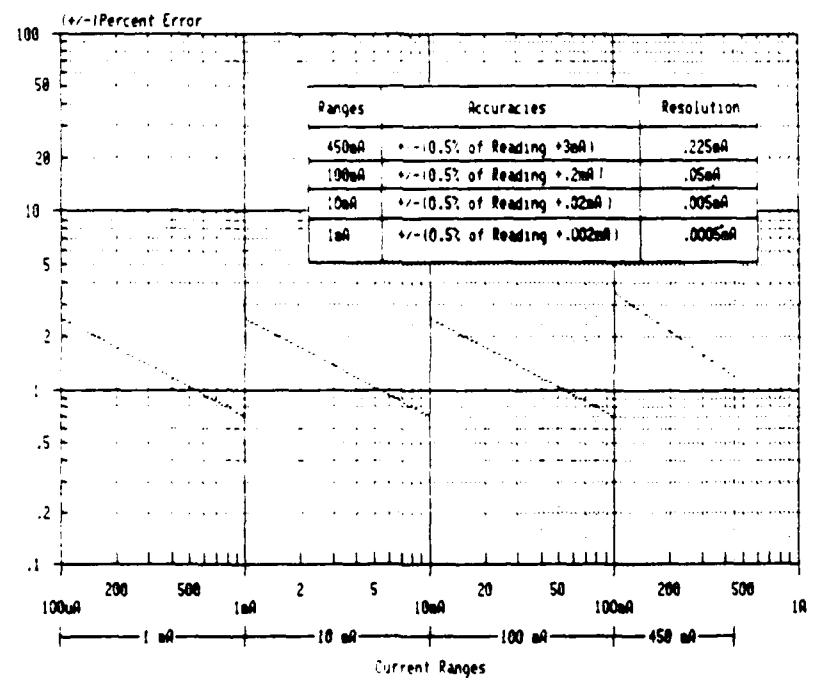


Figure 2-5. S3260/70 - Current Measurement Accuracies (Cont'd.)

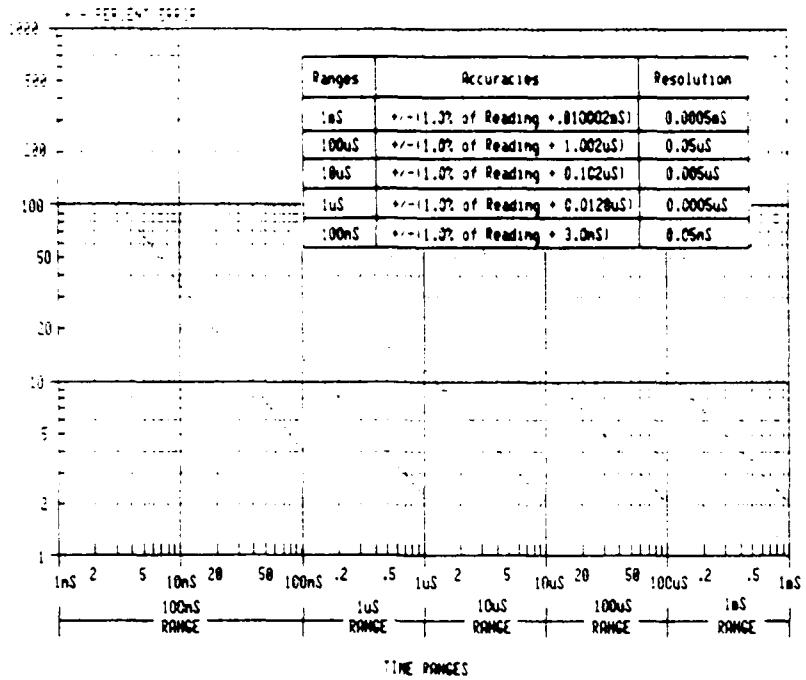


Figure 2-6. S3260/70 - Time Measurement Accuracies

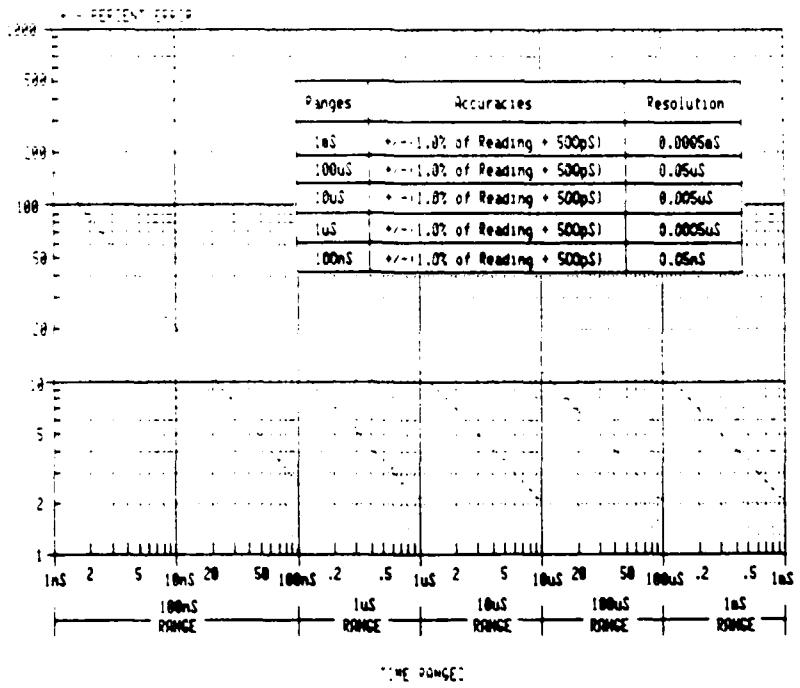


Figure 2-7. S3260/70 - Time Measurement Accuracies - HPO

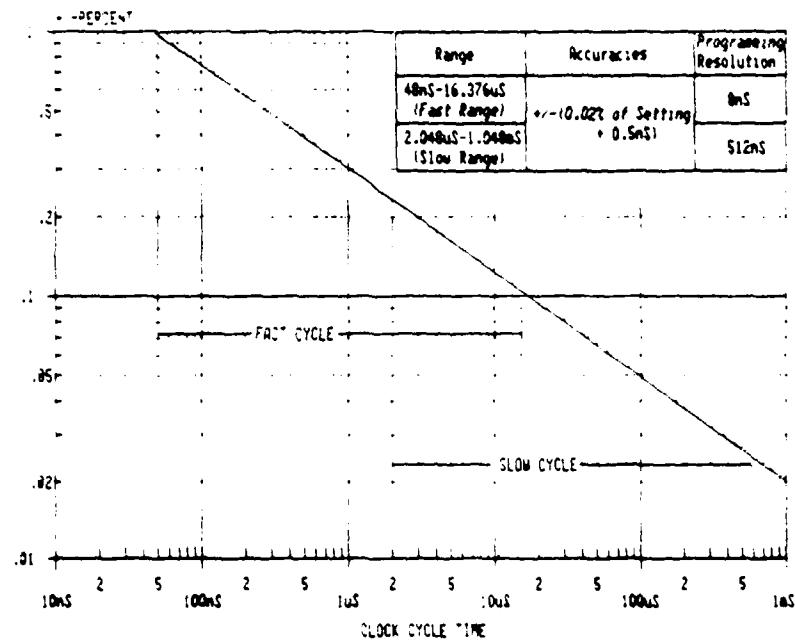


Figure 2-8. S3260/70 - Clock Cycle Accuracies

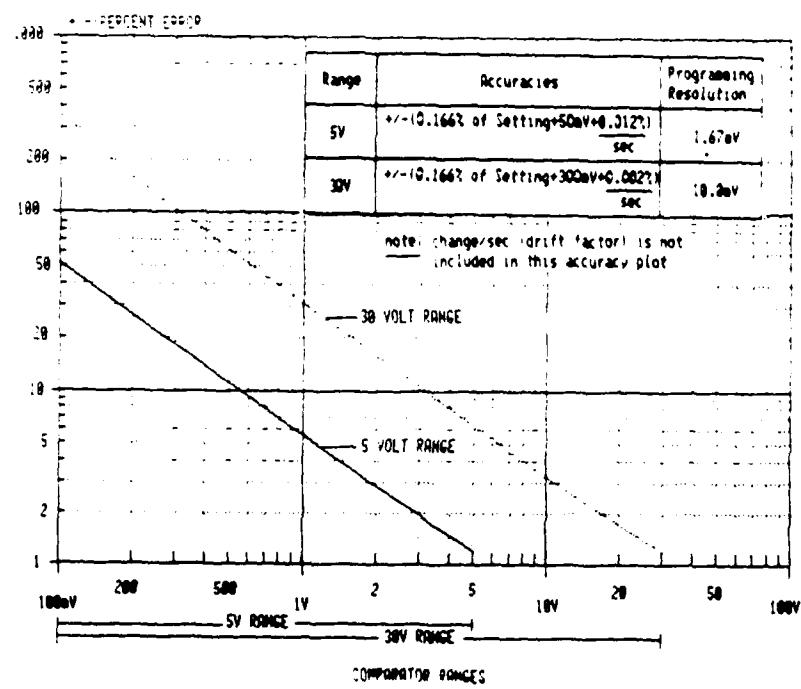


Figure 2-9. S3260/70 - D70 Pin Electronics Card Accuracies

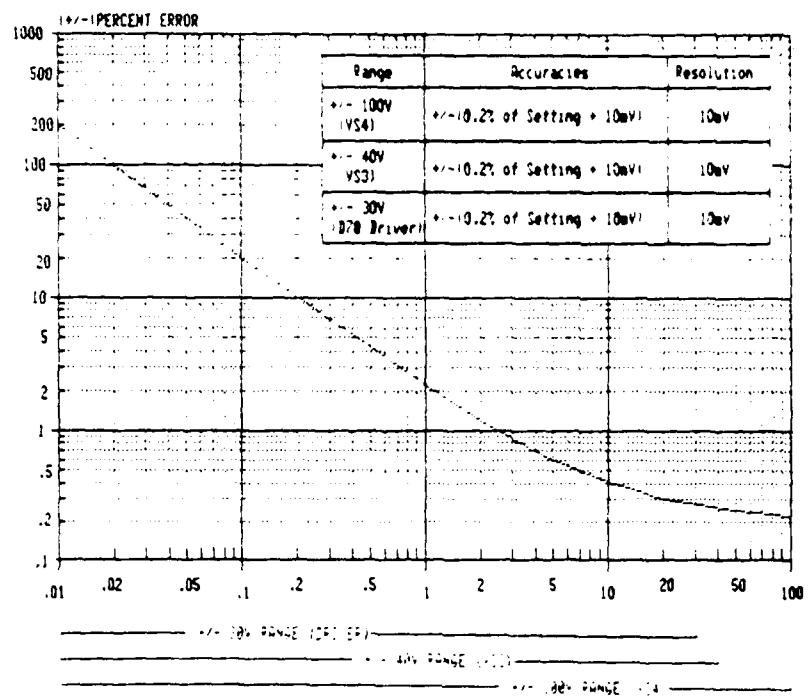


Figure 2-10. S3260/70 - Forcing Voltage Accuracies

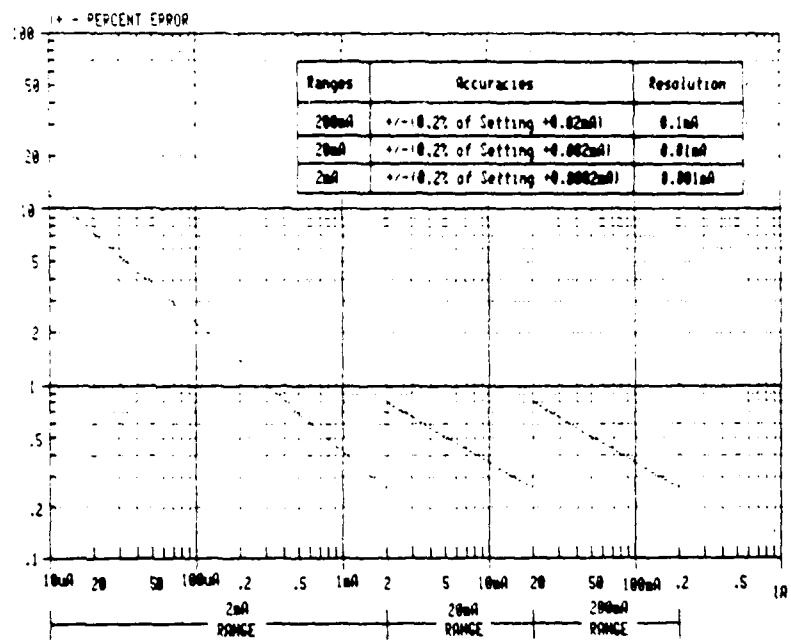


Figure 2-11. S3260/70 - Forcing Current Accuracies

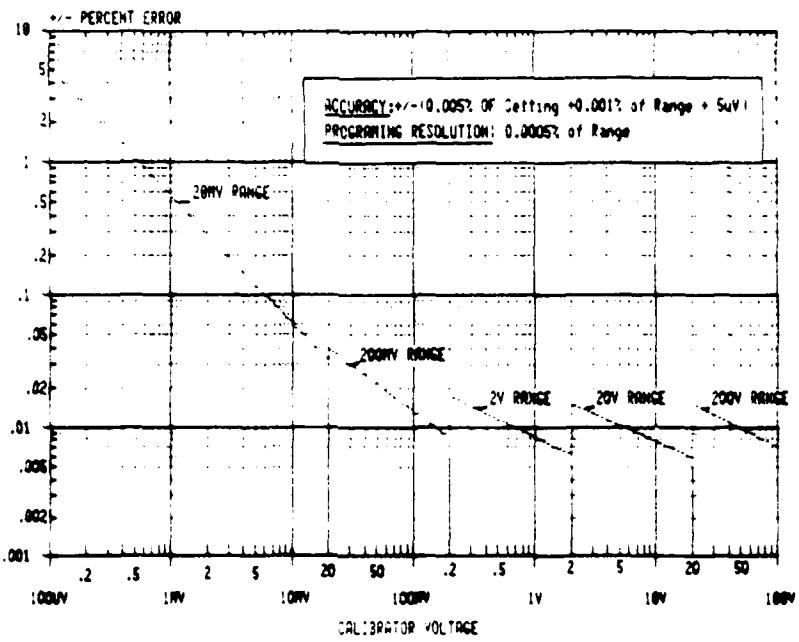


Figure 2-12. Fluke 8100B Meter Calibrator - Forcing Voltage Accuracies

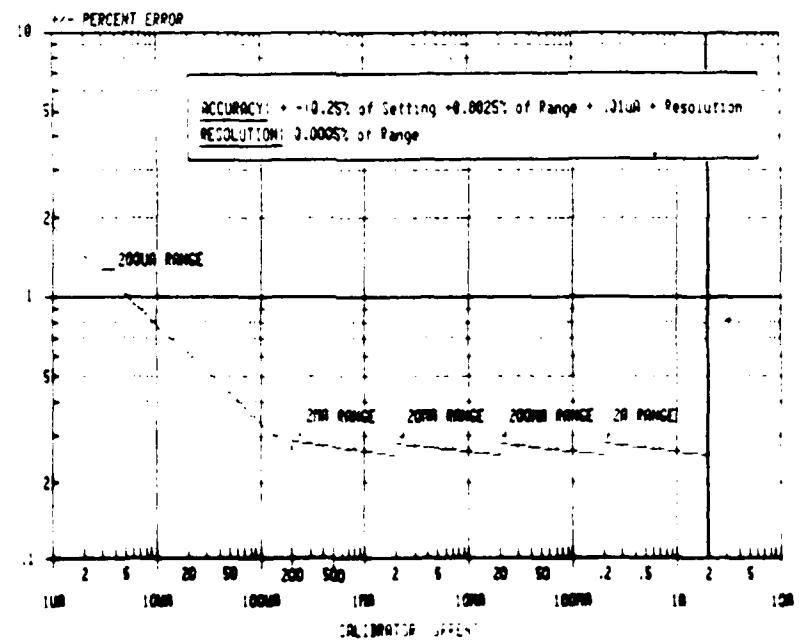


Figure 2-13. Fluke 8100B Meter Calibrator - Forcing Current Accuracies

NOTES: 1. ZERO (0) IN LIMITS COLUMN MEANS NO LIMIT. IT CAN BE INTERPRETED AS A DASH (-).

55450 DUAL PERIPHERAL POSITIONER AND DRIVER; DATE=11 DEC 30 TIME=05:36:33
TEMPERATURE=25DEG C; DATE=11 DEC 30 TIME=05:36:33

PARAMETER	TEST CONDITIONS	TEST PIN#	I/O-LIMIT	SN11	SN12	SN13	SN14	SN15	I/O-LIMIT
VIL	UCC=4.5V	1	800.00	1.120	1.370	1.380	1.420	1.420	2.000
		2	800.00	1.190	1.380	1.390	1.410	1.410	2.000
		13	800.00	1.390	1.390	1.390	1.420	1.420	2.000
VIM	UCC=4.5V	1	800.00	1.390	1.380	1.390	1.410	1.410	2.000
		2	800.00	1.400	1.390	1.400	1.420	1.420	2.000
		13	800.00	1.400	1.400	1.400	1.430	1.430	2.000
VIK	UCC=4.5V	1	-1.500	985.00M	-1.000	-985.00M	-995.00M	-995.00M	0.000
		2	-1.500	-1.150	-1.160	-1.170	-1.155	-1.155	0.000
		13	-1.500	-1.155	-1.170	-1.160	-1.165	-1.165	0.000
III1	UCC=5.5V	VIH=5.5V	1	0.000	26.40U	10.25U	16.20U	14.65U	8.55A
		VIH=5.5V	2	0.000	12.10U	5.950U	7.450U	7.850U	4.40A
		VIH=5.5V	13	0.000	6.250U	4.850U	7.450U	5.50A	3.88A
III2	UCC=5.5V	VIH=2.4V	1	0.000	17.45U	8.050U	12.65U	11.45U	6.90A
		VIH=2.4V	2	0.000	7.750U	4.700U	5.800U	6.150U	3.40A
		VIH=2.4V	13	0.000	5.000U	3.550U	6.950U	5.10A	4.00A
III3	UCC=5.5V	VIL=0.4V	1	-3.200M	-2.100M	-2.145M	-2.155M	-2.145M	0.000
		VIL=0.4V	2	-1.600M	-1.055M	-1.080M	-1.075M	-1.075M	0.000
		VIL=0.4V	13	-1.600M	-1.060M	-1.080M	-1.075M	-1.075M	0.000
VOL	UCC=4.5V	VIL=0.8V	3	0.000	236.00M	246.5M	259.5M	242.5M	236.5M
		VIL=0.8V	12	0.003	232.00M	242.0M	248.5M	250.5M	236.8M
VOH	UCC=4.5V	VIH=2.0V	3	2.400	2.695	2.695	2.715	2.725	2.700
		VIH=2.0V	12	2.400	2.725	2.695	2.705	2.730	2.690
I0S1	UCC=4.5V	VIL=0.0V	3	-55.00M	-25.15M	-25.00M	-25.10M	-25.30M	-24.55M
		VIL=0.0V	12	-55.00M	-24.95M	-24.95M	-24.35M	-25.10M	-24.50M
I0S2	UCC=5.5V	VIL=0.0V	3	-55.00M	-32.10M	-31.95M	-32.00M	-32.30M	-31.45M
		VIL=0.0V	12	-55.00M	-31.95M	-31.90M	-31.10M	-32.05M	-31.35M
ICCH	UCC=5.5V	VIH=5.0V	8	0.000	2.275P	2.320M	2.315M	2.160M	4.000M
		VIL=0.0V	8	0.000	7.000M	7.100M	7.100M	6.600M	11.00M

PT Model 2-15, Test Data for 55450 Dual Peripheral Positioner and Driver

FOR DEVICE S/N 31 AT 25 DEG C
UDD=+15.0 V UREF=10.0 V 29 JAN 81

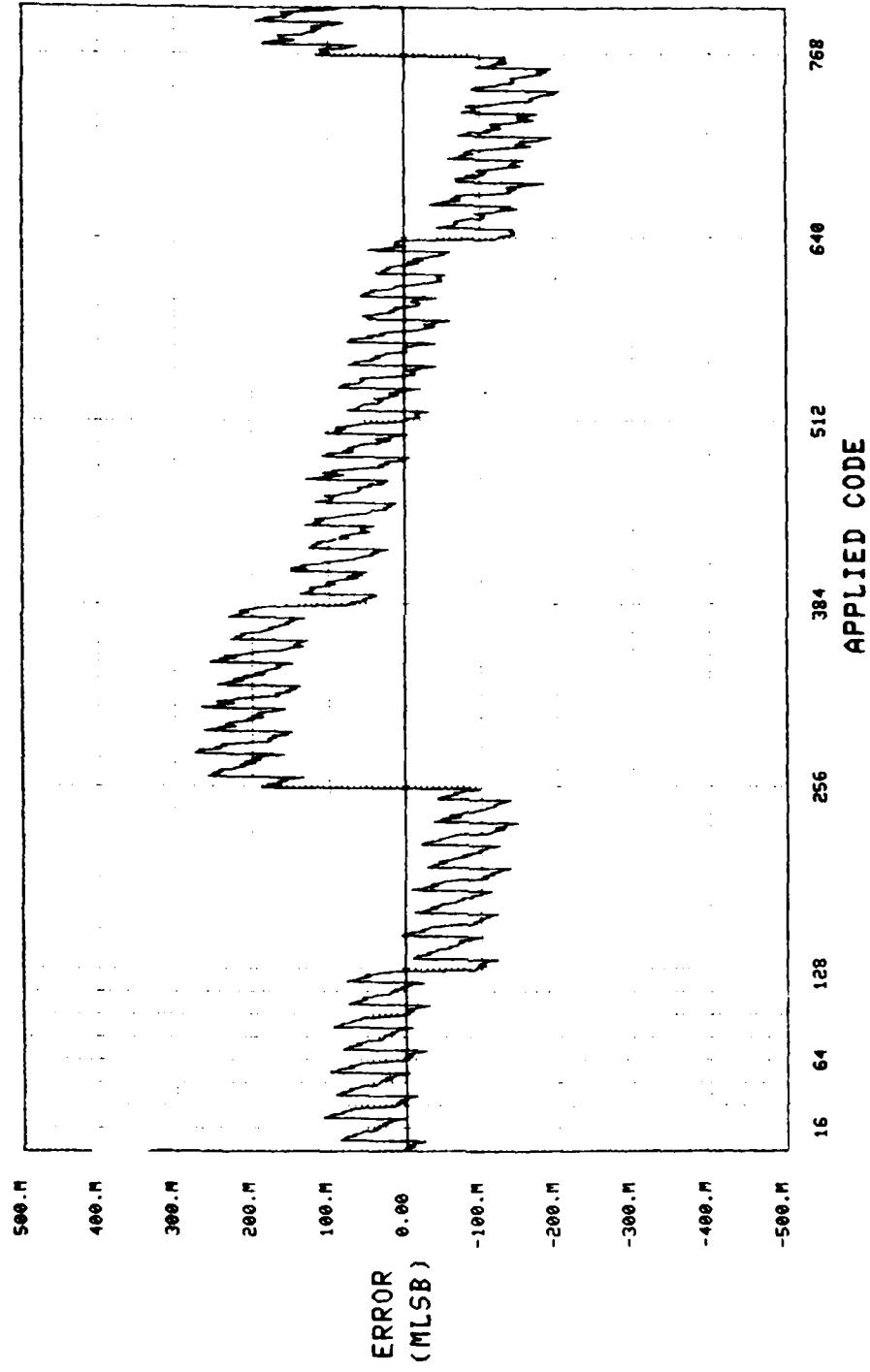


FIGURE 2-16. LINEARITY ERROR (ALL CODES)
7520-10 BIT MULIT. D/A CONVERTER

HFE1 AT UCE=3V, Tc=12degA

DEVICE TYPE 554503

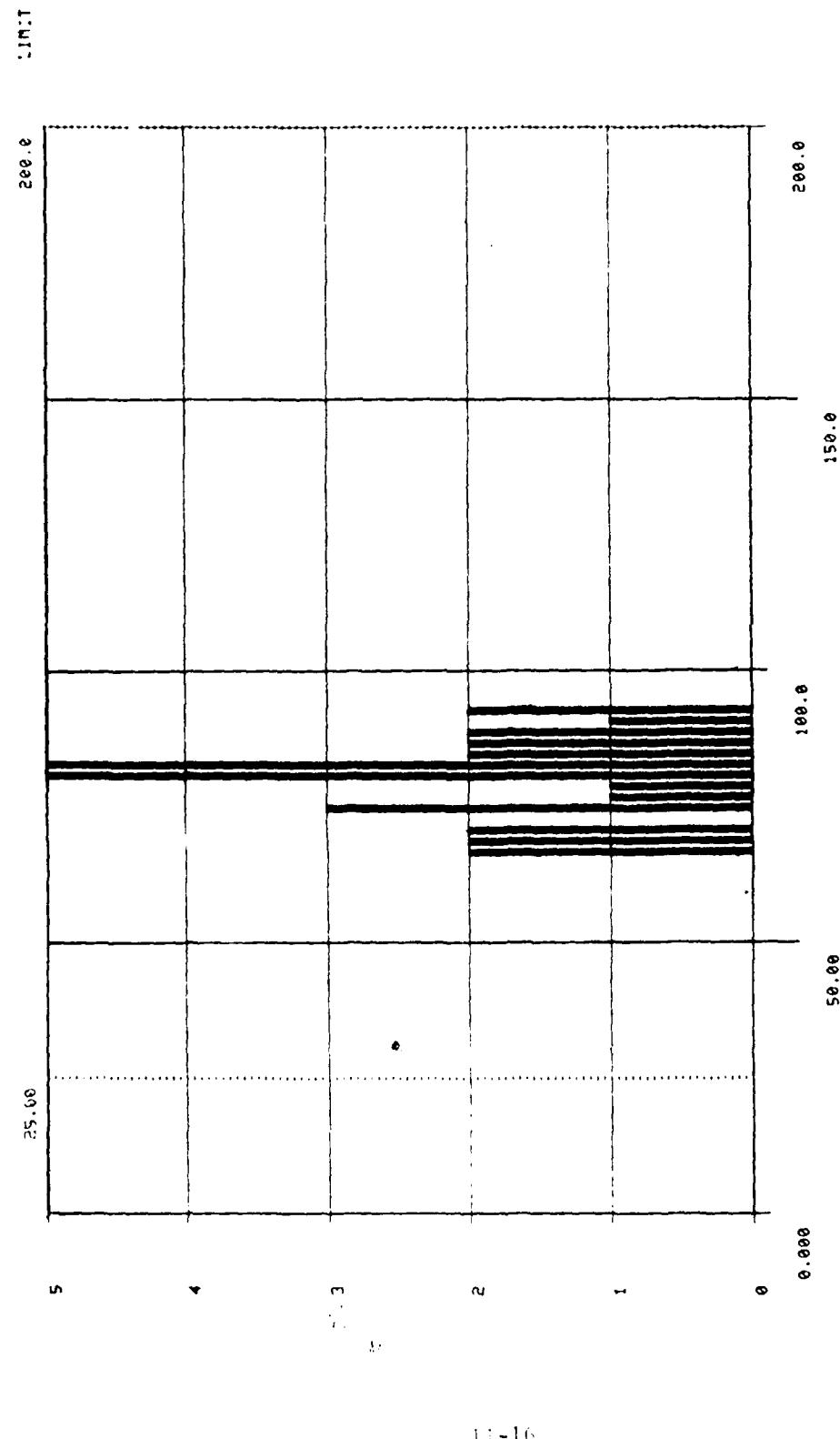
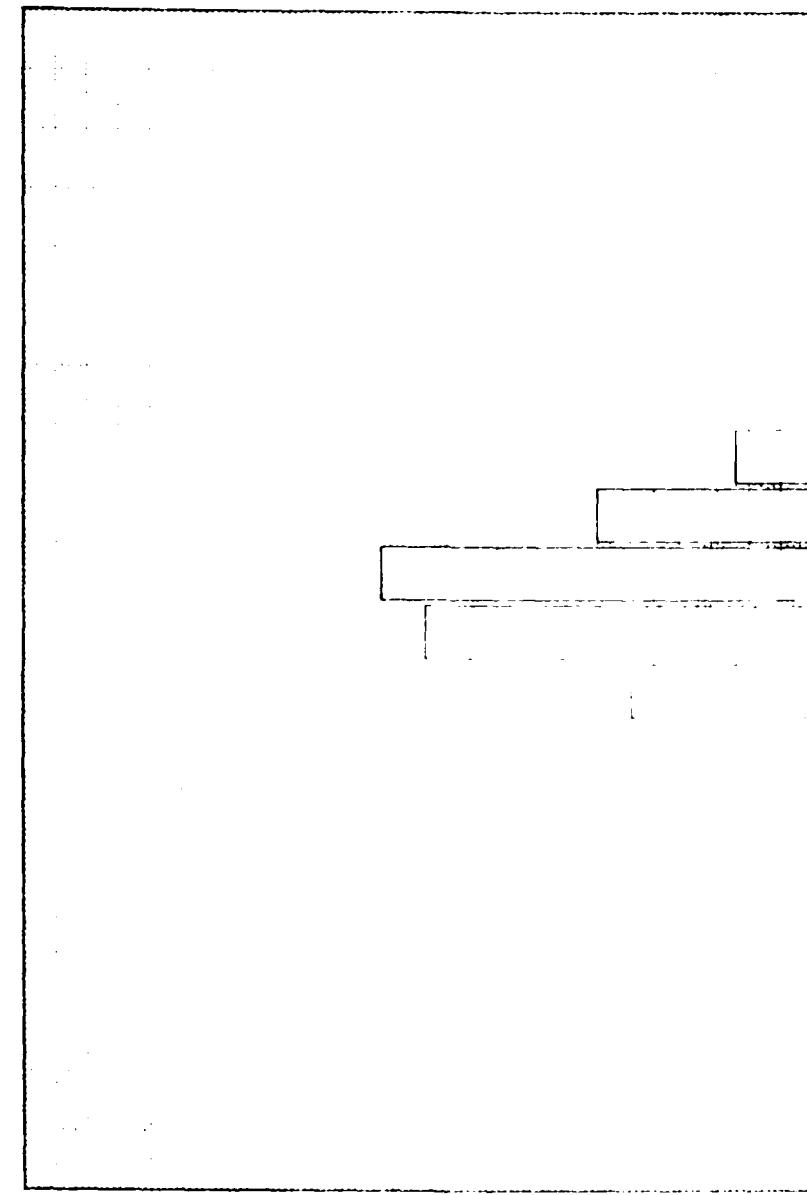


FIGURE 2-17. Histogram representation of Characterization Data

FOR DEVICE S/N 10 AT 25 DEG C
VDD=+15.0
29 JAN 81



-1.0 -0.9 -0.8 -0.7 -0.6 -0.5 -0.4 -0.3 -0.2 -0.1 0.0 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1.0
ERR:R BAND (LSB)

LINEARITY ERROR DISTRIBUTION
7520-10 BIT CMOS D/A CONVERTER

SECTION III

PERIPHERAL DRIVERS

TABLE OF CONTENTS

3.1	Introduction	III-1
3.2	Description of Device Types	III-2
3.3	Test Development	III-2
3.4	Test Results and Data	III-17
3.5	Discussion of Results	III-18
3.6	Slash Sheet Development	III-19
3.7	Conclusions and Recommendations	III-19

Section III
(Characterization of Peripheral Drivers)

3.1 Introduction

Devices for interfacing between TTL logic and the outside world have been a requirement in military systems for as long as TTL logic has been employed in these systems. The devices selected for characterization provide great flexibility in application. The devices can be used as high-speed logic buffers, power drivers, relay drivers, lamp drivers, MOS drivers, line drivers, and memory drivers. Table 3-1 gives some specifics on the devices tested and their relationship to the military slash sheet device types.

Table 3-1. Table of Device Types Specified.

Military Device Type	Generic Device Type	Manufacturer Symbol	Peripheral Driver Description
12901	55450	N,T	Dual NAND gate and transistor (separate)
12902	55451	N,T	Dual AND, gate and transistor connected
12903	55452	-	Dual NAND gate and transistor connected
12904	55453	N,T	Dual OR, gate and transistor connected
12905	55454	-	Dual NOR, gate and transistor connected
12906	55460	-	High voltage 55450
12907	55461	N,T	High voltage 55451
12908	55462	-	High voltage 55452
12909	55463	N	High voltage 55453
12910	55464	-	High voltage 55454

N = National Semiconductor

T = Texas Instruments

The manufacturer symbol column reflects the source of the devices which were characterized.

Some of the features of the 5440/5540 series of devices which helped to earn its characterization as a military device type are as follows:

- Low-level voltage inputs
- High output current (characterized to 300 mA)
- Low power switching
- Low input current (decreased input current)
- Standard TTL supply voltages
- Good flexibility in application and test function

3.1 Description of Device Types

The pinouts for all of the peripheral drivers are shown in Figure 3-1 and their corresponding schematic circuits are shown in Figure 3-2.

The peripheral drivers consist of two basic types of logic and memory devices. The first type is the standard logic devices which are characterized as TTL or CMOS. The second type is the memory devices which are characterized as SRAM or DRAM. The peripheral drivers with corresponding schematics show some differences in circuit topology (with the exception of the SRAM) since it deletes the clamp diodes normally found in the SRAM since the total-pole output stage and some minor circuitry is deleted. Consequently, V_{DD} , V_{PP} , V_{SS} , V_{DD} (TTL), V_{DD} (CMOS), V_{DD} (SRAM), V_{SS} , I_{DD} , I_{PP} , I_{SS} , and I_{DD} (SRAM) are the measurements for the peripheral drivers compared to the standard logic gate measurements.

Since the peripheral drivers incorporate a high-current output stage, additional specifications are included for propagation delay, measurement of output current, memory transistor threshold voltages, V_{TH} , V_{THS} , V_{THA} , V_{THP} , V_{THSS} , V_{THPS} , V_{THAS} , V_{THAP} , V_{THSP} .

3.2 Test Equipment

Test fixtures developed at JPL for the electron S-3270 test system to enable automated testing of all peripheral driver devices. All standard and non-test recommended by the I-11 Committee, including some optional tests, were incorporated. MOS as part of the standard automated parametric testing of peripheral drivers was also incorporated to verify proper MOS operation.

3.3 Test Adapter

A test adapter, shown in Figure 3-3, was designed to provide the required interface between the device under test (DUT) and the S-3270

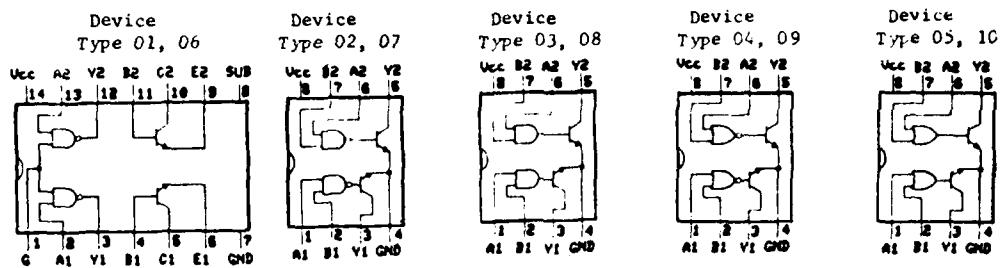


Figure 3-1 Peripheral Driver Block Diagram

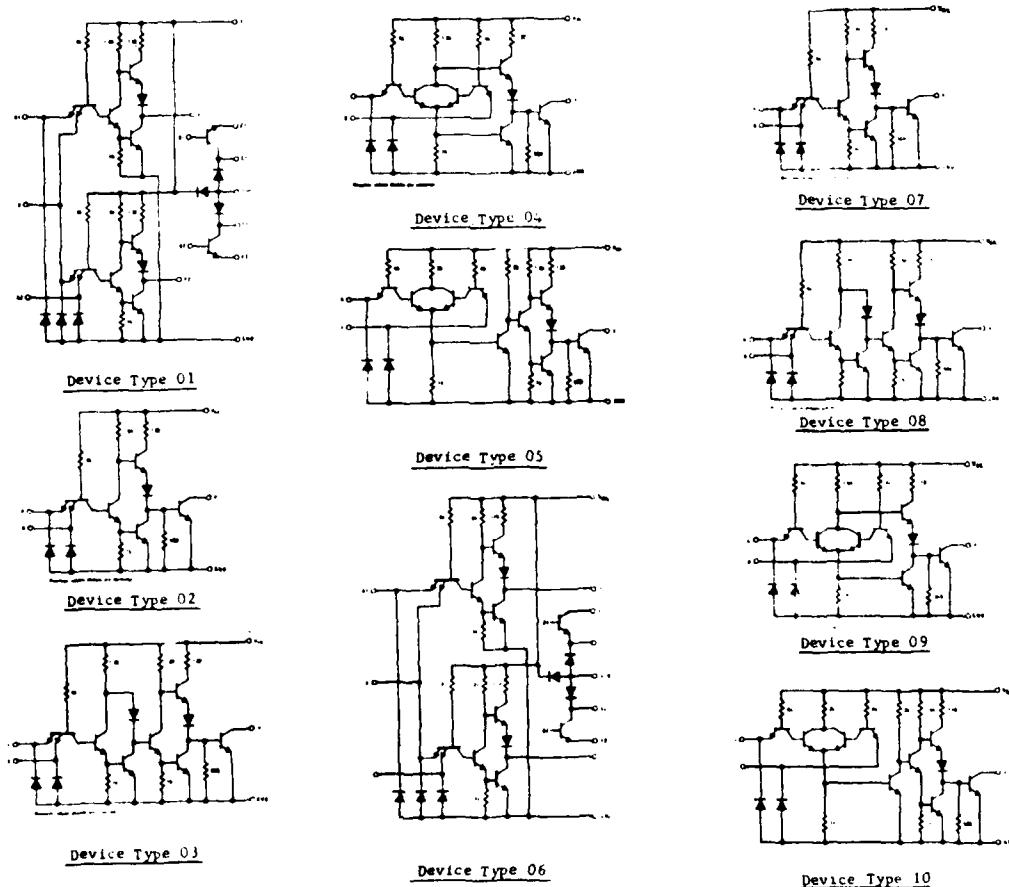


Figure 3-2 Peripheral Driver Schematic Circuits

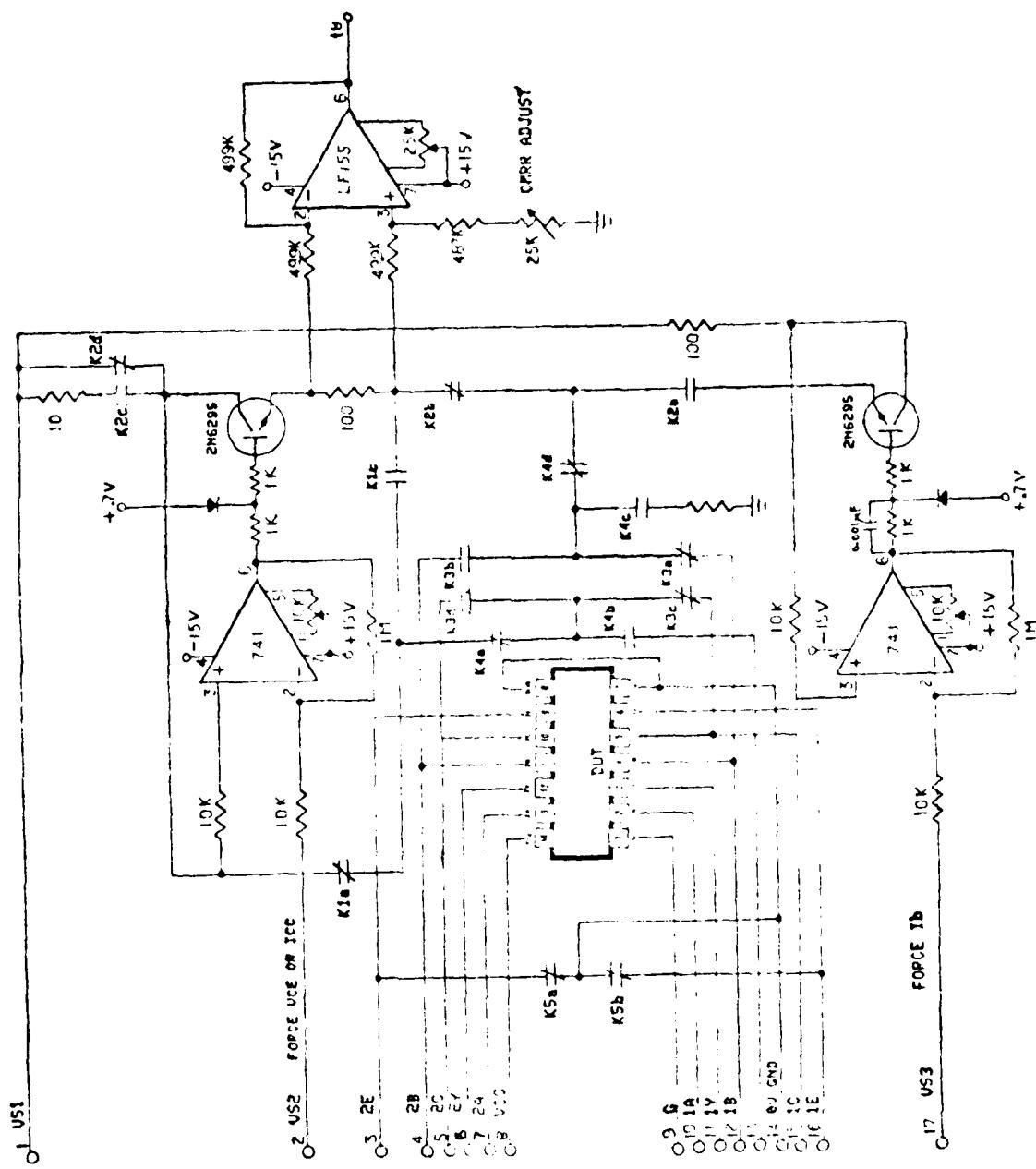


Figure 3-7. Electromagnetic static test chapter

test system. The adapter has the ability to test all static and static pulsed parameters required for characterization of the 55450 and 55460 peripheral drivers.

The adapter consists of Op Amp and transistor circuitry used to force the proper pulsed conditions on the DUT, while stimulated by the S-3270. Actual signal paths to the DUT are implemented by relay control and routed to the S-3270 for testing. All other static tests are performed using the S-3270 driver and measurement system capability.

h_{FE} Tests

Within the "static" test parameters, measurement of h_{FE} was the most difficult. Manufacturers' data sheets specify a $t_w = 300$ us with a duty cycle $\leq 2\%$. Bench testing indicated that h_{FE} testing could be accurately performed with $t_w = 100$ us and a duty cycle of 2%. The data sheet specification allows time for the servo circuit used in h_{FE} measurements to reach its final value. A major concern was to minimize the effect of device self heating on parameter measurement.

The Forward Current Transfer Ratio (β_{FE}) of the 55450, 55460 peripheral driver is automated using the circuit shown in Figure 3-4 in conjunction with the S-3270 and the Tektronix Waveform Digitizer option 20 (WFD).

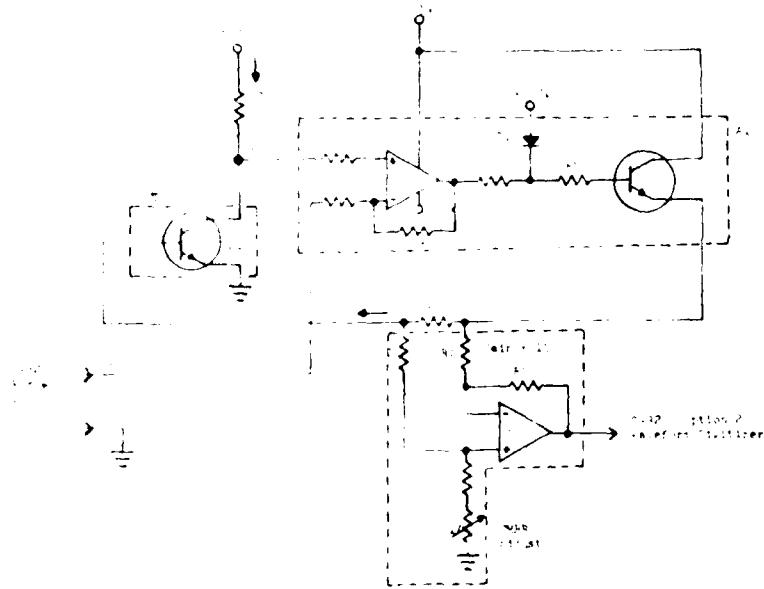


Figure 3-4. bfg Test Circuit.

The criteria for measuring h_{FE} is to force V_{CE} and I_C to predescribed levels while servoing the base current, I_B to achieve these levels. The Forward Current Transfer Ratio h_{FE} becomes

$$h_{FE} = I_C/I_B \text{ with } V_{CE} \text{ constant}$$

The V_{CE} pulse level from the S-3270 is applied to one input of the base drive and comparator amplifier circuit, A1, while the other input to amplifier A1 monitors the V_{CE} level of the DUT. The output of amplifier circuit A1 servos the base current I_B until the DUT's V_{CE} voltage equals the input stimuli from the S-3270. The collector current I_C is forced to the proper level by the relationship of $(V_{CC} - V_C)/R_C$, since V_{CC} and R_C were fixed.

Buffer amplifier A2, senses the voltage drop across resistor R_B , which is proportional to the base current I_B . The buffer amplifier A2 was configured in a differential mode to reduce large common mode voltages present on R_B and to provide increased gain for single-ended measurement capability need by the WFD.

Figure 3-5 illustrates a digitized voltage pulse from across R_B .

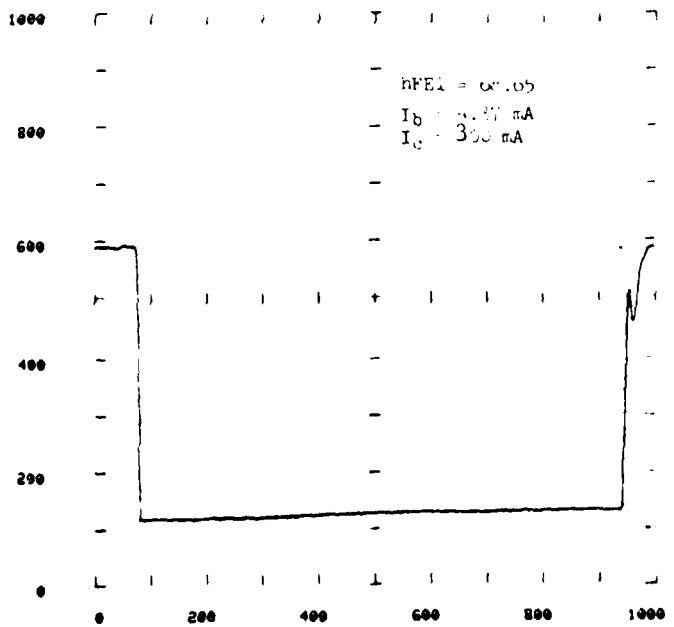


Figure 3-5. h_{FE} measurement waveform.

The voltage translates to 4.370 mA of current. Since the collector current was at 300 mA, h_{FE} is therefore 68.6.

The pulsed measurement techniques were used with V_C of 3 V at currents I_C of 100 mA and 300 mA.

V_{BE} and $V_{CE}(\text{SAT})$

The Base to Emitter Voltage (V_{BE}) and the Collector to Emitter Saturation Voltage ($V_{CE}(\text{SAT})$) pulsed parameters are measured by using the circuit of Figure 3-6 for S-3270 and WFD option 20.

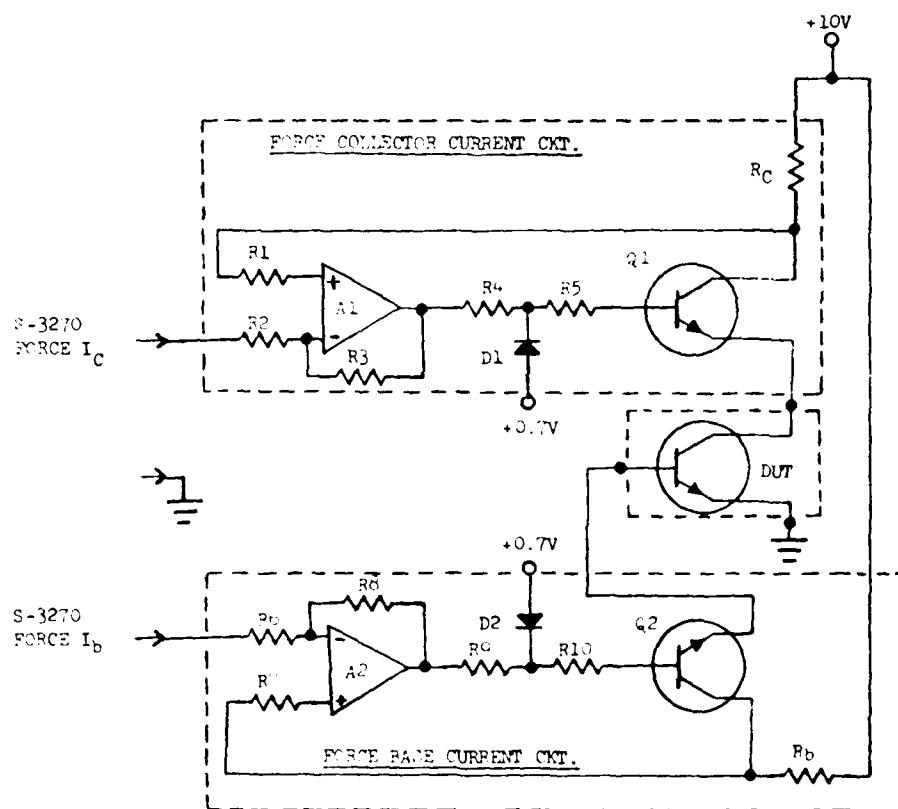


Figure 3-6. V_{BE} , $V_{CE}(\text{SAT})$ test circuit.

The requirements for these tests are to force a given base drive and collector drive current under pulsed conditions, while measuring the resultant base-to-emitter and collector-to-emitter voltages. These

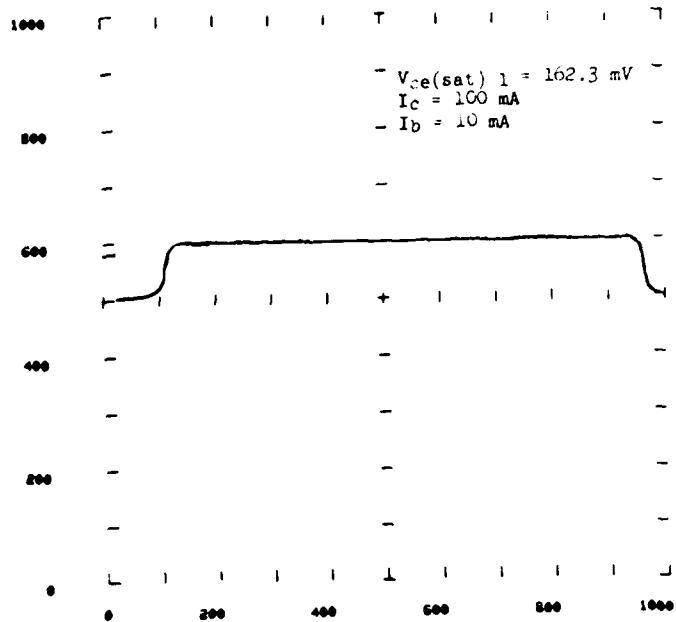


Figure 3-7A $V_{ce(sat)}$ Measurement Waveform

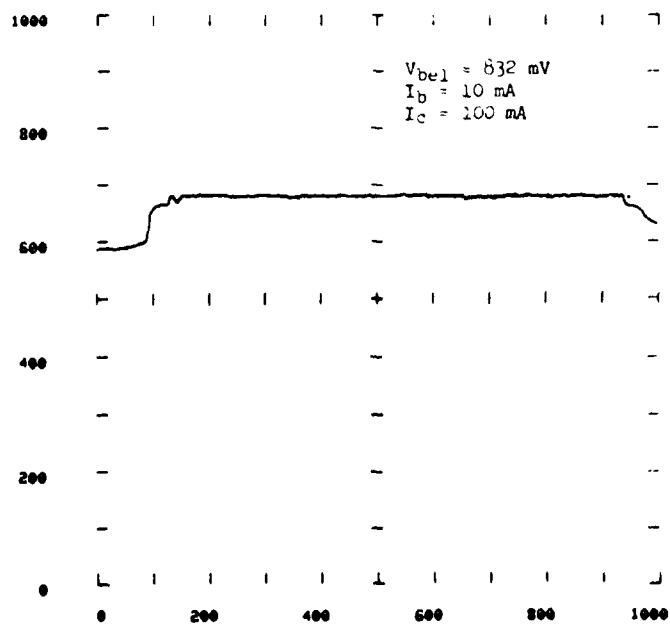


Figure 3-7B V_{bel} Measurement Waveform

are accomplished by applying an S-3270 programmed voltage V_B to one input of comparator amplifier A2. The other input to amplifier A2 monitors the voltage V_B' located at one end of resistor R_B , causing the output of A2 to servo the voltage V_B' until it exactly equals the input stimuli voltage V_B , applied from the S-3270. When these conditions are met, the DUT base current has been forced to the proper drive current level by the relationship of

$$I_B = (V_{BB} - V_B') / R_B$$

since V_{BB} and R_B are constants.

The collector current (I_C) is forced to the proper conditions in much the same way as I_B , with the exception of a much higher current provided by amplifier A1. The relationship of S-3270 input stimuli V_C to forcing current I_C , becomes

$$I_C = (V_{CC} - V_C') / R_C$$

Figure 3-7 illustrates digitized waveforms of $V_{CE(SAT)}$ and V_{SL} parameters for a typical 55450 device using a base current $I_B = 10 \text{ mA}$ and a collector current of 100 mA respectively.

V_{IL} Threshold

Input V_{IL} threshold tests are developed for the S-3270 test system to determine the margin between guaranteed $V_{IL \max} = +0.8 \text{ V}$ and the actual V_{IL} input switching point.

Referring to Figure 3-8, the tests were implemented by pulsing input A, while sampling the output for a change of state.

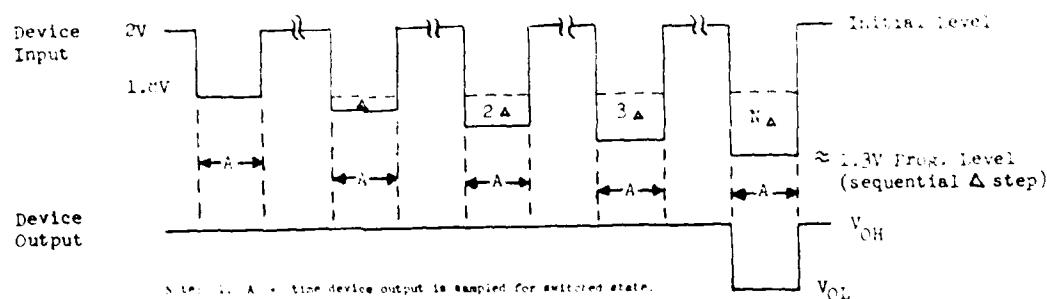
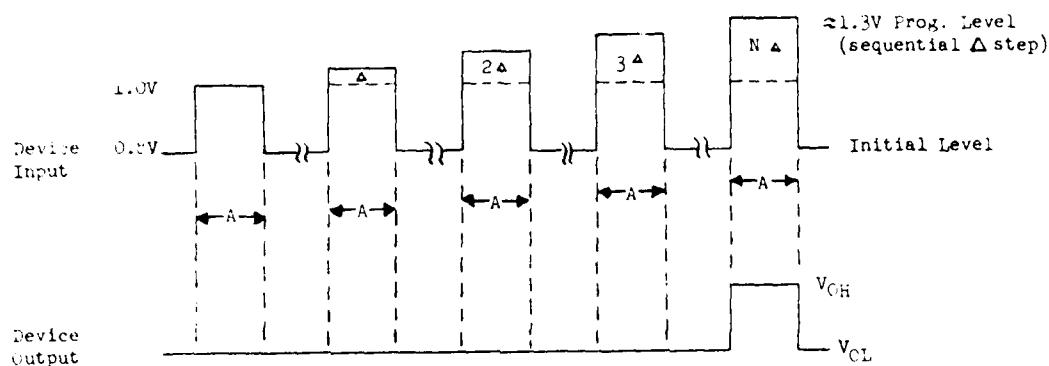


Figure 3-8. V_{IL} Threshold Test.

The initial level starts at + 2.0 V and each succeeding pulse is decremented by -10 mV. During the low level of the pulse, the device output is sampled for the V_{OL} state. If the output fails to switch during the sampling time, the input pulse is returned to + 2.0 V and a new pulse, with a level lowered by -10 mV is applied to input A. This process is repeated N times, until the output switches to V_{OL} , at which point the V_{IL} value is recorded.

V_{IH} Threshold

The input V_{IH} threshold tests are performed in a similar manner to the V_{IL} threshold tests with the exception of the initial pulse level and the delta increment (refer to Figure 3-9).



Note: 1. A = time device output is sampled for switched state.

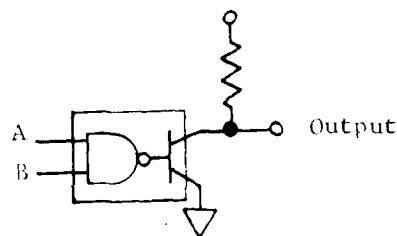


Figure 3-9. V_{IH} Threshold Test.

The initial level starts at + 0.8 V and each succeeding pulse is incremented by + 10 mV. During the high level of the pulse, the device output is sampled for the V_{OH} state. If the output fails to switch to the V_{OH} state during the sampling time, the input pulse is returned to + 0.8 V and a new pulse, with a level increased by + 10 mV.

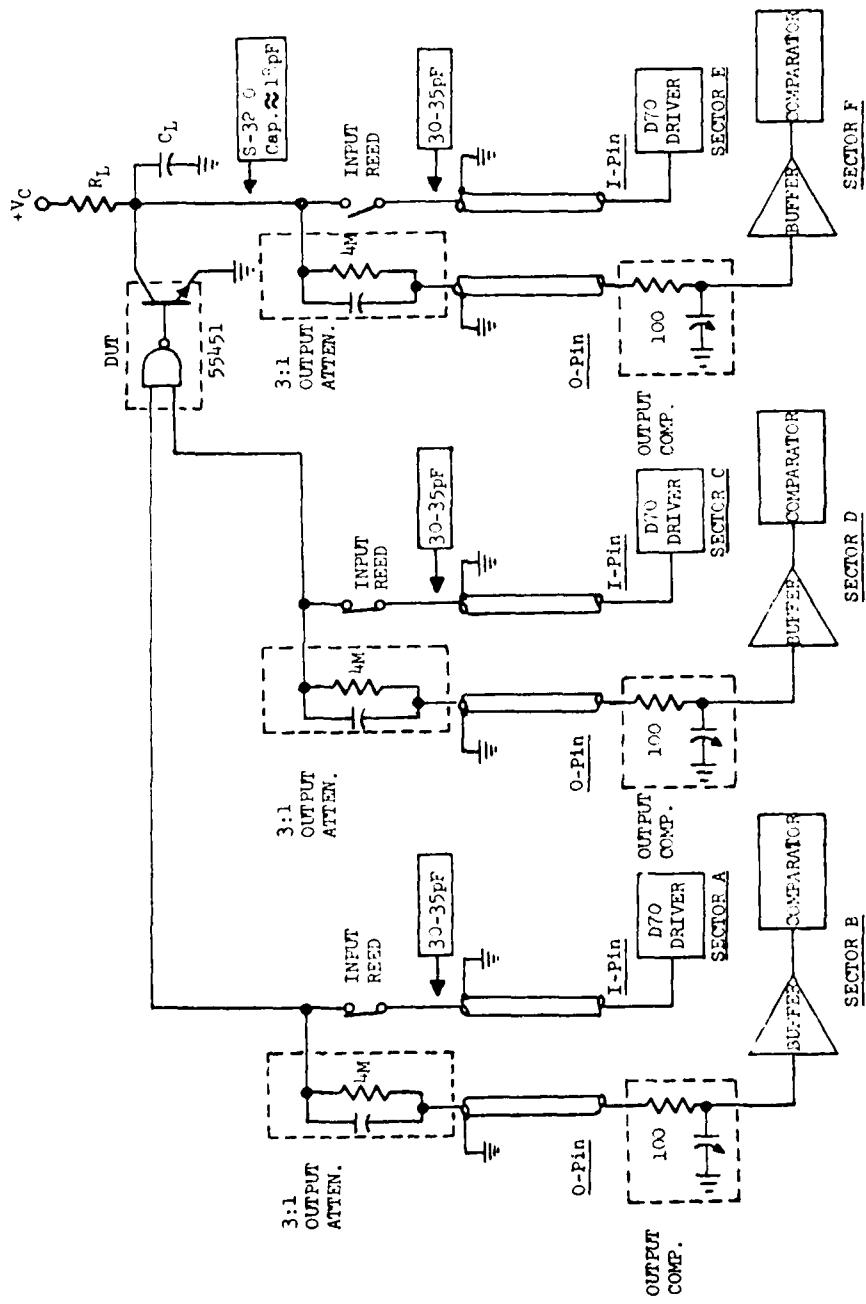


Figure 3-10 Simplified Circuit Diagram of S-3270 Test System with HP0

This process is repeated N times, until the output switches to V_{OH} , at which point the V_{IH} value is recorded.

T_{tLH} , T_{tHL} , T_{PLH} , T_{PHL}

Transition times and propagation delay times for device types (-10) were measured using the S-3270 test system, the Tektronix High Performance Option (HPO) and a specially constructed test adapter.

The HPO option provides for high accuracy time measurements, skew time corrections, low device pin capacitance (<18 pF) and buffered scope-type compensation on all device output pins connected to the S-3270 system. A simplified HPO circuit diagram is shown in Figure 3-10, indicating the different signal paths, attenuators, and output compensating networks to provide high accuracy measurements. Correction factors such as skew time between S-3270 sector pins, comparator offsets and output compensator networks are all handled under separate S-3270 calibration procedures to ensure integrity of the system.

Ambiguities can occur as a result of time measurements dependency on supply voltage, temperature, load circuit consideration, layout and test equipment inaccuracies.

Figure 3-11 is the schematic of the load circuit for TTL gates that was proposed by JC-41.

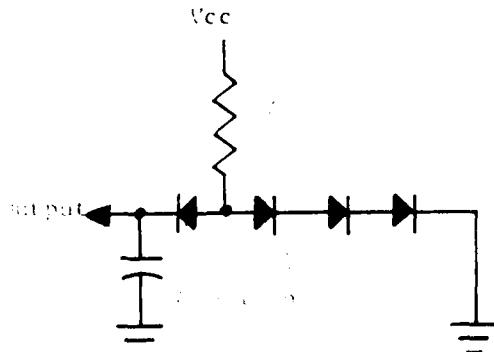


Figure 3-11. JC-41 load circuit for TTL gates.

This circuit is used to simulate 10 standard TTL loads. Comparison of output waveforms obtained with this circuit loading the 55450 "gate" output versus 10 standard TTL gates loading the same gate showed similar results. (See Figure 3-12A, B).

Figure 3-12A

T_{PLH} using JC-41 load circuit
 $V_{CC} = 4.5$ V.

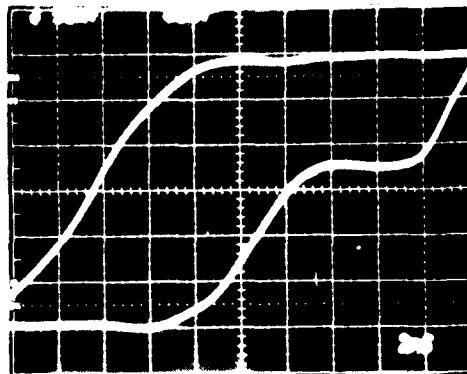
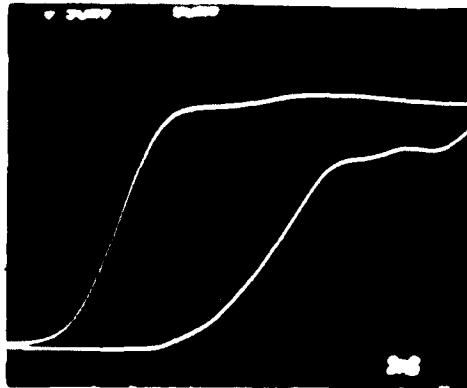


Figure 3-12B

T_{PLH} using 10 TTL gate loading
 $V_{CC} = 4.5$ V



The JC-41 load circuit, however, does not simulate worst case loading. The $400\ \Omega$ resistor only gives 10 times the nominal I_{OL} at V_{OL} . No provision was made for simulating I_{OH} loading. C_L isn't high enough to reflect the maximum input capacitances from a TTL gate (approximately 5 pF).

The JC-41 load circuit also increases the ambiguity in propagation delay time measurements.

Propagation delay times are measured at the 1.5 volt points on the input and output waveforms. The flat region in the output waveform occurs near 1.5 V. Propagation delay times can vary by as much as 4 ns as a result of placing the output decision point on the low side or the high side of the flat region in the output waveform. This is clearly unacceptable.

The circuit shown in Figure 3-13 has been used as the load circuit for testing the TTL gate portion of the peripheral driver ICs.

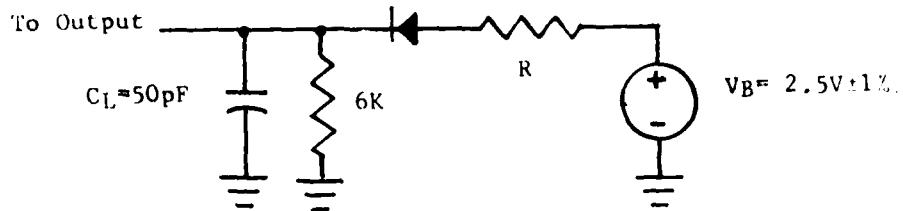


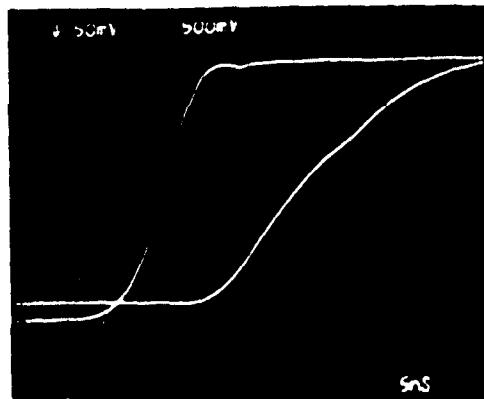
Figure 3-13. Recommended TTL gate load circuit.

This circuit eliminates the ambiguity in propagation delay measurements and also stimulates worst case loading. C_L was raised to give a realistic value for ten TTL gate input capacitances (5 pF/input). R_1 was added to give $10 \times I_{IHMAX}$. R_2 is selected to give $I_o = 10 \times I_{ILMAX}$ at V_{OLMAX} .

Figure 3-14 shows the output waveforms that result after changing the load to the recommended configuration.

Figure 3-14

T_{PLH} using recommended
load circuit
 $V_{CC} = 4.5$ V



This additional load capacitance increases T_{PLH} , and the flat region previously noted is eliminated because reverse recovery in D₁ occurs through a higher effective impedance. This eliminates the propagation delay measured ambiguity.

Switching time measurements for the output transistors and for the complete peripheral drivers were also measured with a $C_L = 50$ pF to reflect a more realistic value of load capacitance.

Supply voltage variations from 4.5 V to 5.5 V have resulted in variations in switching time measurements of up to 2 ns. The majority of devices exhibit slowest switching action at $V_{CC} = 4.5$ V so this has been selected for these measurements.

Refer to Figure 3-15 for a graph of typical variation in switching parameters with V_{CC}.

T_{thL} C_l=50PF $I_{OL}=200mA$ R_L=50ohms

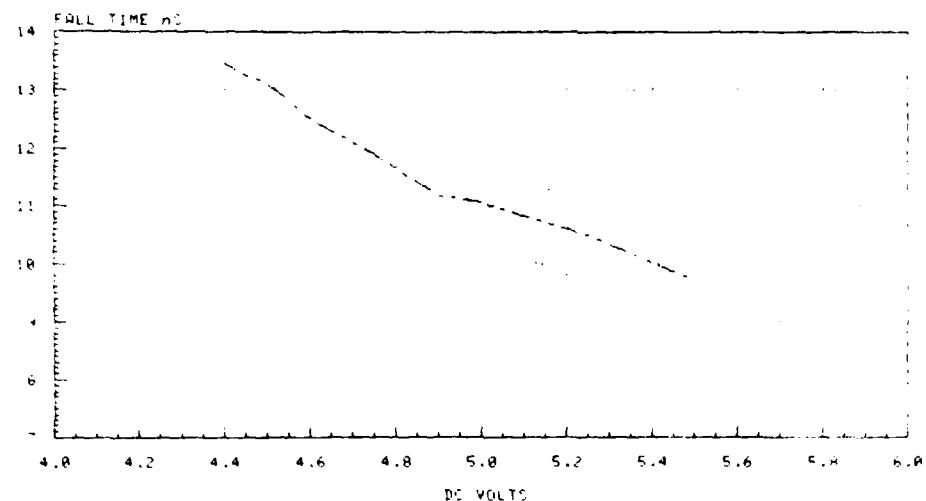


Figure 3-15 T_{thL} vs V_{CC}

Transition time tests were the most difficult to implement, since they involved switching times in the order of 10 ns or less. Careful consideration to the test adapter layout, inductance, capacitance and grounding were critical to ensure that clean output switching waveforms could be achieved.

Figure 3-16 shows typical output transition waveforms from three different vendors.

It should be noted that the output transitions are different in the 80% - 100% and 0% - 20% regions for each vendor.

Correlation of S-3270 transition and propagation time data to bench data was verified by using three independent methods. These verification methods are as follows:

- 1) Measure data on bench circuit using oscilloscope.
- 2) Measure S-3270 test adapter on bench using oscilloscope.
- 3) Measure S-3270 test adapter on S-3270 test system using oscilloscope.

Figure 3-16A

Vendor A

T_{TLH}

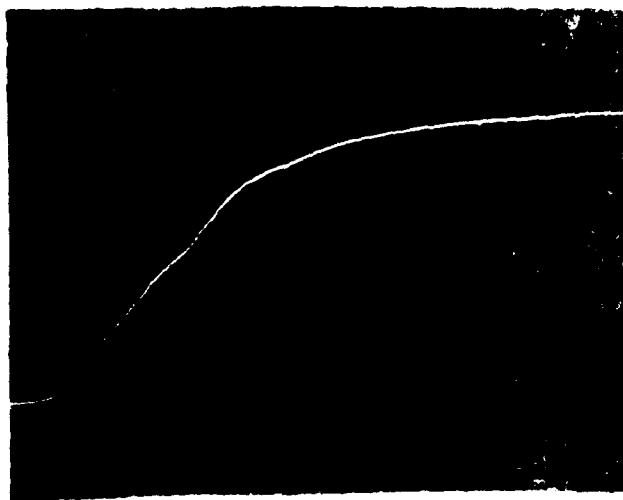


Figure 3-16B

Vendor B

T_{TLH}



Figure 3-16C

Vendor C

T_{TLH}



3.4 Test Results and Data

A total of 85 peripheral drivers were tested on GEOS' Tektronix S-3270. Each device was sequentially tested at 25°C, -55°C and 125°C.

A typical data sheet for a group of 55450 devices is shown in Table 3-4. Data for up to 5 devices is displayed on a single sheet. This method simplifies comparison of different devices at a single temperatures.

The data was also recorded in the form of histograms for selected parameters at three temperatures. (A sample histogram is given in Table 3-5.) Included were the following:

55460	$t_{T_{HL}}$ t_{TLH}	t_{PLH} t_{PHL}
	t_{PHL1} t_{PLH2}	t_D t_R t_S t_F
	$h_{FE \ 1,2}$ $V_{BE \ 1,2}$ $V_{CE \ 1,2}$	V_{CB01} V_{CER1} V_{BEO}
55451	$t_{T_{HL}}$ t_{TLH}	t_{PLH} t_{PHL}
55453	$t_{T_{HL}}$ t_{TLH}	t_{PLH} t_{PHL}
55461	$t_{T_{HL}}$ t_{TLH}	t_{PLH} t_{PHL}
55463	$t_{T_{HL}}$ t_{TLH}	t_{PLH} t_{PHL}

This data was published in January 1981 for RADC in a 211 pg handbook entitled:

Characterization Data for MIL-M-38510/129
Peripheral Drivers

(55450, -451, -452, -453, -454
55460, -461, -462, -463, -464)

Sample data sheets and histograms have been included in the Appendix.

3.5 Discussion of Results

Most of the test data taken on the 55450/55460 family of peripheral drivers was within the limits proposed by the JC-41 Committee. The exceptions were the result of changes in test conditions (for example, changing the load circuit for timing tests). Although data on a number of parameters fell within a relatively tight spread relative to the test limits, no attempt was made to tighten the test limits due to the relatively small number of device samples. The exceptions are noted below.

Short-circuit output current (IOS)

As originally specified, the IOSMIN specification was tested at VCCMAX. But IOSMIN is lower at VCCMIN. To ensure that IOS would be within the test limits over the full supply voltage range, IOSMIN is tested at VCCMIN and IOSMAX is tested at VCCMAX.

Threshold Voltage (VT)

Threshold testing of the peripheral drivers gave results that were within the expected range of values. The nominal VT was approximately 1.3 volts at TA = 25°C with a d VT/dTA approximately -3 mV/°C. This agrees well with measured VT values for standard TTL.

Breakdown Voltage, VCBO, VCER, VEBO

In all devices tested, VCBO was greater than 17 volts (or nearly 50%) above the minimum breakdown limit. For VCER, all of the devices were greater than 22 volts above the minimum test limit.

Vendor A showed slightly lower VEBO than Vendor B (approximately .5 volts lower on the average).

There were no significant trends observed in breakdown voltages versus temperature.

All breakdown voltages were taken with the substrate pin floating.

Static Forward Current Transfer Ratio (h_{FE})

The JC-41 Committee test conditions specify that h_{FE} is to be measured under pulsed conditions with $t_w = 300$ us and a duty cycle < 2%. The devices were tested over a range of values for t_w with the duty cycle fixed at 2% with negligible changes in the measured values. T_A was changed to $t_w = 100$ us to simplify test hardware.

At $T_A = 25^\circ$, all measured h_{FE} 's exceeded the minimum test limit by greater than two to one. As expected, h_{FE} tended to increase with increasing temperature over the full temperature range. In all cases, the devices tested exceeded the minimum test limit by a reasonable margin.

3.6 Slash Sheet Development

The military specification (MIL-M-38510 slash sheet) on the peripheral drivers was developed in parallel with the characterization effort. The majority of the slash sheet Table I parameters and limits were recommended by the JC-41 Committee on Linear Integrated Circuits. The major changes occurred in the switching time test load circuit and the V_{CC} specification for the switching tests. As a result, the switching parameter test limits were relaxed as needed to accommodate the new test conditions. Also, the I_{OS} testing is now specified at both extremes in supply voltage in order to have the test data reflect the worst case.

3.7 Conclusions and Recommendations

85 generic 55450/460 peripheral drivers were tested on GEOS' S-3270 to characterize their electrical parameters. Bench data was taken to validate S-3270 operation. With the exception of switching time parameters, the devices were well within the test limits.

The switching time of the devices was slowed as a result of the revised test conditions. The test limits for these parameters have been widened to accommodate the test changes.

APPENDIX - SECTION III
PERIPHERAL DRIVERS DATA
SHEETS AND HISTOGRAMS

SS450 DUAL PERIPHERAL POSITION-AND DRIVER (STATIC TESTS ONLY)
 TEMPERATURE=25DEG C ; DATE=09 DEC 80 TIME=11:17:33

PARAMETER	TEST CONDITIONS	V _{DD}	V _{C-LINK}	V _{IN}	S _H -2	S _H -2	S _H -2	S _H -4	S _H -5	S _H -5	S _H -5
U _L	UCC=4.5V	1	0.000	1.320	1.320	1.320	1.320	1.320	1.320	1.320	1.320
		2	0.000	1.348	1.348	1.348	1.348	1.348	1.348	1.348	1.348
		13	0.000	1.350	1.340	1.330	1.320	1.310	1.300	1.290	1.280
U _H	UCC=4.5V	1	2.000	1.210	1.230	1.230	1.230	1.230	1.230	1.230	1.230
		2	2.000	1.213	1.230	1.230	1.230	1.230	1.230	1.230	1.230
		13	2.000	1.218	1.230	1.230	1.230	1.230	1.230	1.230	1.230
U _X	UCC=4.5V	1	-1.5	1.01	-0.01	-0.01	-0.01	-0.01	-0.01	-0.01	-0.01
		2	-1.5	1.01	-0.01	-0.01	-0.01	-0.01	-0.01	-0.01	-0.01
		13	-1.5	1.01	-0.01	-0.01	-0.01	-0.01	-0.01	-0.01	-0.01
U _{H1}	UCC=5.5V	1	0.000	9.650	8.450	7.250	7.250	7.250	7.250	7.250	7.250
		2	0.000	9.650	8.450	7.250	7.250	7.250	7.250	7.250	7.250
		13	0.000	9.650	8.450	7.250	7.250	7.250	7.250	7.250	7.250
U _{H2}	UCC=5.5V	1	0.000	7.350	6.550	5.550	5.550	5.550	5.550	5.550	5.550
		2	0.000	7.350	6.550	5.550	5.550	5.550	5.550	5.550	5.550
		13	0.000	7.350	6.550	5.550	5.550	5.550	5.550	5.550	5.550
U _{H3}	UCC=5.5V	1	0.000	7.350	6.550	5.550	5.550	5.550	5.550	5.550	5.550
		2	0.000	7.350	6.550	5.550	5.550	5.550	5.550	5.550	5.550
		13	0.000	7.350	6.550	5.550	5.550	5.550	5.550	5.550	5.550
U _{H4}	UCC=5.5V	1	0.000	3.650	3.180	2.580	2.580	2.580	2.580	2.580	2.580
		2	0.000	3.650	3.180	2.580	2.580	2.580	2.580	2.580	2.580
		13	0.000	3.650	3.180	2.580	2.580	2.580	2.580	2.580	2.580
U _{H5}	UCC=5.5V	1	0.000	2.800	2.450	2.050	2.050	2.050	2.050	2.050	2.050
		2	0.000	2.800	2.450	2.050	2.050	2.050	2.050	2.050	2.050
		13	0.000	2.800	2.450	2.050	2.050	2.050	2.050	2.050	2.050
U _{H6}	UCC=5.5V	1	0.000	1.160	-1.245	-1.265	-1.265	-1.265	-1.265	-1.265	-1.265
		2	0.000	1.160	-1.245	-1.265	-1.265	-1.265	-1.265	-1.265	-1.265
		13	0.000	1.160	-1.245	-1.265	-1.265	-1.265	-1.265	-1.265	-1.265
U _{L1}	UCC=4.5V	1	0.000	209.5M	171.5M	183.5M	183.5M	183.5M	178.0M	175.5M	175.5M
		2	0.000	209.5M	171.5M	183.5M	183.5M	183.5M	178.0M	175.5M	175.5M
		13	0.000	209.5M	171.5M	183.5M	183.5M	183.5M	178.0M	175.5M	175.5M
U _{L2}	UCC=4.5V	1	0.000	2.450	2.750	2.750	2.750	2.750	2.750	2.750	2.750
		2	0.000	2.450	2.750	2.750	2.750	2.750	2.750	2.750	2.750
		13	0.000	2.450	2.750	2.750	2.750	2.750	2.750	2.750	2.750
U _{L3}	UCC=4.5V	1	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		2	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		13	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
U _{L4}	UCC=4.5V	1	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		2	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		13	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
U _{L5}	UCC=4.5V	1	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		2	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		13	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
U _{L6}	UCC=4.5V	1	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		2	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		13	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
U _{L7}	UCC=4.5V	1	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		2	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		13	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
U _{L8}	UCC=4.5V	1	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		2	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		13	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
U _{L9}	UCC=4.5V	1	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		2	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		13	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
U _{L10}	UCC=4.5V	1	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		2	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		13	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
U _{L11}	UCC=4.5V	1	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		2	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
		13	0.000	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M	22.65M
U _{L12}	UCC=5.5V	8	0.403	7.603	8.30M	8.50M	8.50M	8.50M	8.50M	8.50M	8.50M
		9	0.403	7.603	8.30M	8.50M	8.50M	8.50M	8.50M	8.50M	8.50M
		10	0.403	7.603	8.30M	8.50M	8.50M	8.50M	8.50M	8.50M	8.50M

卷之三

55450 DUAL PERIPHERAL POSITIVE-AND DRIVER (STATIC TESTS ONLY)
 TEMPERATURE=25DEG C ; DATE=11 DEC 80 TIME=09:36:33

PARAMETER	TEST CONDITIONS	TEST DATA	LO-LIMIT	SM11	SM12	SM13	SM14	SM15	HI-LIMIT	NOTE
V _H	VCC=4.5V	1 2 13	1.390 1.390 1.390	1.390 1.390 1.390	1.370 1.380 1.390	1.380 1.390 1.390	1.400 1.410 1.420	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=4.5V	1 2 13	1.420 1.420 1.420	1.420 1.420 1.420	1.390 1.400 1.400	1.390 1.400 1.400	1.410 1.420 1.430	2.000 2.000 2.000	2.000 2.000 2.000	
	VCC=4.5V	1 2 13	1.450 1.450 1.450	1.450 1.450 1.450	1.420 1.430 1.430	1.420 1.430 1.430	1.440 1.450 1.460	2.000 2.000 2.000	2.000 2.000 2.000	
V _{IH}	VCC=4.5V	1 2 13	1.480 1.480 1.480	1.480 1.480 1.480	1.450 1.460 1.460	1.450 1.460 1.460	1.470 1.480 1.490	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	1.510 1.510 1.510	1.510 1.510 1.510	1.480 1.490 1.490	1.480 1.490 1.490	1.500 1.510 1.520	2.000 2.000 2.000	2.000 2.000 2.000	
	VIH=5.5V	1 2 13	1.540 1.540 1.540	1.540 1.540 1.540	1.510 1.520 1.520	1.510 1.520 1.520	1.530 1.540 1.550	2.000 2.000 2.000	2.000 2.000 2.000	
V _{IL}	VCC=4.5V	1 2 13	1.570 1.570 1.570	1.570 1.570 1.570	1.540 1.550 1.550	1.540 1.550 1.550	1.560 1.570 1.580	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	1.600 1.600 1.600	1.600 1.600 1.600	1.570 1.580 1.580	1.570 1.580 1.580	1.590 1.600 1.610	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	1.630 1.630 1.630	1.630 1.630 1.630	1.600 1.610 1.610	1.600 1.610 1.610	1.620 1.630 1.640	2.000 2.000 2.000	2.000 2.000 2.000	
I _H	VCC=4.5V	1 2 13	1.660 1.660 1.660	1.660 1.660 1.660	1.630 1.640 1.640	1.630 1.640 1.640	1.650 1.660 1.670	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	1.690 1.690 1.690	1.690 1.690 1.690	1.660 1.670 1.670	1.660 1.670 1.670	1.680 1.690 1.700	2.000 2.000 2.000	2.000 2.000 2.000	
	VIH=5.5V	1 2 13	1.720 1.720 1.720	1.720 1.720 1.720	1.690 1.700 1.700	1.690 1.700 1.700	1.710 1.720 1.730	2.000 2.000 2.000	2.000 2.000 2.000	
I _L	VCC=4.5V	1 2 13	1.750 1.750 1.750	1.750 1.750 1.750	1.720 1.730 1.730	1.720 1.730 1.730	1.740 1.750 1.760	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	1.780 1.780 1.780	1.780 1.780 1.780	1.750 1.760 1.760	1.750 1.760 1.760	1.770 1.780 1.790	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	1.810 1.810 1.810	1.810 1.810 1.810	1.780 1.790 1.790	1.780 1.790 1.790	1.800 1.810 1.820	2.000 2.000 2.000	2.000 2.000 2.000	
I _O	VCC=4.5V	1 2 13	1.840 1.840 1.840	1.840 1.840 1.840	1.810 1.820 1.820	1.810 1.820 1.820	1.830 1.840 1.850	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	1.870 1.870 1.870	1.870 1.870 1.870	1.840 1.850 1.850	1.840 1.850 1.850	1.860 1.870 1.880	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	1.900 1.900 1.900	1.900 1.900 1.900	1.870 1.880 1.880	1.870 1.880 1.880	1.890 1.900 1.910	2.000 2.000 2.000	2.000 2.000 2.000	
I _{G1}	VCC=4.5V	1 2 13	1.930 1.930 1.930	1.930 1.930 1.930	1.900 1.910 1.910	1.900 1.910 1.910	1.920 1.930 1.940	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	1.960 1.960 1.960	1.960 1.960 1.960	1.930 1.940 1.940	1.930 1.940 1.940	1.950 1.960 1.970	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	1.990 1.990 1.990	1.990 1.990 1.990	1.960 1.970 1.970	1.960 1.970 1.970	1.980 1.990 2.000	2.000 2.000 2.000	2.000 2.000 2.000	
I _{G2}	VCC=4.5V	1 2 13	2.020 2.020 2.020	2.020 2.020 2.020	1.990 2.000 2.000	1.990 2.000 2.000	2.010 2.020 2.030	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	2.050 2.050 2.050	2.050 2.050 2.050	2.020 2.030 2.030	2.020 2.030 2.030	2.040 2.050 2.060	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	2.080 2.080 2.080	2.080 2.080 2.080	2.050 2.060 2.060	2.050 2.060 2.060	2.070 2.080 2.090	2.000 2.000 2.000	2.000 2.000 2.000	
I _{G3}	VCC=4.5V	1 2 13	2.110 2.110 2.110	2.110 2.110 2.110	2.080 2.090 2.090	2.080 2.090 2.090	2.100 2.110 2.120	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	2.140 2.140 2.140	2.140 2.140 2.140	2.110 2.120 2.120	2.110 2.120 2.120	2.130 2.140 2.150	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	2.170 2.170 2.170	2.170 2.170 2.170	2.140 2.150 2.150	2.140 2.150 2.150	2.160 2.170 2.180	2.000 2.000 2.000	2.000 2.000 2.000	
I _{G4}	VCC=4.5V	1 2 13	2.200 2.200 2.200	2.200 2.200 2.200	2.170 2.180 2.180	2.170 2.180 2.180	2.190 2.200 2.210	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	2.230 2.230 2.230	2.230 2.230 2.230	2.200 2.210 2.210	2.200 2.210 2.210	2.220 2.230 2.240	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	2.260 2.260 2.260	2.260 2.260 2.260	2.230 2.240 2.240	2.230 2.240 2.240	2.250 2.260 2.270	2.000 2.000 2.000	2.000 2.000 2.000	
I _{G5}	VCC=4.5V	1 2 13	2.290 2.290 2.290	2.290 2.290 2.290	2.260 2.270 2.270	2.260 2.270 2.270	2.280 2.290 2.300	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	2.320 2.320 2.320	2.320 2.320 2.320	2.290 2.300 2.300	2.290 2.300 2.300	2.310 2.320 2.330	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	2.350 2.350 2.350	2.350 2.350 2.350	2.320 2.330 2.330	2.320 2.330 2.330	2.340 2.350 2.360	2.000 2.000 2.000	2.000 2.000 2.000	
I _{G6}	VCC=4.5V	1 2 13	2.380 2.380 2.380	2.380 2.380 2.380	2.350 2.360 2.360	2.350 2.360 2.360	2.370 2.380 2.390	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	2.410 2.410 2.410	2.410 2.410 2.410	2.380 2.390 2.390	2.380 2.390 2.390	2.400 2.410 2.420	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	2.440 2.440 2.440	2.440 2.440 2.440	2.410 2.420 2.420	2.410 2.420 2.420	2.430 2.440 2.450	2.000 2.000 2.000	2.000 2.000 2.000	
I _{G7}	VCC=4.5V	1 2 13	2.470 2.470 2.470	2.470 2.470 2.470	2.440 2.450 2.450	2.440 2.450 2.450	2.460 2.470 2.480	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	2.500 2.500 2.500	2.500 2.500 2.500	2.470 2.480 2.480	2.470 2.480 2.480	2.490 2.500 2.510	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	2.530 2.530 2.530	2.530 2.530 2.530	2.500 2.510 2.510	2.500 2.510 2.510	2.520 2.530 2.540	2.000 2.000 2.000	2.000 2.000 2.000	
I _{G8}	VCC=4.5V	1 2 13	2.560 2.560 2.560	2.560 2.560 2.560	2.530 2.540 2.540	2.530 2.540 2.540	2.550 2.560 2.570	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	2.590 2.590 2.590	2.590 2.590 2.590	2.560 2.570 2.570	2.560 2.570 2.570	2.580 2.590 2.600	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	2.620 2.620 2.620	2.620 2.620 2.620	2.590 2.600 2.600	2.590 2.600 2.600	2.610 2.620 2.630	2.000 2.000 2.000	2.000 2.000 2.000	
I _{G9}	VCC=4.5V	1 2 13	2.650 2.650 2.650	2.650 2.650 2.650	2.620 2.630 2.630	2.620 2.630 2.630	2.640 2.650 2.660	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	2.680 2.680 2.680	2.680 2.680 2.680	2.650 2.660 2.660	2.650 2.660 2.660	2.670 2.680 2.690	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	2.710 2.710 2.710	2.710 2.710 2.710	2.680 2.690 2.690	2.680 2.690 2.690	2.700 2.710 2.720	2.000 2.000 2.000	2.000 2.000 2.000	
I _{G10}	VCC=4.5V	1 2 13	2.740 2.740 2.740	2.740 2.740 2.740	2.710 2.720 2.720	2.710 2.720 2.720	2.730 2.740 2.750	2.000 2.000 2.000	2.000 2.000 2.000	U
	VCC=5.5V	1 2 13	2.770 2.770 2.770	2.770 2.770 2.770	2.740 2.750 2.750	2.740 2.750 2.750	2.760 2.770 2.780	2.000 2.000 2.000	2.000 2.000 2.000	
	VIL=5.5V	1 2 13	2.800 2.800 2.800	2.800 2.800 2.800	2.770 2.780 2.780	2.770 2.780 2.780	2.790 2.800 2.810	2.000 2.000 2.000	2.000 2.000 2.000	

TESTS OF DIODES IN GENERAL POSITION AND DRIVERS (STATIC TESTS ONLY)
TESTS OF DIODES IN GENERAL POSITION AND DRIVERS (STATIC TESTS ONLY)

TEST NUMBER	TEST CONDITIONS	TEST FREQ.	LO-LIMIT	S/N1	S/N2	S/N3	S/N4	S/N5	HI-LIMIT	TESTS
UCE501	IC-100mA	IE=0	5 10	35.00 25.00	52.55 53.75	52.60 51.45	72.70 73.62	65.50 75.15	68.75 73.15	102.6 103.0
UCE502	IC-100mA	Rbe=500	5 10	30.00 30.00	55.60 53.55	52.35 61.60	73.80 73.42	64.55 75.20	67.50 73.55	102.6 103.0
UCE503	IC-100mA	IC=0	5 10	5.000 5.000	6.810 5.995	6.350 6.350	6.335 6.220	6.235 6.240	6.235 6.235	25.00 25.00
UCE504	IC=0	3V	5 10	25.00 25.00	70.30 60.93	83.17 50.19	61.93 62.02	54.35 60.24	75.50 76.23	201.0 201.0
UCE505	Uce=3V	IC=30mA	5 10	32.00 32.00	73.93 75.17	73.76 75.89	74.46 78.15	77.38 69.02	68.82 69.02	200.0 200.0
UCE506	Ib=10mA	IC=100mA	4 11	0.000 0.000	742.2M 805.6M	805.6M 831.0M	805.6M 818.3M	805.6M 831.0M	805.6M 831.0M	1.000 1.000
UCE507	Ib=30mA	IC=300mA	4 11	0.000 0.000	562.1M 554.5M	517.5M 545.2M	532.5M 530.2M	545.2M 545.2M	545.2M 545.2M	1.200 1.200
UCE508	Ib=10mA	IC=100mA	5 10	272.9M 261.1M	313.2M 260.6M	265.2M 269.6M	265.2M 269.6M	290.6M 272.9M	400.0M 400.0M	200.0 200.0
UCE509	Ib=30mA	IC=300mA	5 10	0.000 0.000	377.4M 275.3M	415.5M 462.8M	352.5M 357.0M	372.6M 352.6M	372.6M 377.4M	700.0M 700.0M

56450 DUAL PERIPHERAL POSITIVE-AND DRIVER (STATIC TESTS ONLY)
 TEMPERATURE=25DEG C ; DATE=10 DEC 88 TIME=10:06:53

TEST CONDITIONS	TEST PIN#	LO-LIMIT	SN6	SN7	SN8	SN9	SN10	HI-LIMIT	UNITS
IC-E1 IC=10mA	5 10	35.00 35.00	72.75 81.95	71.50 71.15	69.75 70.00	70.45 70.60	74.80 74.75	100.0 100.0	U
IC-E2 IC=500	5 10	33.00 30.00	72.40 81.75	71.20 71.55	70.00 70.00	70.35 70.30	74.50 74.45	100.0 100.0	U
U2E0 IE=10mA IC=0	5 10	5.000 5.000	6.320 6.320	6.230 6.230	6.250 6.250	6.265 6.255	6.350 6.360	25.00 25.00	U
U2E1 Uce=3V	IC=100mA 10	25.00 25.00	82.02 85.31	81.77 83.50	81.71 83.50	82.75 82.90	92.30 93.40	250.0 250.0	X
U2E2 Uce=3V	IC=300mA 10	31.00 30.00	73.53 74.70	75.17 76.14	63.13 62.46	65.58 67.07	84.58 85.19	250.0 250.0	X
U3E1 Ib=10mA	IC=100mA 11	0.620 0.630	835.0M 818.3M	818.3M 816.3M	818.3M 831.0M	818.3M 818.3M	818.3M 818.3M	1.000	U
U3E2 Ib=30mA	IC=300mA 11	0.500 0.500	937.5M 932.2M	932.5M 945.2M	957.5M 945.2M	945.2M 952.5M	932.5M 931.0M	1.200	U
UCEST1 Ib=10mA	IC=100mA 13	0.600 0.600	227.5M 230.5M	227.5M 225.0M	227.5M 225.0M	225.2M 225.2M	252.4M 252.5M	400.0M 400.0M	U
UCEST2 Ib=30mA	IC=300mA 10	0.500 0.500	215.1M 215.0M	206.7M 205.0M	217.4M 219.3M	219.3M 239.0M	326.7M 326.3M	700.0M 700.0M	U

SG450 DUAL PERIPHERAL POSITIONER AND DRIVER ; DATE = 10 DEC 80 TIME = 16:03:22
 TEMPERATURE = 25DEG ; STATIC TESTS ONLY)

TEST NUMBER	TEST CONDITIONS	TEST PTH#	LO-LIMIT	SN11	SN12	SN13	SN14	SN15	HI-LIMIT	NITE
UCE1	IC=100mA IE=0	5 10	35.00 35.00	52.85 53.15	59.55 59.75	60.65 62.30	61.35 61.60	58.55 58.60	100.0 100.0	U U
UCE2	IC=100mA Rbe=500	5 10	30.00 30.00	52.90 53.25	59.55 59.85	60.70 62.40	61.40 61.65	58.60 58.70	100.0 100.0	U U
UCE3	IE=100mA IC=0	5 10	5.000 5.000	6.780 6.785	6.835 6.825	6.755 6.680	6.820 6.835	6.560 6.560	25.00 25.00	U U
UFE1	Uce=3V IC=100mA	5 10	25.00 25.00	52.25 57.49	61.62 62.62	75.67 74.19	87.62 89.71	83.39 82.74	100.0 100.0	X X
UFE2	Uce=3V IC=300mA	5 10	30.00 30.00	62.97 61.89	73.53 74.02	68.28 67.46	73.67 75.71	75.64 77.15	200.0 200.0	X X
UFE3	Ib=10mA IC=100mA	4 11	0.030 0.030	817.6M 826.8M	805.6M 815.4M	804.4M 817.8M	808.7M 818.3M	831.0M 831.0M	1.010 1.000	U U
UFE4	Ib=30mA IC=300mA	4 11	0.070 0.070	935.5M 942.8M	934.5M 945.0M	947.8M 947.6M	945.2M 945.8M	922.5M 932.5M	1.200 1.200	U U
UCEST1	Ib=10mA IC=100mA	5 10	0.030 0.030	259.6M 259.2M	265.2M 267.8M	267.6M 289.2M	265.2M 266.0M	215.2M 264.8M	400.0M 400.0M	U U
UCEST2	Ib=30mA IC=300mA	5 10	0.070 0.070	343.6M 391.2M	349.5M 351.8M	359.5M 351.2M	353.6M 353.8M	325.5M 324.8M	700.0M 700.0M	U U

55459 DUAL PERIPHERAL POSITIVE-AND DRIVER -02 DEG C ; DATE-08 DEC 80 TIME-17:22:56
TEMPERATURE-25DEG C ; DATE-08 DEC 80 TIME-17:22:56

TEST PINS	TEST CONDITIONS	TEST TIME	S11	S12	S13	S14	S15	HIGH-LIMIT
77L	UCC-4.5V IOL-200mA RI-50	5 0.000 10 0.000	9.32SN 9.25SN	10.66N 10.66N	9.20SN 9.25SN	9.35SN 9.38SN	15.00N 15.00N	5 5
77LH	UCC-4.5V IOL-200mA RI-50	5 0.000 10 0.000	9.12SN 8.42SN	9.17DN 8.72N	8.97DN 8.37DN	9.02DN 8.46DN	8.92DN 8.42DN	12.00N 12.00N
7P2H	UCC-4.5V IOL-200mA RI-50	1 0.000 2 0.000 3 0.000	15.72N 15.64N 15.24N	15.76N 15.71N 15.31N	15.43N 15.43N 15.03N	15.92N 15.87N 15.47N	15.22N 15.17N 14.77N	30.00N 30.00N 30.00N
7PHL	UCC-4.5V IOL-200mA RI-50	1 0.000 2 0.000 3 0.000	18.32N 18.11N 17.76N	18.90N 18.76N 18.41N	18.12N 17.92N 17.57N	18.27N 18.07N 17.72N	18.06N 17.88N 17.53N	30.00N 30.00N 30.00N

55459 DUAL PERIPHERAL POSITIVE-AND DRIVER -02 DEG C ; DATE-08 DEC 80 TIME-17:17:17
TEMPERATURE-25DEG C ; DATE-08 DEC 80 TIME-17:17:17

TEST PINS	TEST CONDITIONS	TEST TIME	S11	S12	S13	S14	S15	HIGH-LIMIT
77L	UCC-4.5V IOL-200mA RI-50	5 0.000 10 0.000	9.12SN 9.02SN	9.17DN 8.72N	9.35SN 9.38SN	9.42SN 9.42SN	15.00N 15.00N	5 5
77LH	UCC-4.5V IOL-200mA RI-50	5 0.000 10 0.000	9.12SN 8.42SN	9.17DN 8.26N	9.35SN 8.32DN	9.42SN 8.32DN	15.00N 15.00N	5 5
7P2H	UCC-4.5V IOL-200mA RI-50	1 0.000 2 0.000 3 0.000	15.63N 15.55N 15.17N	15.76N 15.71N 15.31N	15.43N 15.43N 15.03N	14.72N 14.72N 14.72N	15.21N 15.14N 15.14N	30.00N 30.00N 30.00N
7PHL	UCC-4.5V IOL-200mA RI-50	1 0.000 2 0.000 3 0.000	18.32N 18.11N 17.76N	18.90N 18.76N 18.41N	18.12N 17.92N 17.57N	18.27N 18.07N 17.72N	18.06N 17.88N 17.53N	30.00N 30.00N 30.00N

55450 DUAL PERIPHERAL POSITIVE-AND DRIVER (GATES & TRANSISTORS COMBINED)
 TEMPERATURE=25DEG C ; DATE=08 DEC 80 TIME=17:30:25

TEST CONDITIONS	TEST FREQ	LO-LIMIT	SN11	SN12	SN13	SN14	SN15	HI-LIMIT	NITS
VCC=4.5V TCL=200mA R1=50	C1=50PF 5 10	0.000 0.020	11.16N 11.61N	10.26N 10.25N	10.11N 10.41N	9.69N 9.708N	10.46N 10.71N	15.00N 15.00N	S S
VCC=4.5V TCL=200mA R1=50	C1=50PF 5 10	0.000 0.020	10.47N 9.47CN	10.17N 9.57CN	10.02N 9.72N	10.42N 9.47CN	9.97NN 9.17EN	12.00N 12.00N	S S
VCC=4.5V TCL=220mA	C1=50PF 1 2	0.000 0.220	21.47N 21.52N	16.05N 16.20N	12.53N 17.75N	19.53N 19.65N	19.73N 19.28N	20.73N 20.28N	S S
VCC=4.5V TCL=200mA R1=50	C1=50PF 1 2	0.000 0.230	20.96N 20.96N	18.20N 18.20N	19.65N 19.65N	19.65N 19.65N	19.65N 19.65N	20.00N 20.00N	S S
VCC=4.5V TCL=200mA R1=50	C1=50PF 1 2	0.000 0.020	19.54N 19.42N	18.84N 18.40N	18.56N 18.67N	18.67N 18.40N	19.32N 20.56N	20.32N 20.56N	S S
TPL									

SS450 DUAL PERIPHERAL POSITIVE-AND DRIVER (SWITCHING TIME-TTL GATE ONLY)
TEMPERATURE=25DEG C ; DATE=15 DEC 92

PIN#	TEST CONDITIONS	TEST PIN#	LO-LIMIT	SN1	SN2	SN3	SN4	SNS	HI-LIMIT	UNITS
T22.1	UCC=4.5V CL=52PF	IOL=16mA	1 2 13	0.000 0.000 0.000	11.5GN 12.15N 10.93N	12.0EN 12.61N 11.35N	10.87N 11.46N 10.24N	12.44N 13.02N 11.81N	12.21N 12.80N 11.56N	22.0CN 22.8CN 22.5CN
T22.2	UCC=4.5V CL=52PF	IOL=16mA	1 2 13	0.000 0.000 0.000	7.94DN 8.12CN 6.51EN	8.10DN 8.12CN 7.197N	7.47EN 7.42EN 7.15EN	8.47CN 8.47EN 7.51EN	8.25CN 8.30CN 7.53EN	22.0CN 22.8CN 22.5CN

SS450 DUAL PERIPHERAL POSITIVE-AND DRIVER (SWITCHING TIME-TTL GATE ONLY)
TEMPERATURE=25DEG C ; DATE=15 DEC 92

PIN#	TEST CONDITIONS	TEST PIN#	LO-LIMIT	SN1	SN2	SN3	SN4	SNS	HI-LIMIT	UNITS
T22.1	UCC=4.5V CL=52PF	IOL=16mA	1 2 13	0.000 0.000 0.000	11.44N 12.34N 13.24N	12.0EN 12.51N 12.81N	11.80N 11.58N 10.53N	10.50N 11.56N 10.35N	10.25N 10.56N 10.35N	22.0CN 22.8CN 22.5CN
T22.2	UCC=4.5V CL=52PF	IOL=16mA	1 2 13	0.000 0.000 0.000	7.11N 6.72N 6.83EN	7.07EN 6.73EN 6.63EN	7.57EN 7.63EN 7.63EN	7.48EN 7.54EN 7.54EN	7.42EN 7.50EN 7.50EN	22.0CN 22.8CN 22.5CN

SS450 DUAL PERIPHERAL POSITIVE-AND DRIVER (SWITCHING TIME-TTL GATE ONLY)
TEMPERATURE=25DEG C ; DATE=15 DEC 92

PIN#	TEST CONDITIONS	TEST PIN#	LO-LIMIT	SN1	SN2	SN3	SN4	SNS	HI-LIMIT	UNITS
T22.1	UCC=4.5V CL=52PF	ICL=16mA	1 2 13	0.000 0.000 0.000	14.20N 14.20N 12.40N	13.77N 13.93N 12.40N	13.45N 14.02N 12.15N	14.37N 14.72N 13.15N	13.20N 13.56N 11.95N	22.0CN 22.8CN 22.5CN
T22.2	UCC=4.5V CL=52PF	IOL=16mA	1 2 13	0.000 0.000 0.000	11.11EN 11.11EN 11.11EN	10.57N 10.57N 10.57N	10.45N 10.45N 10.45N	10.50N 10.56N 10.45N	10.25N 10.56N 10.25N	22.0CN 22.8CN 22.5CN

55450 DUAL PERTHERMAL POSITIVE-AND DRIVER (SWITCHING TIME-TRANSISTOR ONLY)
TEMPERATURE-25DEG C ; DATE-15 DEC 80 TIME-15:46:41

TEST CONDITIONS	TEST POINTS	TEST POINTS	LO-LIMIT	SN1	SN2	SN3	SN4	SNS	HI-LIMIT	UNITS
IB-220MA CL-50PFD	IC-220MA R1-50	1 2	0.003 0.002	8.320N 8.120N	8.320N 8.470N	8.420N 8.520N	9.110N 8.970N	8.522N 8.950N	15.00N 15.00	S
IP	IB-220MA CL-50PFD	1 2	0.003 0.003	8.750N 8.570N	8.670N 8.660N	8.700N 8.600N	9.150N 9.210N	8.814N 8.700N	20.00N 22.60N	S
TS	IB-220MA CL-50PFD	1 2	0.003 0.003	11.32N 11.92N	11.35N 11.35N	11.35N 11.27N	12.17N 12.01N	11.44N 11.25N	15.00N 15.20N	S
TF	IB-220MA CL-50PFD	1 2	0.003 0.003	9.910N 9.940N	8.910N 8.920N	8.920N 8.920N	9.820N 9.820N	8.750N 8.670N	15.20N 15.00N	S

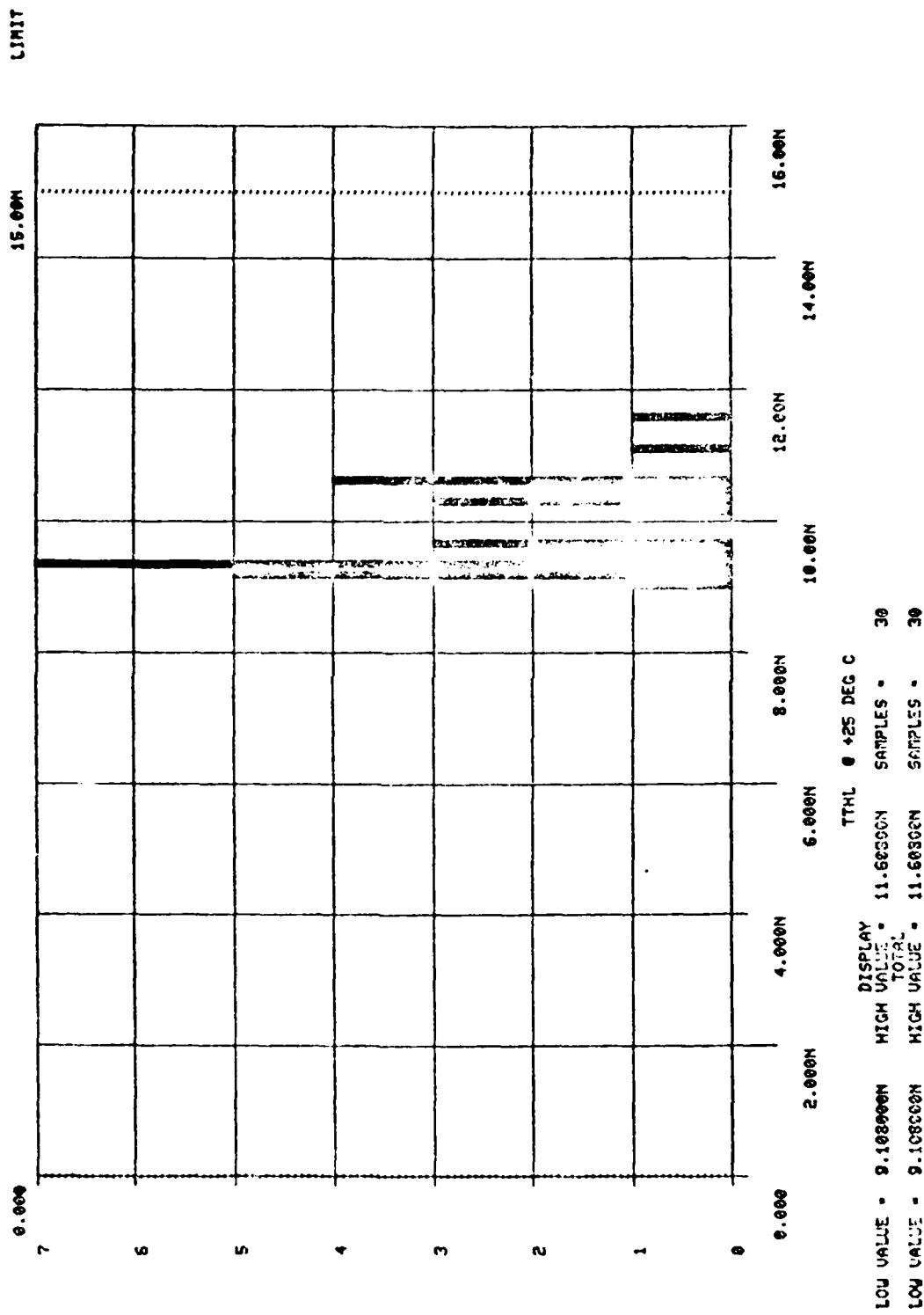
55450 DUAL PERTHERMAL POSITIVE-AND DRIVER (SWITCHING TIME-TRANSISTOR ONLY)
TEMPERATURE-25DEG C ; DATE-15 DEC 80 TIME-19:10:56

TEST CONDITIONS	TEST POINTS	TEST POINTS	LO-LIMIT	SNS	SN3	SN4	SNIC	HI-LIMIT	UNITS	
IB-220MA CL-50PFD	1 2	0.000 0.000	3.160N 3.160N	8.520N 8.220N	8.520N 8.530N	8.520N 8.470N	9.150N 8.470N	9.150N 8.530N	15.00N 15.00	S
IP	IB-220MA CL-50PFD	1 2	0.000 0.000	9.200N 9.200N	9.200N 8.420N	9.200N 8.870N	9.320N 8.740N	9.170N 9.110N	20.00N 20.00N	S
TS	IB-220MA CL-50PFD	1 2	0.000 0.000	11.37N 11.62N	11.37N 11.37N	11.37N 11.37N	11.44N 11.22N	11.14N 10.97N	15.00N 15.00	S
TF	IB-220MA CL-50PFD	1 2	0.000 0.000	10.54N 9.920N	9.410N 9.420N	9.410N 9.370N	9.310N 9.320N	10.00N 10.00N	15.00N 15.00	S

55459 DUAL PERIPHERAL POSITIVE-AND DRIVER (SWITCHING TIME-TRANSISTOR ONLY)
 TEMPERATURE=25DEG C ; DATE=15 DEC 82 TIME=19:30:47

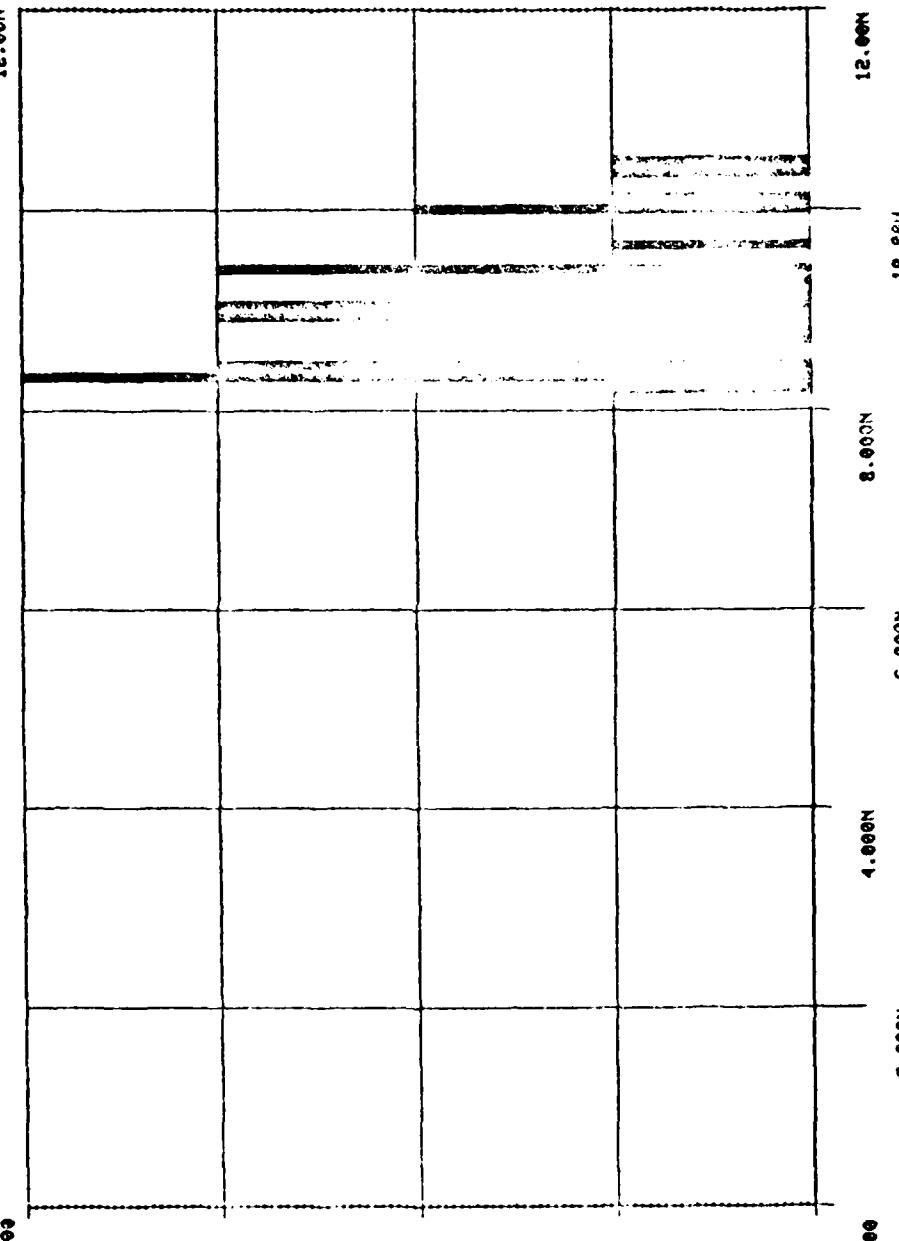
PARAMETER	TEST CONDITIONS	TEST PINS	LO-LIMIT	SN11	SN12	SN13	SN14	SN15	HI-LIMIT	UNITS
TJ	IB=20mA CL=50PF	IC=200mA R1=50	1 2	0.550 0.610	2.72N 2.61N	0.350N 0.35N	10.77N 10.75N	8.550N 8.42N	9.72N 9.65N	15.00N 15.00N
TR	IB=20mA CL=50PF	IC=200mA R1=50	1 2	0.550 0.550	5.15N 3.65N	10.41N 10.32N	10.13N 9.94N	9.21N 9.07N	10.78N 10.53N	20.00N 20.00N
TS	IB=20mA CL=50PF	IC=200mA R1=50	1 2	0.550 0.550	11.77N 11.67N	11.51N 11.47N	11.87N 11.75N	11.13N 11.10N	15.00N 15.00N	15.00N 15.00N
TF	IB=20mA CL=50PF	IC=200mA R1=50	1 2	0.550 0.600	10.37N 9.57N	9.72N 10.12N	10.15N 9.65N	10.54N 10.35N	10.54N 10.35N	15.00N 15.00N

VOLUME OF 5 FROM DE-450 LOGGED 08:19:59 17 DEC 82
TTL AT VCC-4.5V DEVICE TYPE 554529



LOW AT 0CC-4.SU S. FPCN D1450. LOCJD 0812E:58 17 DEC 96
HIGH AT 0CC-4.SU S. FPCN D1450. LOCJD 1000:58 17 DEC 96

0.000 4 3 2 1 0 10.000 12.000

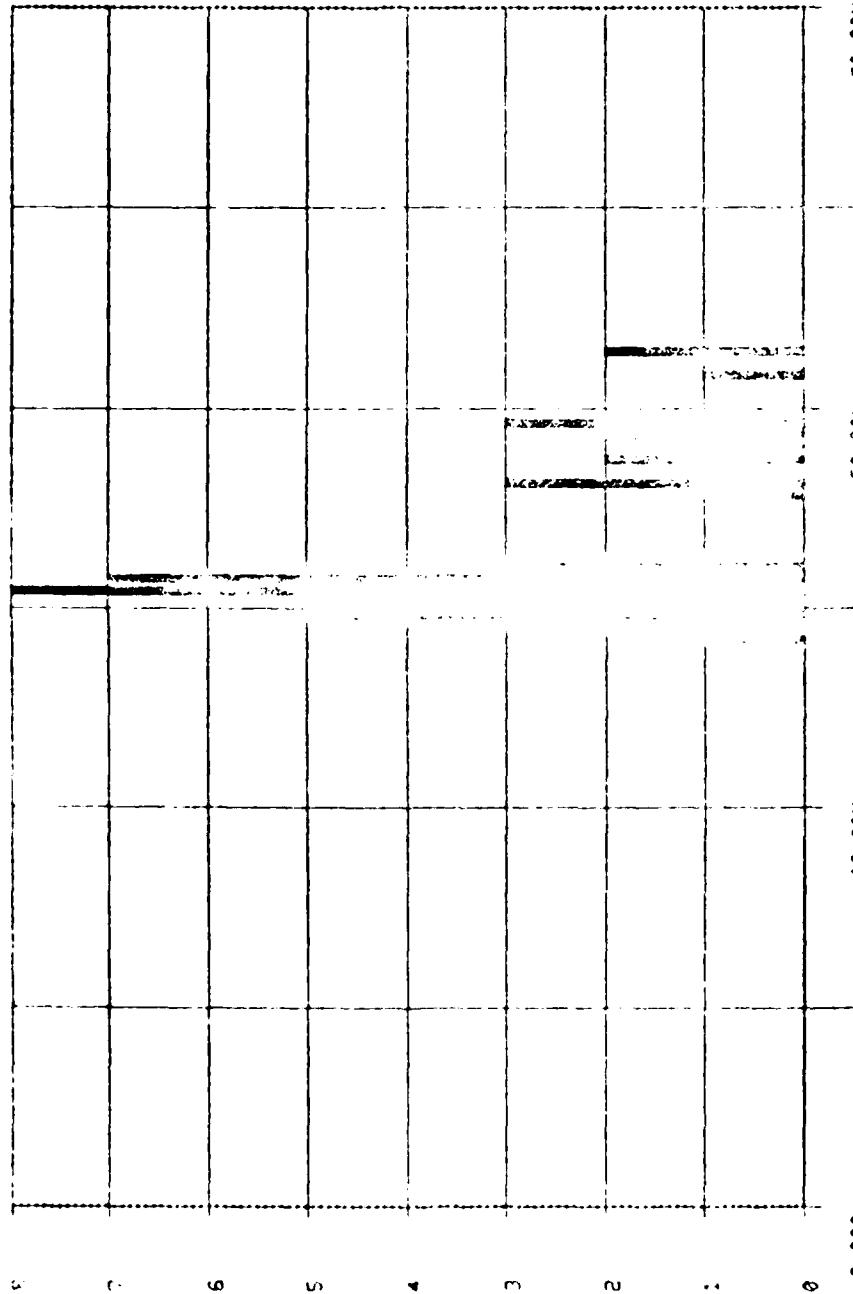


LOW VALUE = 8.26999M HIGH VALUE = 10.47000N SAMPLES = 30
LOW VALUE = 8.269729N HIGH VALUE = 10.47023N SAMPLES = 30

TTLH 0 +25 DEG C

LOGIC AT 100% SCAN MODE, LOC 100 13:34:00 11/22/82

0.000 5.000 10.000 15.000 20.000 25.000 30.000

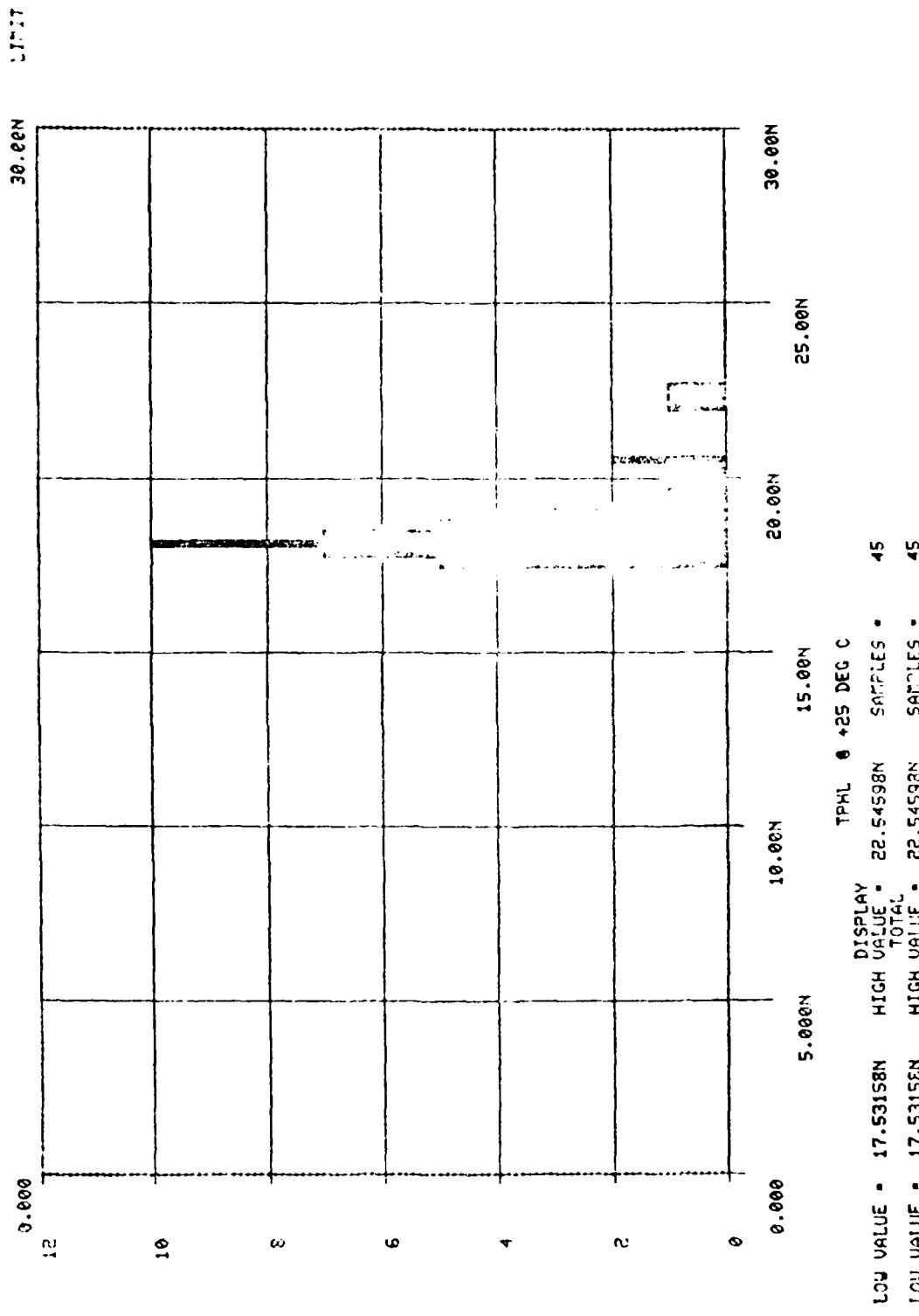


0.000 5.000 10.000 15.000 20.000 25.000 30.000

TPLH @ +25 DEG C

LOW VALUE •	14.36494N	HIGH VALUE •	21.41625N	SAMPLES •	45
HIGH VALUE •	16.36734N	LOW VALUE •	21.41625N	CYCLES •	45

LOCATE AT 5 FROM D5459 LOCATED 1313618 17 DEC 82
TPII AT UCC-4.5U

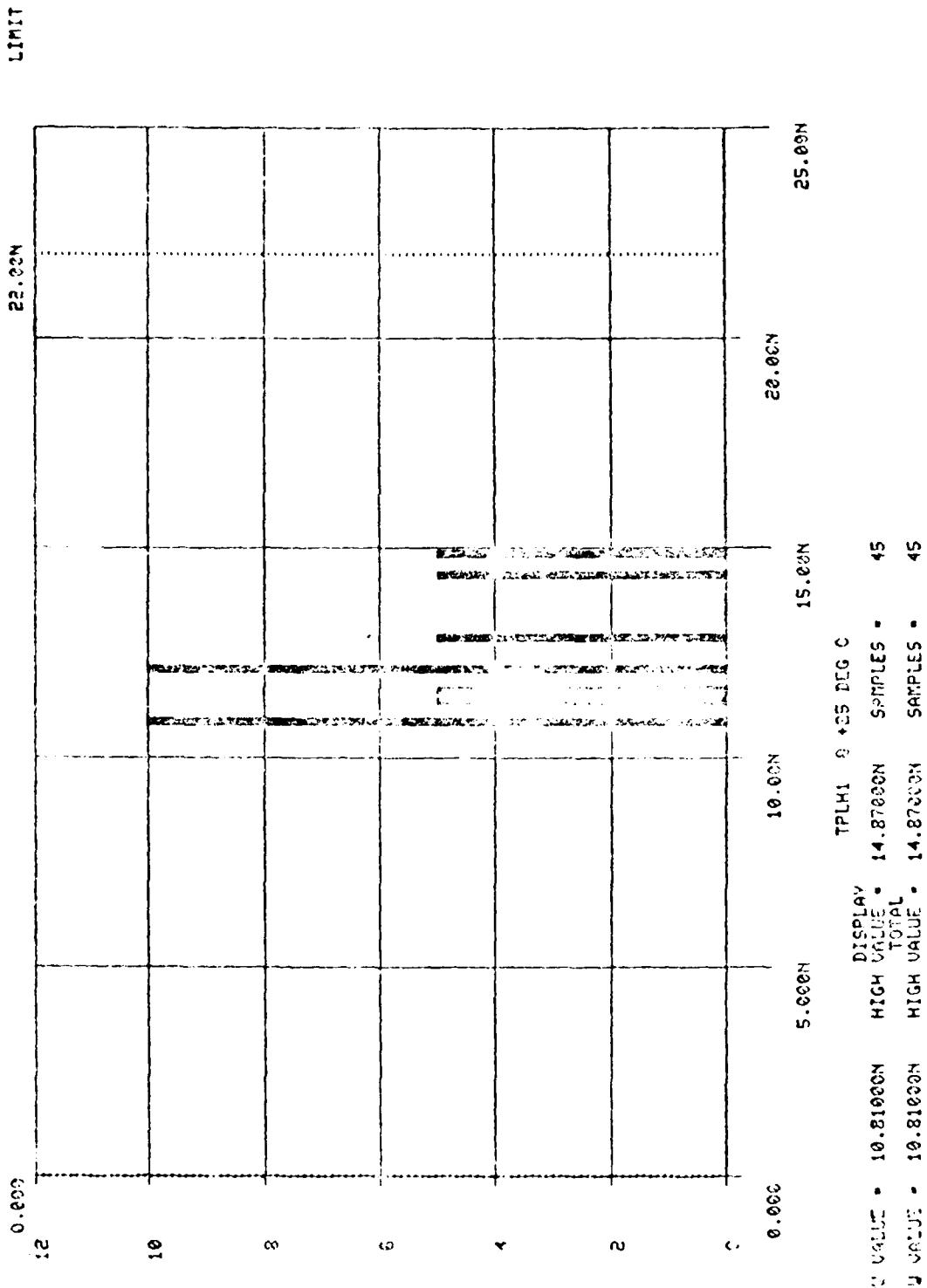


III-35

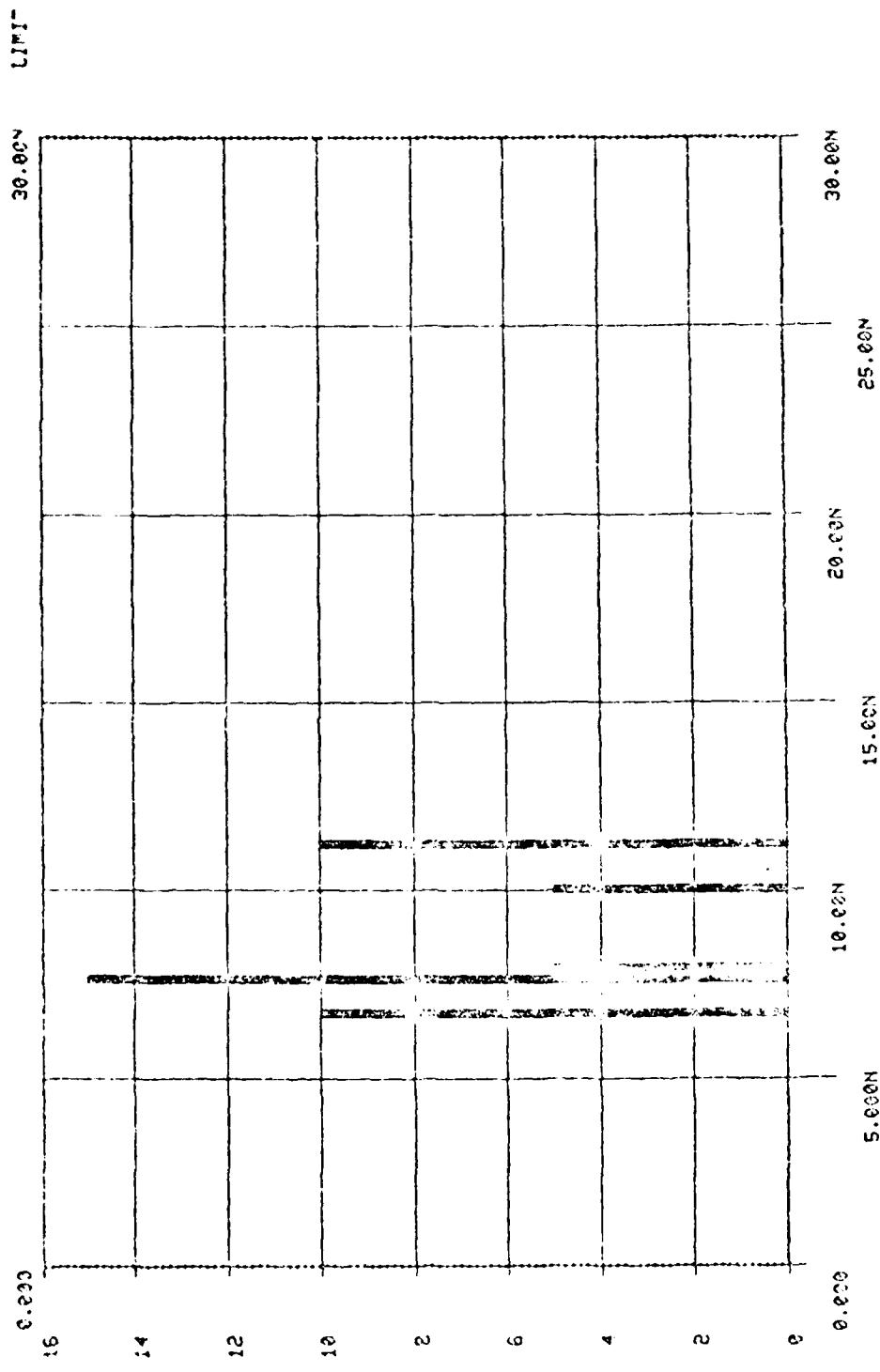
LOC VALUE = 17.53158N HIGH VALUE = 22.54598N SAMPLES = 45
LOC VALUE = 17.53158N HIGH VALUE = 22.54598N SAMPLES = 45

TPII @ +25 DEG C

TRPHI: 10.8100N HIGH DISPLAY • 14.8700N SAMPLES • 45
LCI: 10.8100N HIGH DISPLAY • 14.8700N SAMPLES • 45



DEPTH AT 1000.5 FEET DEPTH LOCATED
TRACE AT 1000.5 FT (TTL 5000 ONLY)
DEVICE TYPE SS450

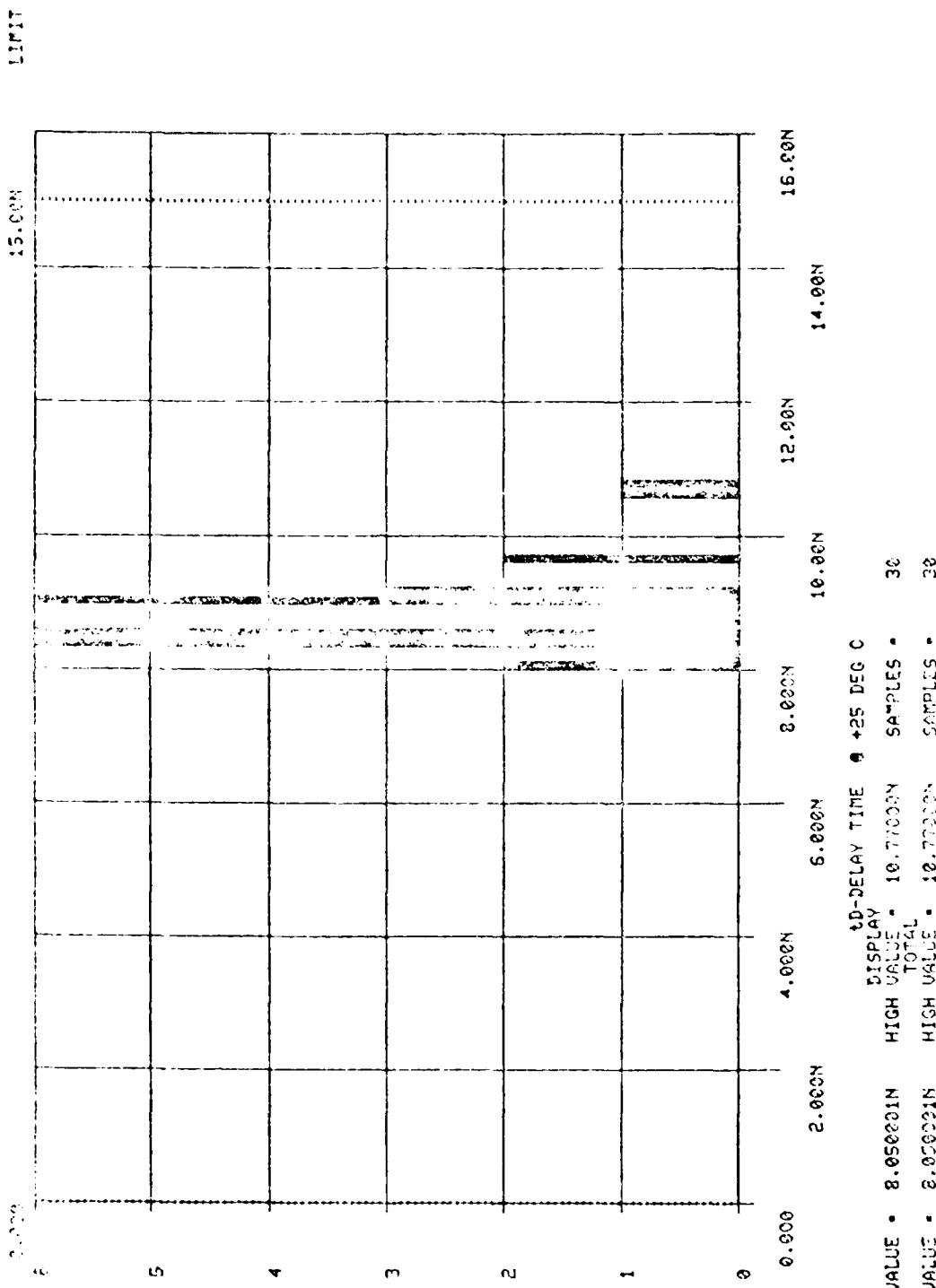


III-37

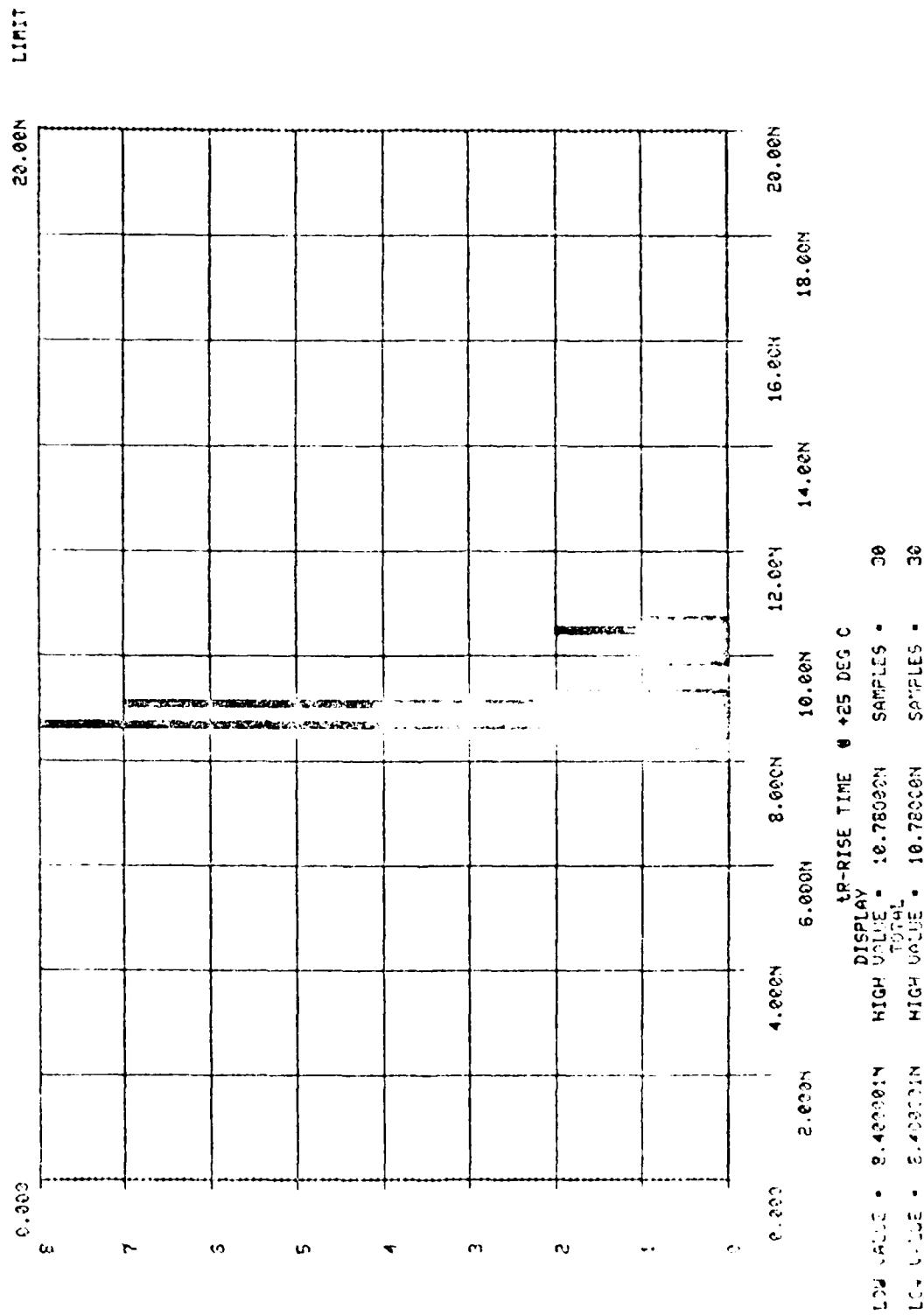
LOG VALUE • 6.62500IN HIGH VALUE • 11.30000IN SAMPLES • 45
LOG VALUE • 6.62500IN HIGH VALUE • 11.30000IN SAMPLES • 45

TPHIL2 0 425 DEG C

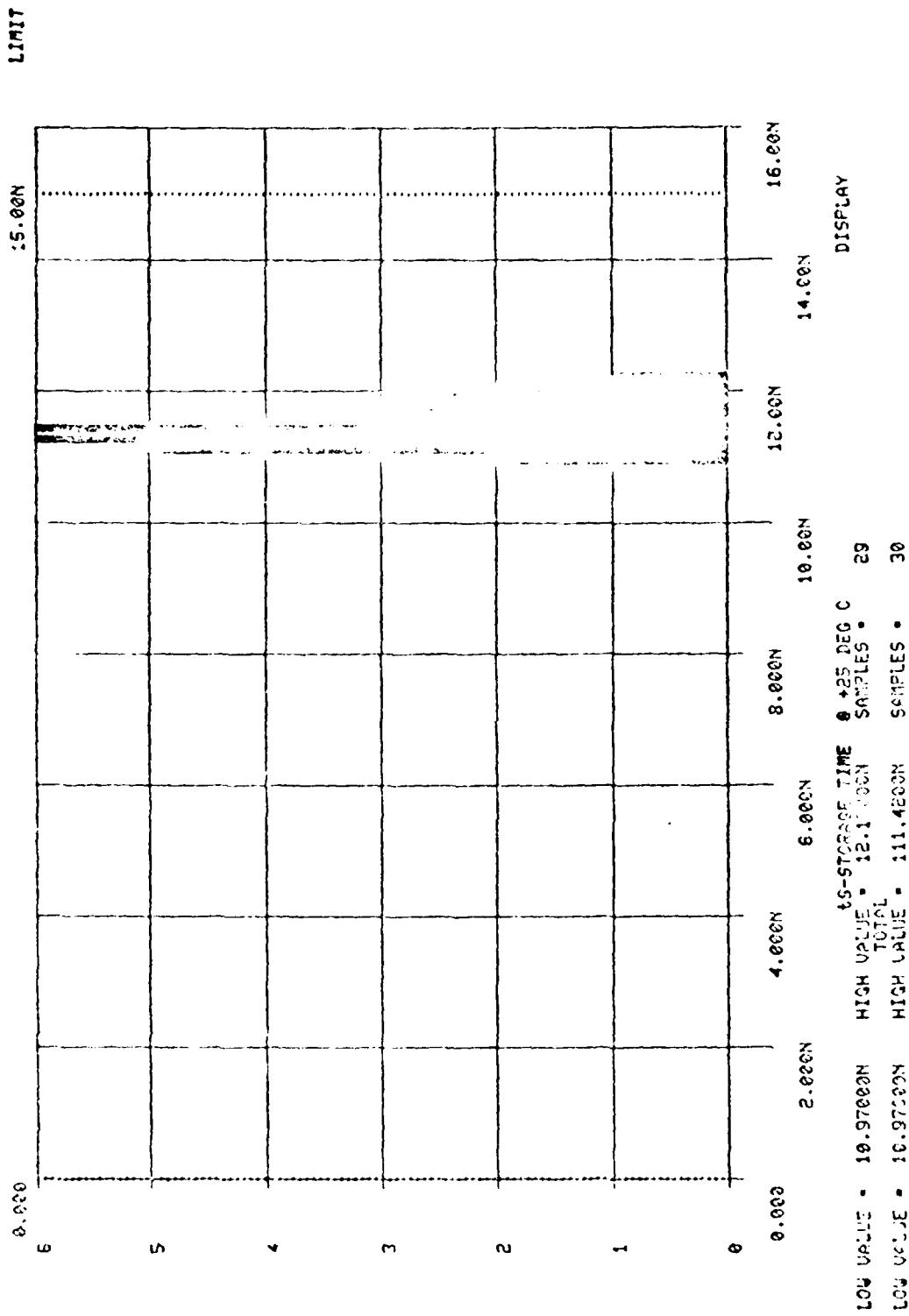
VALUE AT 5 FOCAL LENGTHS
ED-DESIGN DATE 11/20/2014
FOCUS SPAN 1.0-5.0
DEC 20 2014 15:24:27
DEVICE TYPE 554502



VALUE AT 5 FPM LOG:JED 15:39:27 17 DEC 80
TR-RISE TIME AT 18.00A,IC-DIGMA

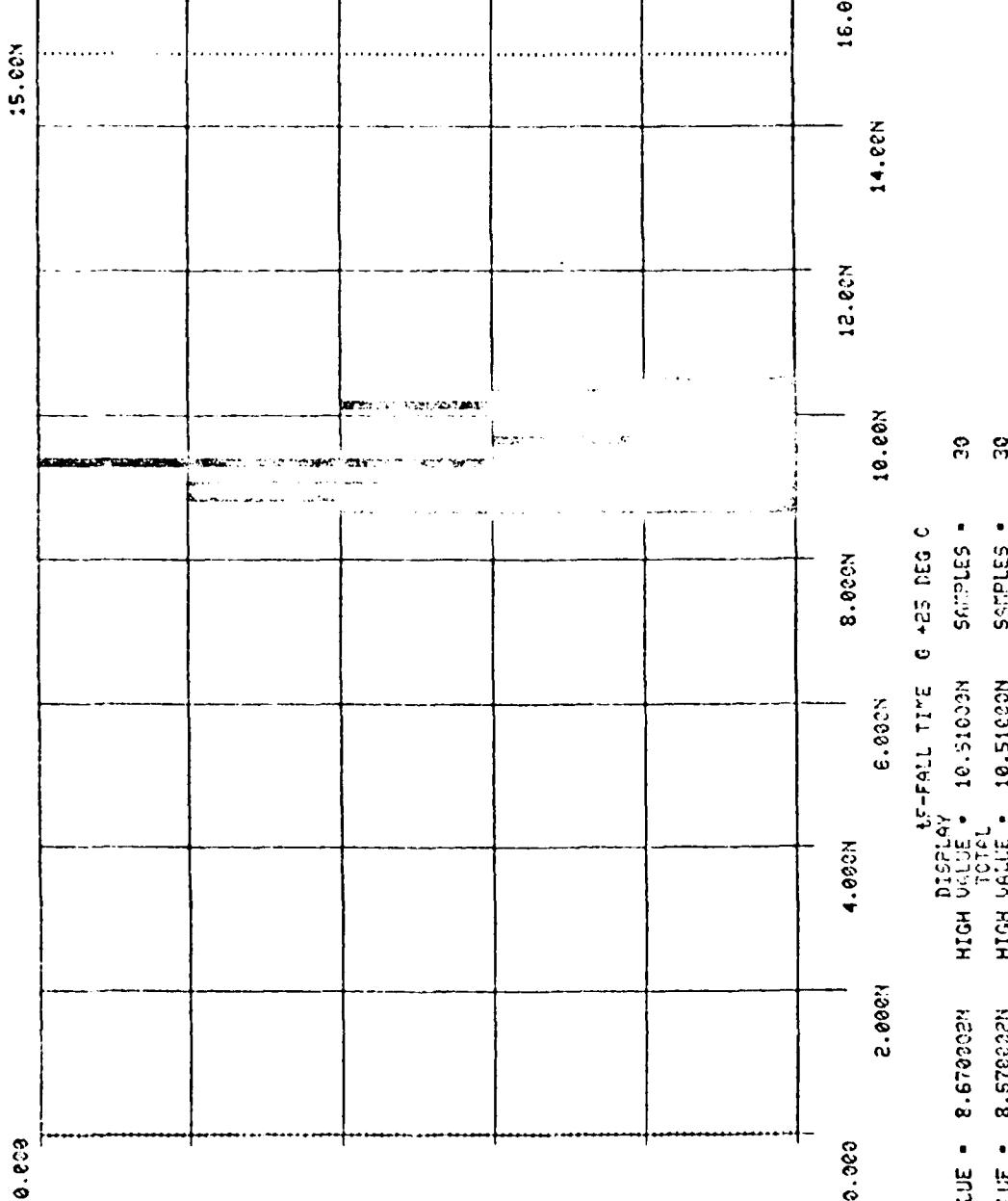


15:44:46 17-03-03 83 554508
15:44:46 17-03-03 83 554508



LOGGED AT 5:11:34 17 DEC 80
FROM DC45C LOG:JED
AT 15:51:34 17 DEC 80
DEVICE TYPE 554-2B

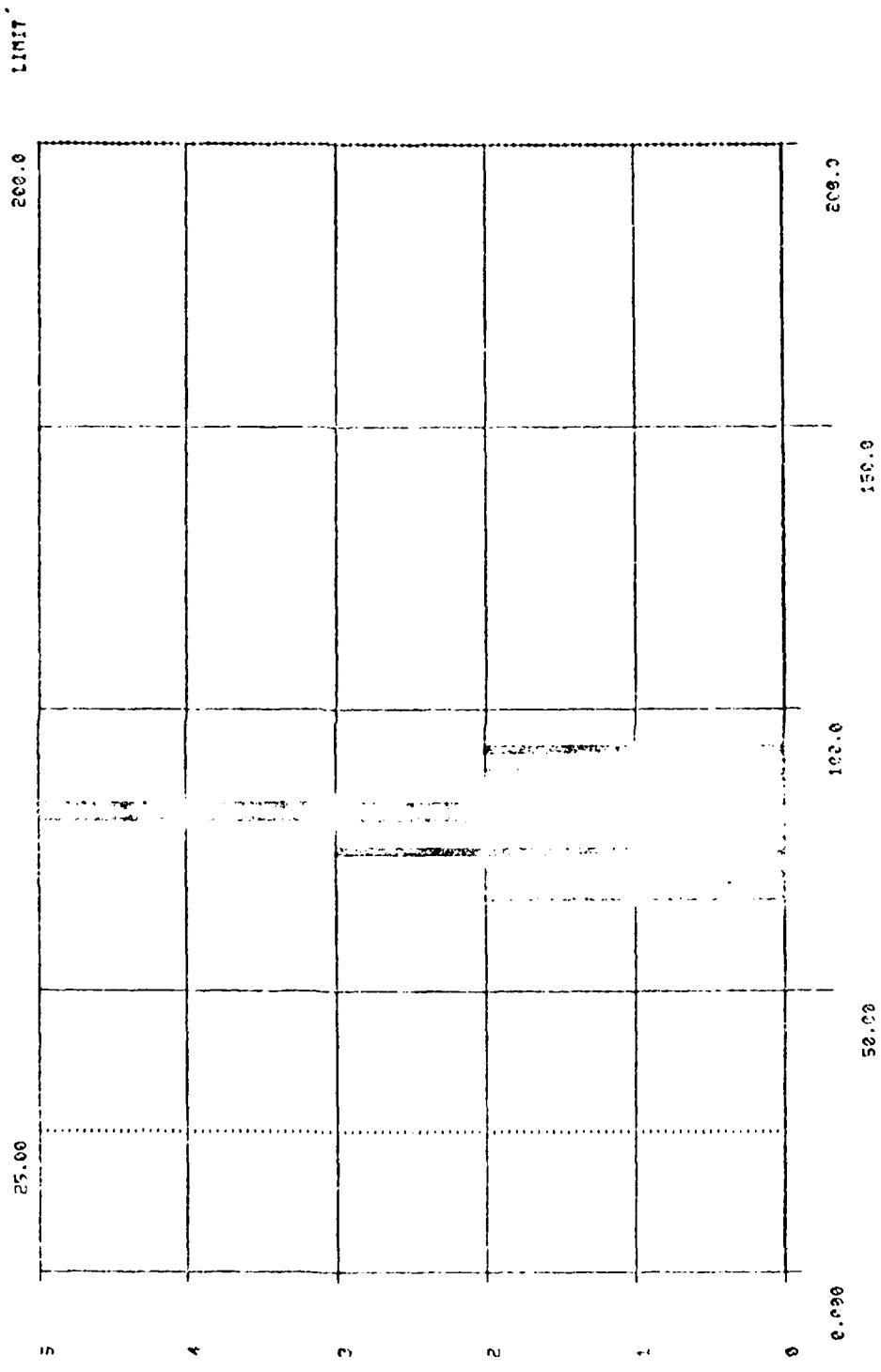
LIMIT



III-41

LOW VALUE = 8.670002N HIGH VALUE = 10.51000N SAMPLES = 39
LOW VALUE = 8.570002N HIGH VALUE = 10.51000N SAMPLES = 30

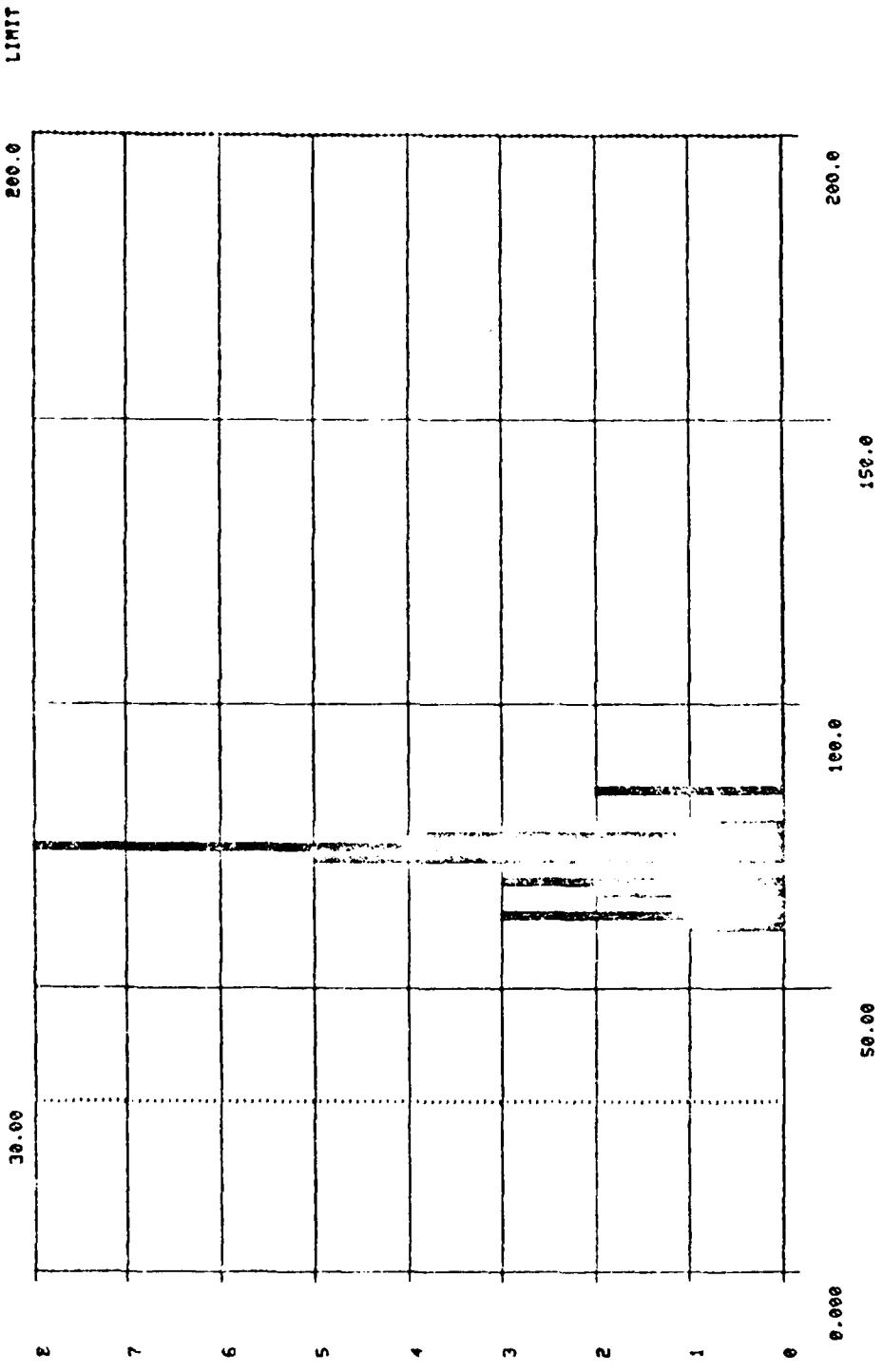
VALUE AT V_{CO}=3° FF01N DR4501 LOG:3ED 09:20:16 17 DEC 82
NFE1 AT V_{CO}=3°, I=+30° A DEU:02 -VFE 554508



NFE1 3 + 25 DEG C

LOW VALUE =	67.45330	HIGH DISPLAY =	23.43000	SAMPLES =	30
LOW VALUE =	67.45330	HIGH DISPLAY =	23.43000	SAMPLES =	36

VALUE AT 1.50-3V, IC=30mA FPCN DP4502.LCC:JED 09:27:56 17 DEC 82
HFE2 AT 1.50-3V, IC=30mA DEVICE -YPE 554500



LOW VALUE •	61.89000	HIGH VALUE •	61.89000	LOW VALUE •	61.89000	HIGH VALUE •	61.89000
		HIGH DISPLAY •	85.19000			HIGH TOTAL •	85.12000
		SAMPLES •	30			SAMPLES •	30

100 940116 - 742.223031 HIGH 0626. - 83.9335
 100 240116 - 742.290031 HIGH 0626. - 83.9335
 100 01520116 - 742.290031 HIGH 0626. - 83.9335

	1.000	500.00	300.00	200.00	100.00	50.00	25.00	12.50	6.25	3.12	1.56	0.78
0	1.000	160.34	267.87	323.00	403.94	500.00	560.00	626.67	690.00	750.00	800.00	850.00

UNIT

1.000

010016 01 12-16-1981, F00142883, D001325
 010016 01 12-16-1981, F00142883, D001325
 010016 01 12-16-1981, F00142883, D001325

0.000

4

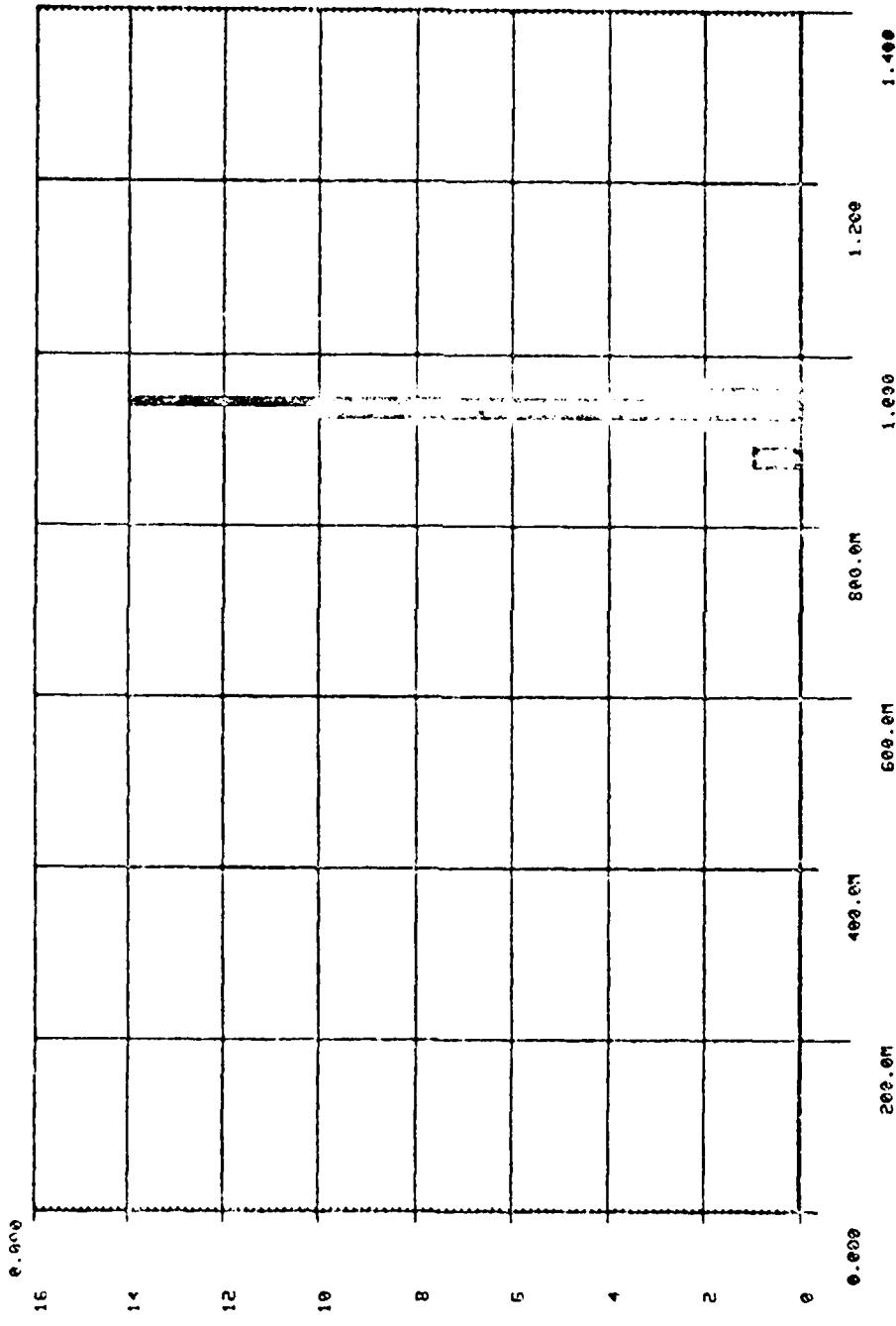
8

12

16

VALUE AT 5 FPM, LOGGED 141115Z 15 DEC 72
REC AT 10.0000, LOGGED 141115Z 15 DEC 72
DEVICE TYPE SS4513

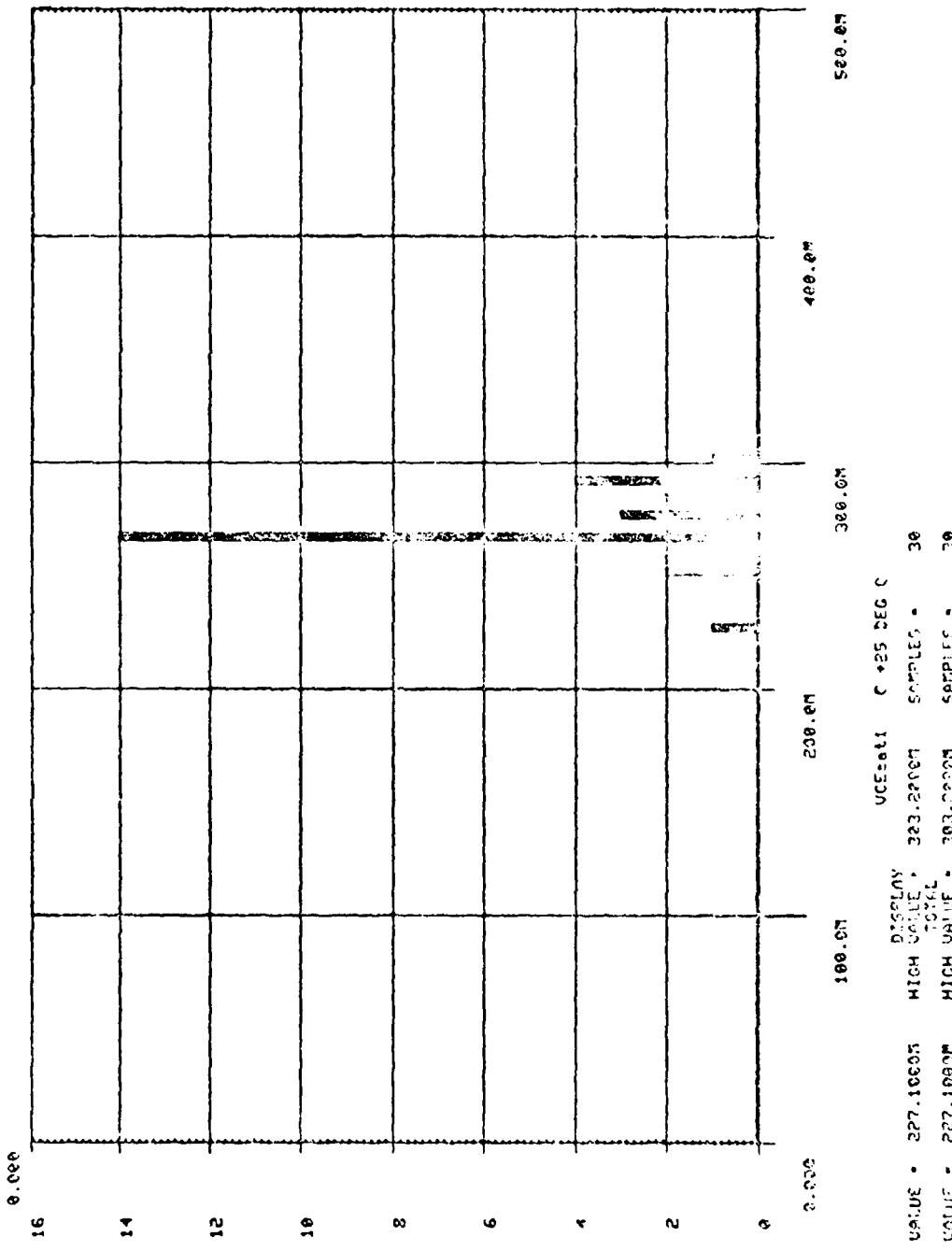
LIMIT



DISPLAY 0 +25 DEG C
HIGH VALUE = 957.5000⁰ SAMPLES = 30
TOTAL = 957.5000⁰
LOW VALUE = 859.1000⁰ HIGH VALUE = 957.5000⁰ SAMPLES = 30
 LOW VALUE = 853.1000⁰

VALUE AT S_1 FROM D₄₅₀ LOGGED 13:56:26 19 DEC 80
VCEsat AT Ib=10mA, Ic=10mA

LIMIT



III-46

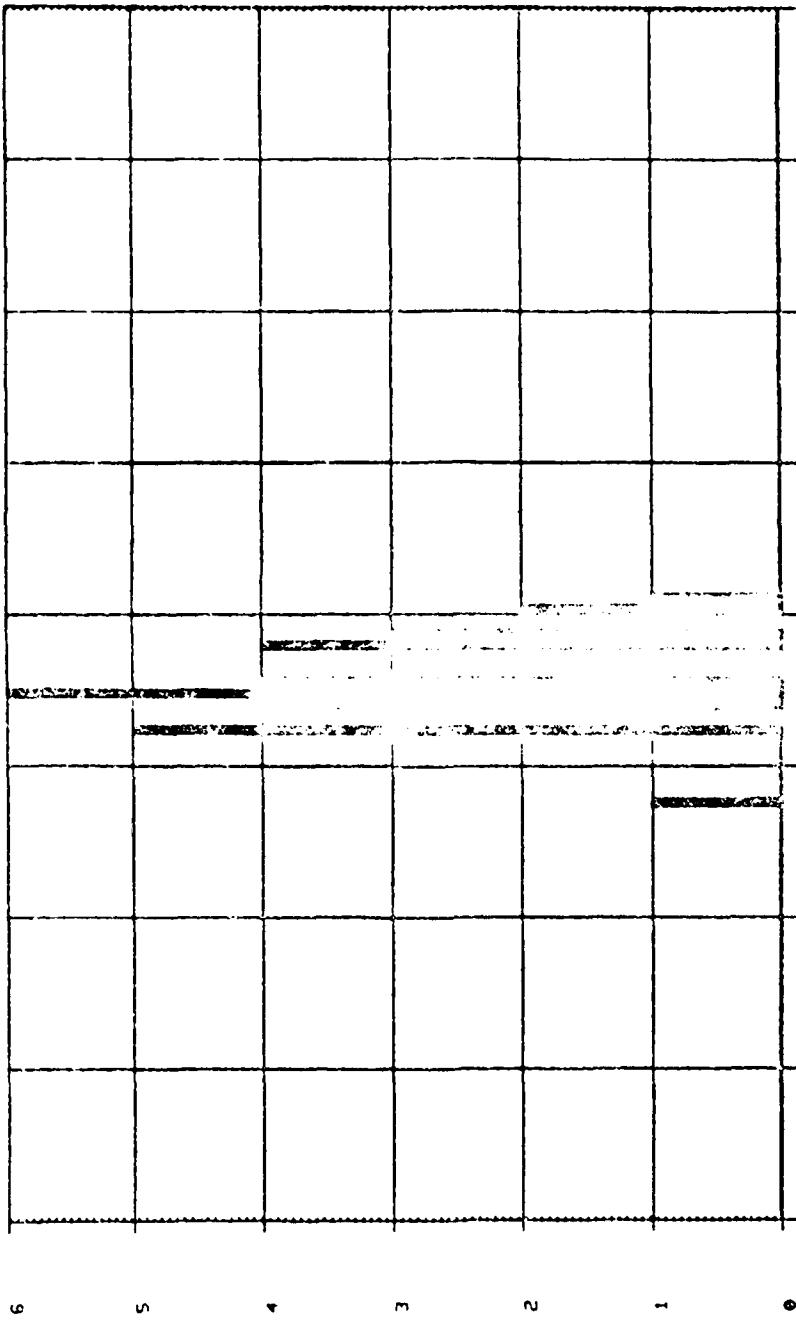
LOG VALUE = 227.10005 HIGH VALUE = 223.22005 SAMPLES = 30
LOW VALUE = 227.10000 HIGH VALUE = 203.00000 SAMPLES = 20

DATA AT 5 FROM D1450 LOCATED AT 1b-30m, 1c-32m
DEVICE TYPE 55452B

LIMIT

800.0m

0.000



LOW VALUE = 275.900m HIGH DISPLAY UCFA#12 @ 425 DEG C
HIGH VALUE = 415.526m SAMPLES = 30
TOTAL = 415.526m SAMPLES = 30
!CU VALUE = 275.900m HIGH VALUE = 415.500m SAMPLES = 30

VALUE AT 5 FROM D6450 LOGGED 14:40:08 17 DEC 80
UCB01 AT IC-1030A DEVICE TYPE 5550B

LIMIT

102.0

35.00

3

2

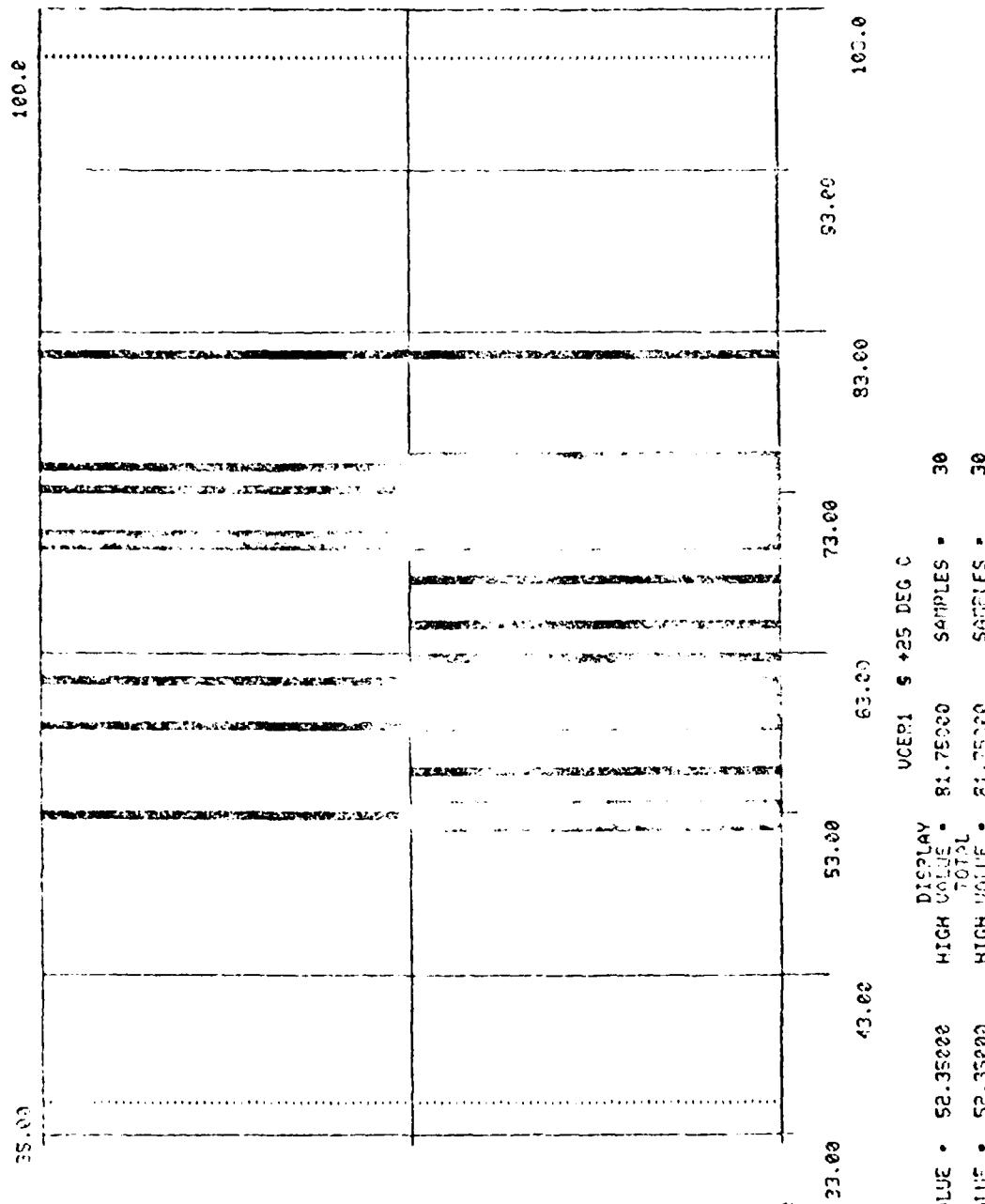
0

103.0
93.00
83.00
73.00
63.00
53.00
43.00
33.00

UCB01 @ +25 DEG C
LOW VALUE = 52.85000 HIGH DISPLAY VALUE = 31.95000 SAMPLES = 30
LOW VALUE = 52.85000 HIGH TOTAL VALUE = 31.95000 SAMPLES = 30

VALUE AT $I_c = 5$ FPM D7450 LOG:JED 14:48:55 17 DEC 80
V_{CE(s)} AT $I_c = 100\mu A$, R_{be}=500 ohms DEVICE TYPE 5545G2

LIMIT

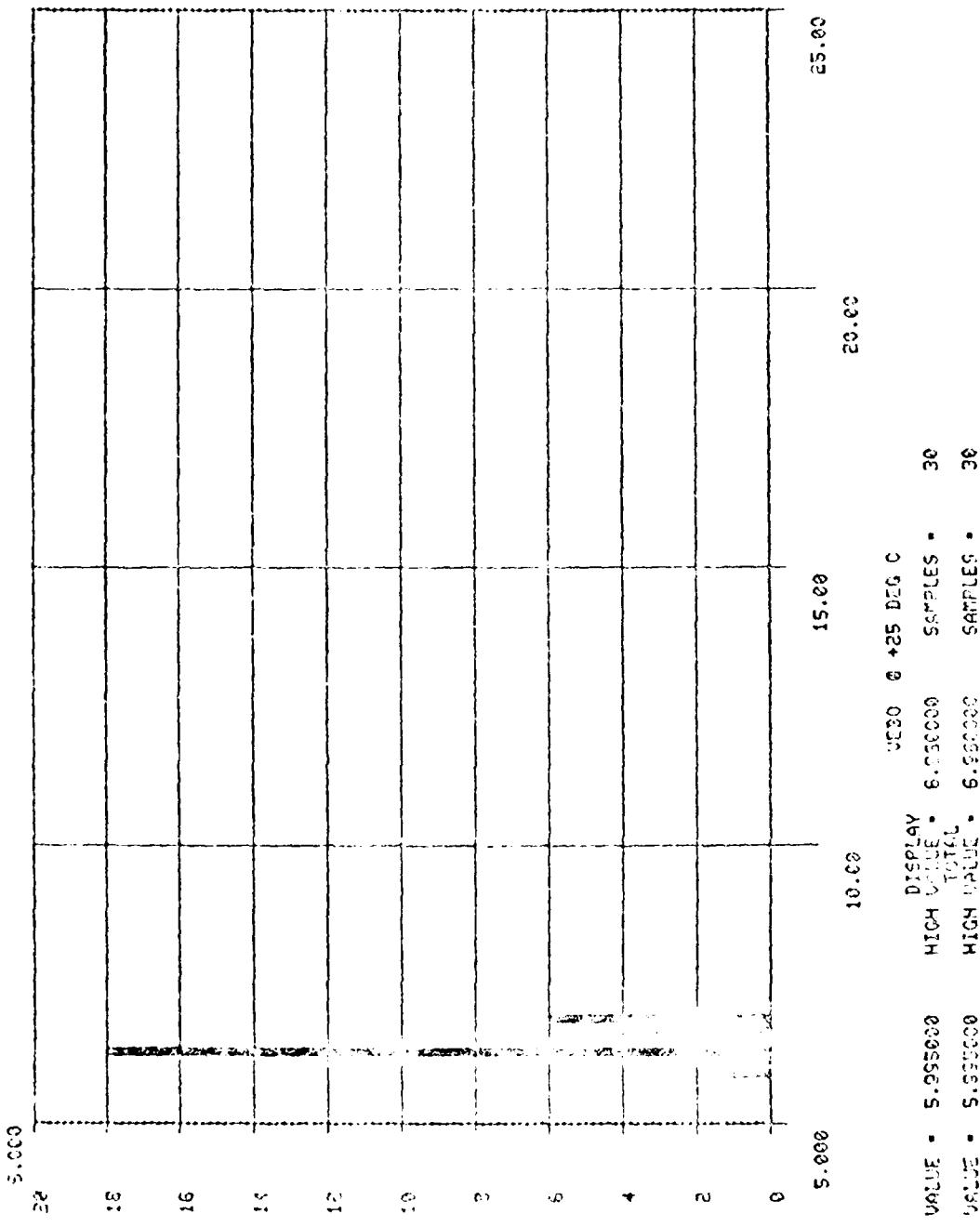


III-49

UICER1 \$ 425 DEG C
DISPLAY
HIGH VALUE • 81.75000 SAMPLES • 30
TOTAL • 81.75000 SAMPLES • 30
LOW VALUE • 52.35000 HIGH VALUE • 81.75000

VOICE AT 5:00PM DEC 24, 1945. LOG: JET ENGINE 14:50:47 : 7 DEC 26

卷之三



SECTION IV

MEMORY CORE DRIVERS

TABLE OF CONTENTS

4.1	Introduction	IV-1
4.2	Description of Device Types	IV-1
4.3	Test Development	IV-4
4.4	Test Results and Data	IV-4
4.5	Slash Sheet Development	IV-14
4.6	Conclusions and Recommendations	IV-14

SECTION IV

MEMORY CORE DRIVERS MIL-M-38510/130

4.1 Introduction

The 55325/326/327 family of memory core drivers is the first line of core drivers to be characterized for RADC. Based on high previous utilization of these devices in military systems, both Texas Instruments and Fairchild Semiconductor recommended characterization of these devices. It is expected, however, that usage in new military systems will be on a decline. Table 4-1 gives some specifics on the devices tested and their relationship to the military slash sheet device types.

Table 4-1 Table of Device Types Specified

Device Type	Generic Type	Manufacturer Symbol	Output Configuration
130-01	55325	F, T	Dual source and dual sink
130-02	55326	F, T	Quad sink
130-03	55327	F, T	Quad source

F = Fairchild Semiconductor (discontinued mid-1980)

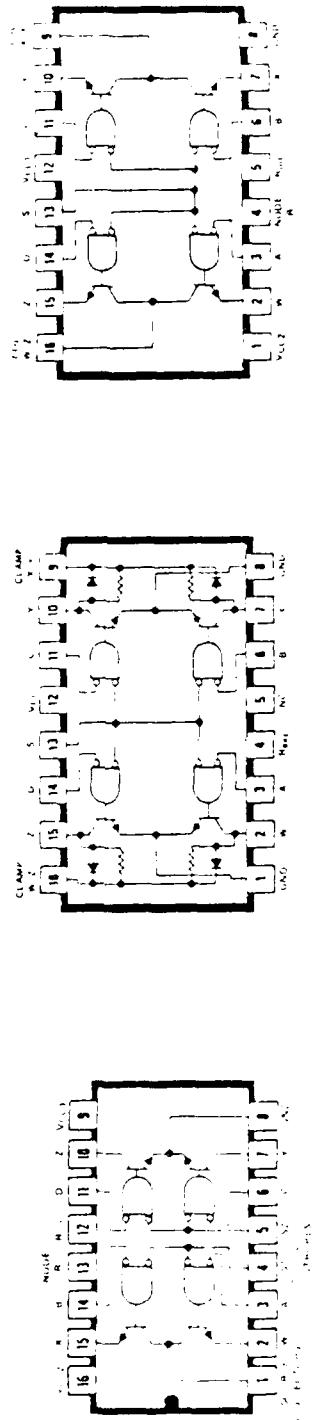
T = Texas Instruments

The manufacturer symbol column reflects the source of the devices which were to be characterized. Other vendors produce the 55325 but were not included in the characterization effort since they did not express interest in the devices. Fairchild memory core drivers were characterized. These devices were discontinued by Fairchild after characterization. Texas Instruments components were received too late to be characterized.

4.2 Description of Device Types

The 55325/326/327 family of devices provide 600 mA of source or sink capability for memory core driver applications. Block diagrams of the various devices are given in Figure 4-1, and detailed schematics are given in Figure 4-2. The input circuit of the core drivers is identical to that used in a standard TTL gate. However, the totem pole driver and the output stage are designed differently in order to deliver higher output currents, to provide level translation from standard TTL levels to higher output voltages, and to provide a method of controlling maximum output current.

Figure 4-1 Block Diagrams, Memory Core Drivers



Device Type 03

Device Type 02

Device Type 01

Figure 4-2 Schematic Circuits, Memory Core Drivers

The primary difference between the 55325, 55326 and the 55327 memory core drivers is their output arrangement. The 55325 provides two source and two sink outputs. The 55326 furnishes 4 sink outputs and the 55327 has 4 "source outputs".

4.3 Test Development

The test development for memory core drivers was similar to the bench test development for peripheral drivers (see Section 3.3). V_{IH} , V_{IL} , V_{IK} , I_I , I_{IH} , I_{IL} , I_{CC} (off), I_{CC1} and I_{CC2} are tested in much the same way as they are for standard TTL gates.

All other test parameters require special consideration, however, since they involve pulse measurement techniques or high speed switching of the devices under test.

A simplified schematic for the static test circuit is included in Figure 4-3. (The actual test box developed contained all of its own loads, drive signals and power supplies.

Schematics of the switching time test circuits are included in figures 4-4, 4-5, 4-6 and 4-7. Automatic tests were not implemented for characterization of this device family.

4.4 Test Results and Data

A total of 24 memory core drivers were bench tested at $T_A = 25^\circ\text{C}$. Sample test data of devices parameters is included in Table 4-2. Testing the 55325 family of devices is straightforward, requiring simple load circuits and TTL type test conditions. Testing is complicated, however, by the large combination of input and output configurations required by the device under test.

Tests that require unusual techniques are described below:

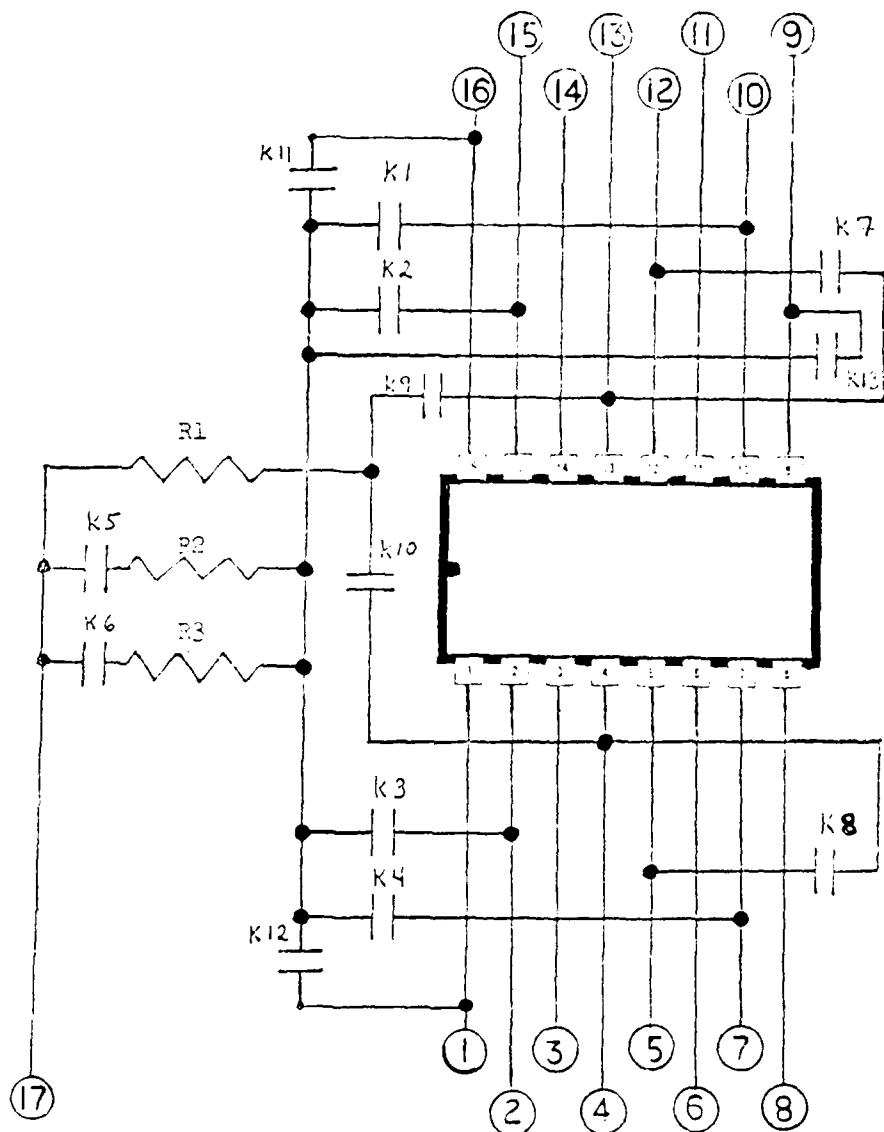
Saturation "Voltage", $V_{(SAT)}$

$V_{(SAT)}$ is measured using pulse techniques. The manufacturers data sheet specifies that $t_w = 200 \mu\text{s}$ with a duty cycle of $\leq 2\%$. The devices were measured over a range of repetition rates and duty cycles. The measured $V_{CE(SAT)}$ was relatively insensitive to changes in both test conditions. (Refer to figure 4-8.)

This parameter must be measured at the DUT pins to minimize measurement error.

Parameter	Test conditions	test pin									
		5:1	5:2	5:3	5:4	5:5	5:6	5:7	5:8	5:9	5:10
V _{DD} 1=4.5V, V _{CC1} =2.4V	4	1.3	1.4	1.4	1.3	1.4	1.3	1.4	1.4	1.4	1.3
	3,14	1.4	1.3	1.3	1.4	1.4	1.3	1.4	1.4	1.4	1.3
	5	1.36	1.36	1.34	1.35	1.32	1.29	1.35	1.35	1.36	1.36
	9	1.36	1.39	1.34	1.35	1.34	1.30	1.33	1.35	1.35	1.35
	6	1.34	1.33	1.34	1.32	1.36	1.27	1.34	1.34	1.33	1.35
	11	1.37	1.34	1.35	1.36	1.37	1.37	1.36	1.37	1.34	1.35
V _{CC1} =4.5V, V _{CC2} =2.4V	1	2	9	3.1	3.2	3.1	3.0	3.2	3.1	3.4	3.2
	7	23.1	23.2	23.1	23.1	23.1	23.2	23.2	23.1	23.1	23.1
	10	23.1	23.2	23.2	23.1	23.2	23.3	23.2	23.1	23.1	23.2
V _{CC1} =5.5V, V _{CC2} =2.4V	3	0.85	0.75	0.75	0.77	0.64	0.77	0.78	0.80	0.72	0.83
	14	0.86	0.76	0.77	0.77	0.64	0.78	0.80	0.81	0.74	0.85
	9	0.90	0.76	0.77	0.76	0.79	0.62	0.79	0.81	0.82	0.75
	11	0.93	0.83	0.84	0.84	0.85	0.65	0.84	0.86	0.89	0.81
	4	1.72	1.51	1.52	1.52	1.27	1.55	1.58	1.62	1.47	1.68
	5	1.71	1.51	1.52	1.54	1.29	1.54	1.59	1.62	1.47	1.68

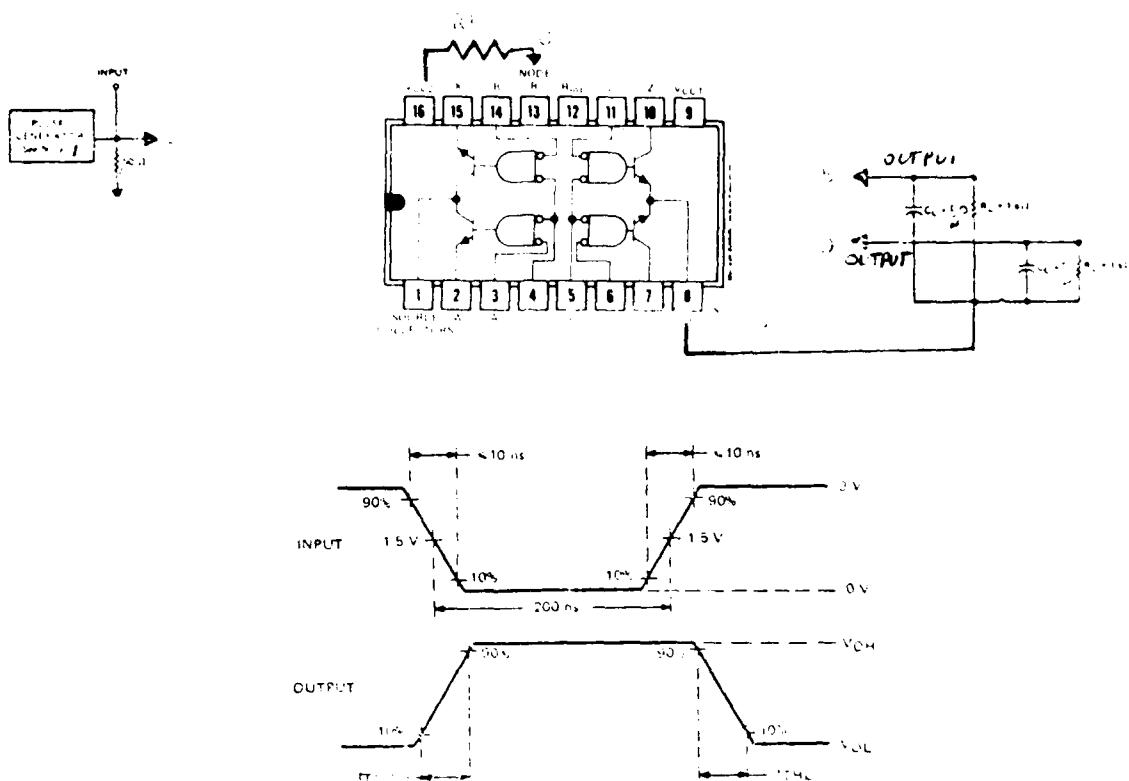
TABLE 4-2. Sample Test Data, 55325.



Notes:

1. All relays are in the de-energized position.
2. $R_1 = 300 \text{ ohms} \pm 5\%$ carbon.
3. $R_2 = 39 \text{ ohms} \pm 5\%$ carbon.
4. $R_3 = 22 \text{ ohms} \pm 5\%$ carbon.

Figure 4-3 Simplified Static Test Circuit Diagram for
Memory Core Drivers

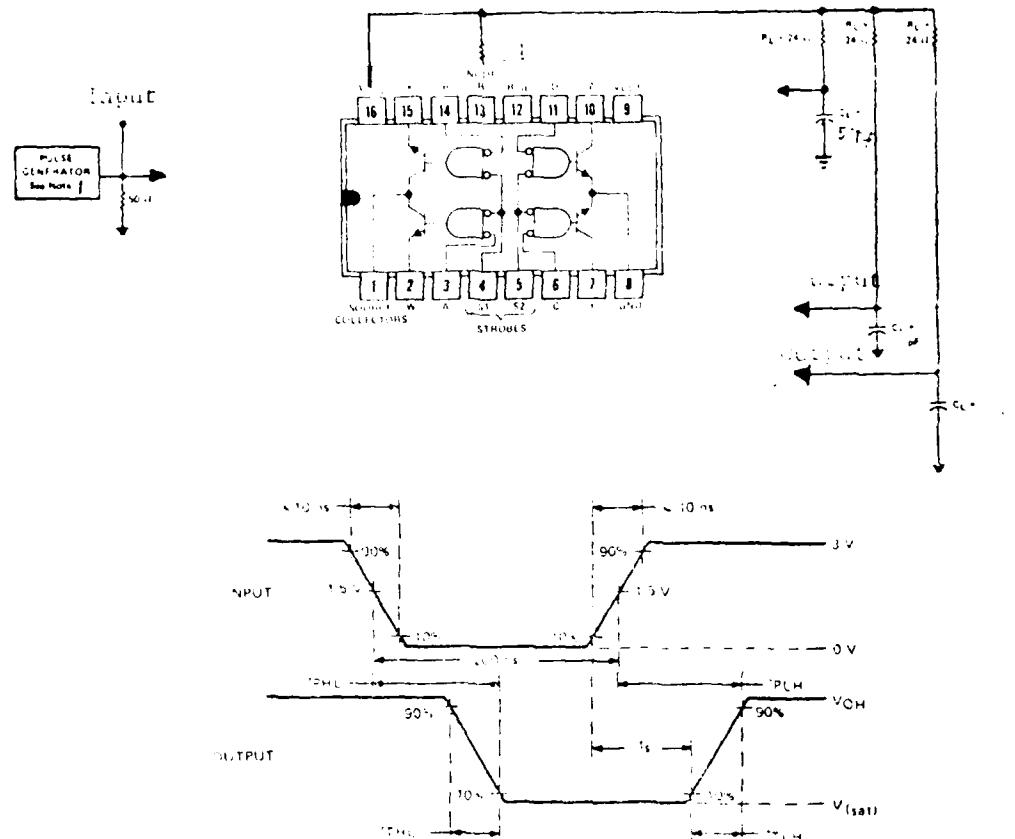


Notes: 1. The pulse generator has the following characteristics:

$$PRR = 0.2\mu s, t_p = 200\text{ns}, Z_{out} \approx 50 \Omega .$$

2. $R_L = 1\text{Kohm} \pm 5\%$ carbon.
3. $C_L = 50\text{pF} \pm 5\%$, including probe and jig capacitance.
4. $R_1 = 30\Omega$ ohms $\pm 5\%$ carbon.

Figure 4-4 Switching Time Test Circuit for Device Type 01

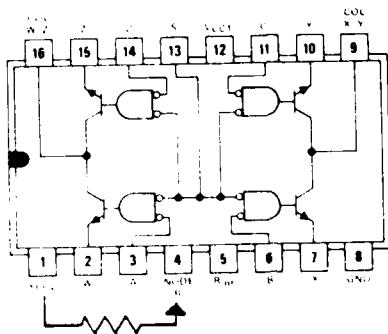
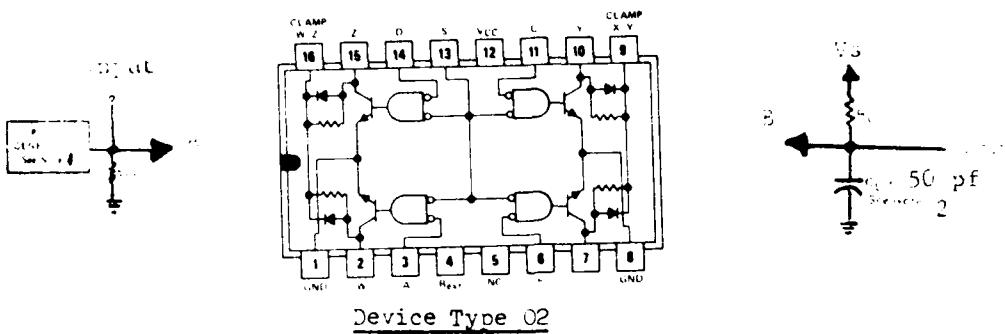


Notes: 1. The pulse generator has the following characteristics:

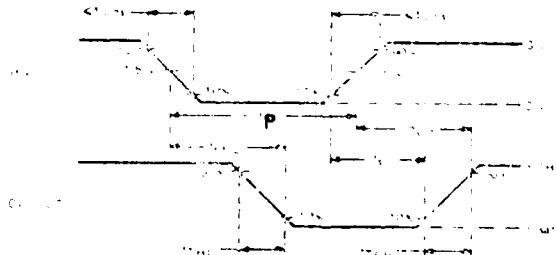
$$\text{PRR} = 1.2\mu\text{s}, t_p = 200\text{ns}, Z_{out} = 50\Omega$$

2. $R_L = 24\Omega \pm 5\%$ carbon.
3. $C_L = 50\text{pF} \pm 5\%$, including probe and jig capacitance.
4. $R_1 = 1\text{ M}\Omega \pm 5\%$ carbon.

Figure 4-9. Switching Time Test Circuit for Device Type 01



Device Type 03

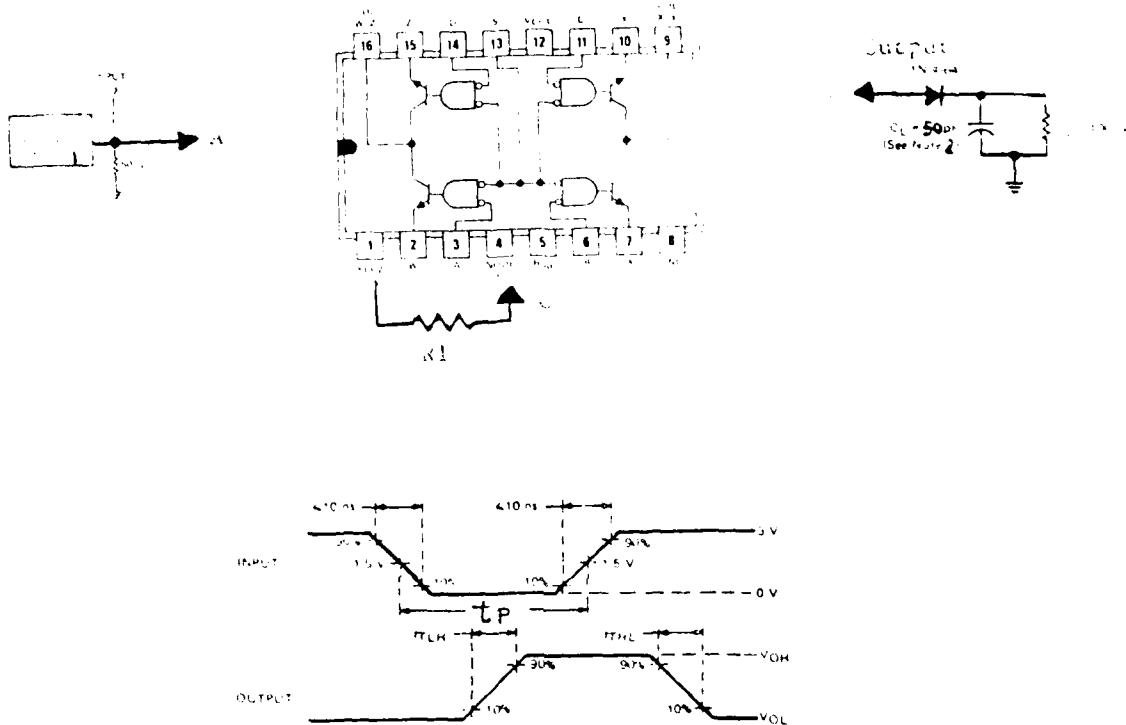


Notes: 1. The pulse generator shall have the following characteristics:

$Z_{out} \approx 50 \text{ ohms}$ - For testing V_{OH} (after switching)
 $\text{PRR} = 12.5 \text{ kHz}$, $t_p = 40 \mu\text{s}$ - For all other tests.
 $\text{PRR} = 0.2 \mu\text{s}$, $t_p = 200 \text{nS}$.

2. $C_L = 50 \text{ pF} + 5\%$ (including jig and probe capacitances).
3. $R_L = 4.1 \text{ ohms} \pm 5\%$ carbon for V_{OH} tests. For all other tests
 $R_L = 22 \text{ ohms} \pm 5\%$ carbon.
4. Connect W_1 to $V(Clamp)$ for device type '2'. For device type '3',
connect W_3 to $V(Clamp)$.
5. $R_1 = 3\text{-}5 \text{ ohms} \pm 5\%$ (device type '3' only).

Figure 4-6 Switching Time Test Circuit for Device Types 02 and 03



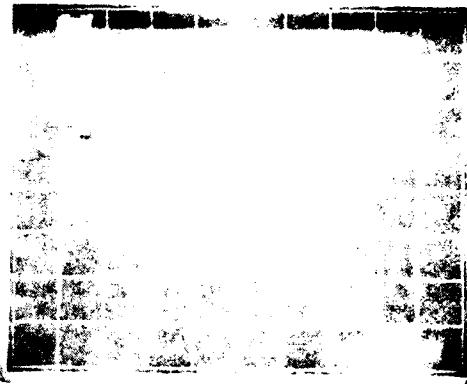
Notes: 1. The pulse generator shall have the following characteristics:

$$Z_{out} \approx 50 \text{ ohms}, PRR = 0.2\text{ns}, t_p = 200\text{ns}$$

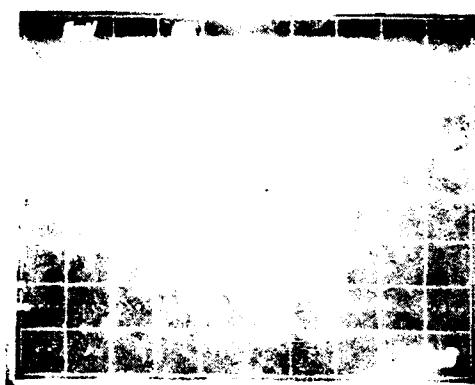
2. $C_L = 5\text{pF} \pm 5\%$ (including jig and probe capacitances).
3. $R_L = 100 \text{ ohms} \pm 5\%$ carbon.
4. $R_1 = 300 \text{ ohms} \pm 5\%$ carbon.

Figure 4-7 Switching Time Test Circuit for Device Type 03

$V_{(SAT)}$ = .38
Rep Rate = 10
Duty Cycle = 2%



$V_{(SAT)}$ = .389
Rep Rate = 10 m
Duty Cycle = 10%



$V_{(SAT)}$ = .38
Rep Rate = 10
Duty Cycle = 20%

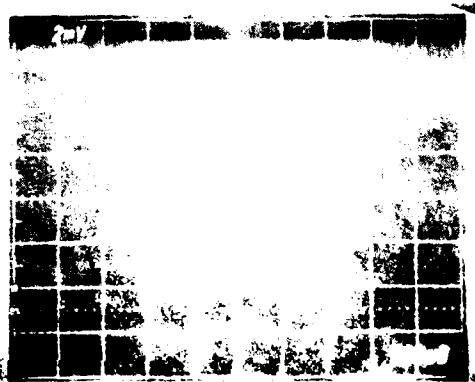


Figure 4-8 Saturation Voltage vs. Duty Cycle
for 55325 Device

Switching characteristics T_{THL} , T_{HHL} , T_{PLH} , T_{PHL}

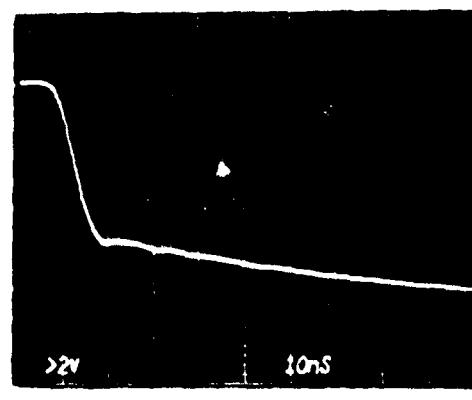
The following guidelines were used to ensure accurate and repeatable switching time measurements:

1. Test circuits were built on ground planes to minimize induced noise through signal returns and to minimize circuit inductances. High frequency wiring techniques were used throughout.
2. All power supply voltage pins were bypassed as close to the device under test (DUT) as possible. All supply lines were then checked for noise with the DUT switching.
3. The total bandwidth of the oscilloscope mainframe, plug ins, and probes were selected and verified to provide an overall oscilloscope measurement bandwidth of 350 MHz. This translates to an oscilloscope rise/fall time of ± 1 ns.
4. All probes were adjusted for proper compensation.
5. The time skew between channels on the oscilloscope was nullled out.
6. The input signal to the DUT was terminated to minimize line reflections. The input signal lines are made as short as possible to shorten the time frame during which any residual reflections might occur.
7. Supply voltages were carefully regulated to minimize switching time measurement errors due to supply voltage variation.
8. Load capacitance was adjusted for probe capacitance.

Most of the switching parameter results were as expected; however, one anomaly was discovered in T_{PHL} measurements at the source outputs for the 55325 devices. As shown in Figure 4-9A, the high-to-low output transition shows a very high initial slope, but suddenly flattens out approximately 10 ns after the start of the output transition.

Figure 4-9A

T_{PHL} , source output, 55325
Vendor A
 $C_L = 25 \text{ pF}$
 $R = 1 \text{ K}$



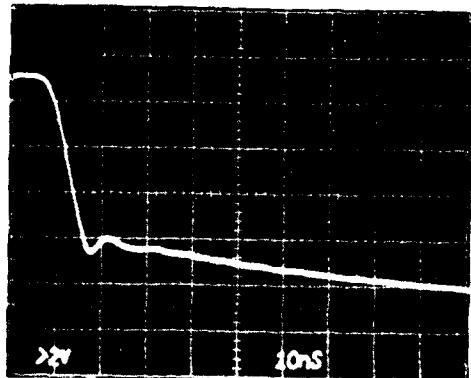


Figure 4-9B

F_{HI}, source output, 55325

Vendor B

$$C_1 = 25 \text{ pF}$$

$$R_1 = 1 \text{ K}$$

One possible explanation for this effect involves reverse recovery action in the output stage.

As shown in Figure 4-10 (the simplified schematic diagram), the source section of the 5532 consists of a standard TTL inverter followed by a high voltage totem pole driver and an emitter follower output. Assume that the input is initially in a logic low state. Q₃ is off, causing the Darlington pair consisting of Q₃ and Q₄ to be on and Q₅ to be off.

Hence, Q_1 is conducting and the output is in a high state.

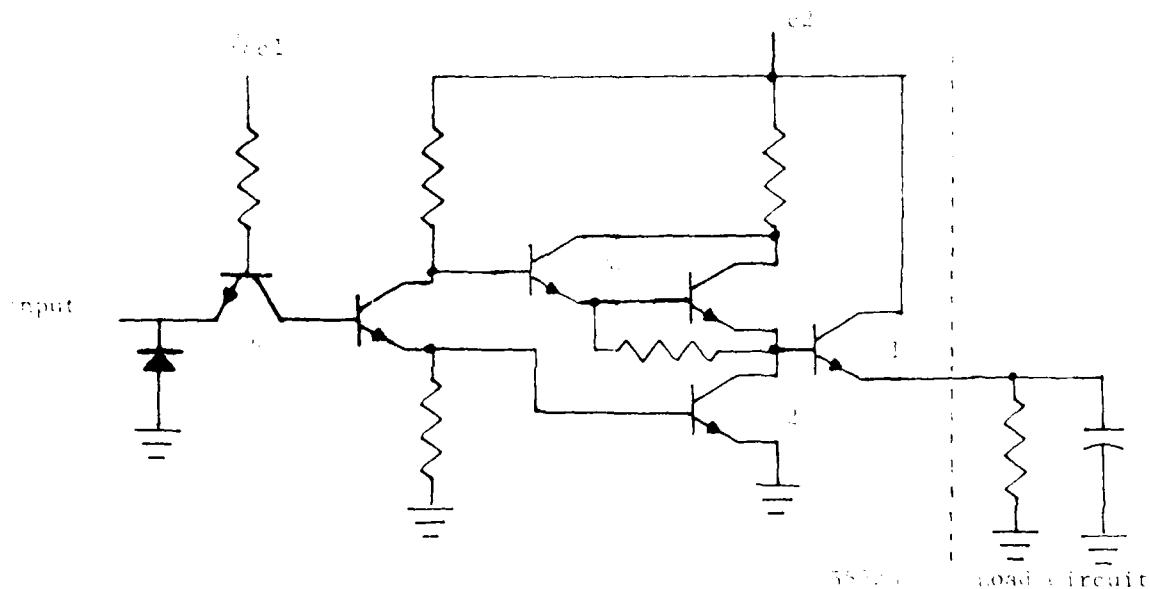


Figure 4-10. Simplified source section of 55325

If the input to the gate were to change from the low state to the high state, the collector of Q_1 will become forward biased, Q_3 will turn on, Q_2 and Q_4 will turn off, and Q_5 will start to conduct.

As the totem pole driver (consisting of Q₂, Q₃ and Q₄) changes state, the bias voltage across the emitter junction of Q₁ changes from the forward direction to the reverse direction. Reverse recovery action begins in the emitter of Q₁, tending to discharge C_L rapidly through the emitter of Q₁ and through Q₂. After recover, Q₁ is cut off and C_L is left to discharge through R_L. Hence, the output of the core driver shows a two slope transition. The steep initial transition is due to discharge of C_L primarily through Q₁, and the flatter portion of the transition occurs as C_L discharges through R_L.

A similar effect could occur with emitter breakdown of Q₁ during a high to low output transition. Further work is needed to investigate the exact cause.

4.6 Slash Sheet Development

The military specification (MIL-M-38510 slash sheet) on memory core drivers was developed in parallel with the characterization effort. As the test circuits and procedures were proofed out in the taking of device data, they were also incorporated into the slash sheet. With few exceptions, the proposed slash sheet Table I parameters and limits are the same as in the manufacturers data sheets. Limit changes were made only to switching parameters. An anomaly was observed in T_{THL} at the source outputs for the 55325. Further investigation is needed to fully understand the cause.

4.7 Conclusions and Recommendations

Twenty-four generic 55325 series memory core drivers were bench tested at GEOS. The devices tested in a predictable fashion and within manufacturers limits except for selected switching time measurements. The data and slash sheet parameters and limits will be reviewed by interested manufacturers prior to issuance of MIL-M-38510/130.

SECTION V

CMOS MULTIPLYING D/A CONVERTERS

MIL-M-38510/127

Table of Contents

	Page
5.1 Introduction	V-1
5.2 Description of Device Types	V-2
5.3 Test Development	V-5
5.4 Test Results and Data	V-11
5.5 Discussion of Data	V-14
5.6 Sigh Sheet Development	V-16
5.7 Conclusions and Recommendations	V-24

AD-A102 841

GENERAL ELECTRIC CO PITTSFIELD MA ORDNANCE SYSTEMS
ELECTRICAL CHARACTERIZATION AND SPECIFICATION OF PERIPHERAL DRI--ETC(U)
MAY 81 J S KULPINSKI, T HACK, T SIMONSEN F30602-80-C-0057

F/6 9/5

NL

UNCLASSIFIED

RADC-TR-81-72

200-2
40
4x284

END
DATE
FILED
9-81
DTIC

SECTION V

MIL-M-38510/127

5.1 Introduction

CMOS multiplying digital to analog converters were initially introduced in late 1973 by Analog Devices. Since then these devices have been used in many applications and several other manufacturers have incorporated them into their product lines. Table 5-1 shows the CMOS multiplying DA converters to be specified in MIL-M-38510/127.

Table 5-1. Table of Device Types Specified.

Device Type	Generic Type	Manufacturer Code *	Multiplying D/A Converter Description
01	AD7523S	A,M	8-bit res., 8-bit lin.
02	AD7520U	A,M,I,N	10-bit res., 10-bit lin.
03	AD7521U	A,M,I,N	12-bit res., 10-bit lin.
04	AD7541T	A,I	12-bit res., 12-bit lin.
05	AD7541T	A,I	12-bit res., 12-bit lin.**
06	DAC1020LD	N	10-bit res., 10-bit lin.
07	DAC1220LD	N	12-bit res., 10-bit lin.
08	DAC1218LD	N	12-bit res., 12-bit lin.
09	DAC1220LD	N	12-bit res., 12-bit lin.**

*Manufacturer Code

A = Analog Devices

M = Micro Power

I = Intersil

N = National Semiconductor

**Best fit linearity. All others are specified with end-point linearity.

Later deleted in slash sheet per agreement reached at JEDEC JC-41 meeting, 12 Feb 81.

A recommendation for characterization and possible slash sheet action was made by the JC-41 Committee to RADC. Some device features which should sustain this recommendation are as follows:

1. First monolithic 10-bit D/A converter. (AD7520)
2. Many potential applications and user options.
3. Cost effective with other competing process technologies.
4. Device is sourced by several manufacturers.
5. Low power dissipation.
6. Usage in military systems is high.

5.2 Description of Device Types

This CMOS series of multiplying D/A converters are fabricated with a deposited thin film R-2K ladder over a CMOS integrated circuit. A functional schematic of a typical circuit is shown in Figure 5-1.

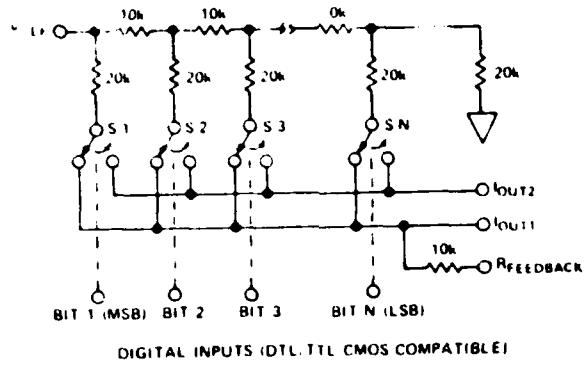


Figure 5-1. CMOS Multiplying D/A Converter

The R-2K ladder resistors consists of silicon-chromium material arranged to provide the network shown. In one vendor's design, these resistors have nominal values of 10 K ohms and 20 K ohms with an absolute temperature coefficient of approximately $-350 \text{ ppm}/\text{oC}$ and a tracking temperature coefficient of better than 1 ppm/oC.

When a voltage is applied to the reference terminal of the structure, the precision of the binary division of current is governed by the matching of the resistors and the drop across the associated switches. For proper operation on the output terminals I_{OUT1} and I_{OUT2} should be as close to ground reference as possible. The CMOS switches of the integrated cir-

structure are shown schematically in Figure 5-2.

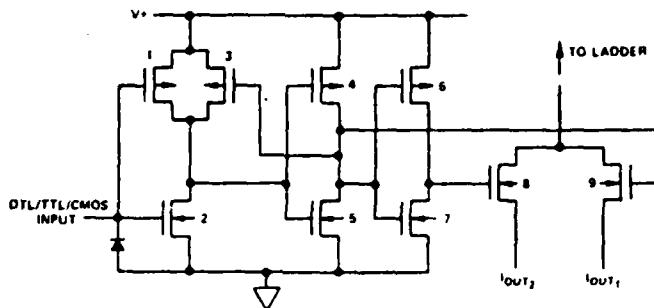


Figure 5-2. CMOS Switch Schematic

With the application of a DTL/TTL/CMOS compatible logic signal, two CMOS inverters assume the proper states to drive their respective output switches such that one is "ON" and the other "OFF". The end result is that the same ladder current is steered in either direction. A logic "high" input results in an Iout1 switch position and current flow.

Most applications of these R-2R ladder and switch networks involve an external operational amplifier configured as a current to voltage converter. The feedback resistor for this op amp is one of the deposited thin film resistors. Figure 5-3 shows how both devices are connected together to form a voltage output multiplying DAC. The digital input word determines the states of all of the bits from the MSB (Most Significant Bit) to the LSB (Least Significant Bit). All of the binary currents gated through logic "1" positioned switches flow through the feedback resistor to the op amp output. Therefore,

$$E_o = -I_{out1} * R_{fb}$$

The current Iout1 is the product of the reference voltage and the digital binary fraction divided by the R-2R ladder input resistance.

$$I_{out1} = D * E_{ref}/Z_{in}$$

where

$$D = B_1*(1/2) + B_2*(1/4) + B_3*(1/8) + \dots B_N*(1/2^N)$$

B1 thru BN are 1 or 0.

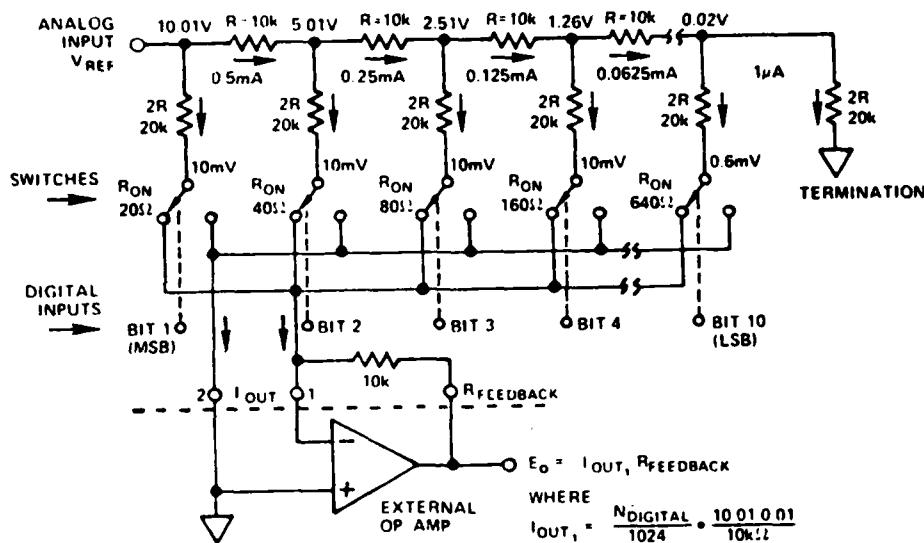


Figure 5-3. Typical Voltage Output MDAC Application

For the more common 2-quadrant multiplication application of an 8 bit device as shown in Figure 5-3, the relationship between digital input and analog output is as follows:

Digital Input	Analog Output
1111 1111	$-V_{REF} * (1 - 1/2 \exp 8) = -V_{REF} * (255/256)$
....	
....	
1000 0001	$-V_{REF} * ((1/2) + (1/2 \exp 8)) = V_{REF} * (129/256)$
1000 0000	$-V_{REF} * (1/2)$
....	
....	
0000 0001	$-V_{REF} * (1/2 \exp 8) = -V_{REF} * (1/256)$
0000 0000	0

This current mode DAC has an output impedance which varies with the input digital code word. Parasitic output capacitance interacting with this variable output impedance can result in poor closed loop response (either reduced bandwidth or ringing). A compensating capacitor across the output amplifier feedback resistor is recommended. Since the output impedance varies, the noise gain of the output op amp will result in a variable gain to noise and offsets. The op amp should therefore have low offset, low offset drift, and low noise. Also grounding techniques should be given careful consideration.

5.3 Test Development

A variety of devices were procured from three manufacturers as shown in Table 5.2.

Table 5.2. Device Types for Characterization.

Generic Type	Manufacturer	Quantity	Date Code
AD7523UD	Intersil	10*	7947
AD7523TD	Intersil	6*	7947
AD7520UD	Intersil	11*	7947
AD7520UD	Analog Devices	15	8006
AD7520UD	Analog Devices	10	8019
AD7521UD	Intersil	12*	7947
AD7521UD	Analog Devices	7*	8030
AD7541KD	Intersil	15*	7949
AD7541TD	Analog Devices	10	8038,8021
DAC1218	National	10*	8045

*Data was submitted with the devices.

Much of the test development for the CMOS MDAC characterization originated with the work done in characterizing the AD562 D/A converters. Many of the test techniques are similar.

CMOS MDAC Test Parameters

At a JC-41 meeting in August 1979 the manufacturers presented a proposed CMOS MDAC Specification. A list of parameters is shown in Table 5-3.

Table 5-3. Test Parameters for Characterization.

Item No	Symbol	Test Parameter
1	I _{cc}	Supply Current
2	I _{ref}	Reference Input Current
3	I _{IL}	Digital Input Leakage Current (logic 0)
4	I _{IH}	Digital Input Leakage Current (logic 1)
5	I _{ZS}	Zero Scale Current (I _{OUT1} at logic 0 input)
6	dI _{ZS} /dT	Zero Scale Current Drift
7	I _{ZS'}	Zero Scale Current (I _{OUT2} at logic 1 input)
8	+dVFS	Gain Error (Full Scale) with +10V Reference
9	-dVFS	Gain Error (Full Scale) with -10V Reference
10	dVFS/dT	Gain Error Drift
11	+PSS	Power Supply Sensitivity (+ 1V change)
12	-PSS	Power Supply Sensitivity (- 1V change)
13	LE	Linearity Error (End Point)
14	LE(BF)	Linearity Error (Best Fit)
15	MCE	Major Carry Error
16	FTE	Feedthrough Error
17	t _{SLR}	Output Current Settling Time (low to high)
18	t _{SHL}	Output Current Settling Time (high to low)
19	C _O	Output Capacitance
20	en	Noise (broadband)

Test parameter items 1 through 15, except LE(BF) were setup to be measured on GEOS' S-3270 Automatic Tester. All of these parameters are static. The static test circuit is shown in Figure 5-4. This circuit is very similar to the one used in testing the AD562 D/A Converters. There were, however, several essential differences which had to be made. Since the CMOS multiplying D/A's use a variable reference, it was decided that data had to be taken for several reference voltage conditions. These conditions were chosen at + 10 V, - 10 V, and + 1.25 V. A Fluke 5100B was used to generate the different reference voltage levels. The 16 bit reference D/A converter was remotely located from the adapter through a ribbon cable so that it could be used with other test adapters. In order to maintain voltage accuracy at the adapter U6 error amplifier, the reference D/A output buffer U4 has its output to feedback connection made at the error amplifier output. Also a ground driver U2-U3 is used to force the DUT and adapter ground to be at the same potential as the external reference D/A. The IOUT1 current output of the DUT is converted to a voltage by means of op amp U5. Since a millivolt of op amp offset voltage at 10 volts full scale causes a 0.01% linearity error, it is important that this offset be trimmed out. In other words, Iout1 and Iout2 must go to virtual ground and output ground for proper operation. The offset adjustment of U5 is done with relays K1 and K4 energized. For any digital code word between zero scale and full scale, the test circuit and software are mechanized so that nearly equal and opposite voltages are generated by the reference D/A at the output of U4 and the DUT at the output of U5. The differences between these voltages is amplified by U6 with a gain setting of 100 V/V and appears at adapter output pin 21.

Since the reference D/A is accurate to 16 bits, it is assumed perfect and any error is charged against the DUT. The inverted voltage output of the DUT D/A at U5 is determined indirectly as follows:

$$EDUT = Eo/G - EREF D/A$$

$$EDUT = -Eo/100 - 10(N)/2 \exp B$$

where

G = -100 V/V is the error amp gain

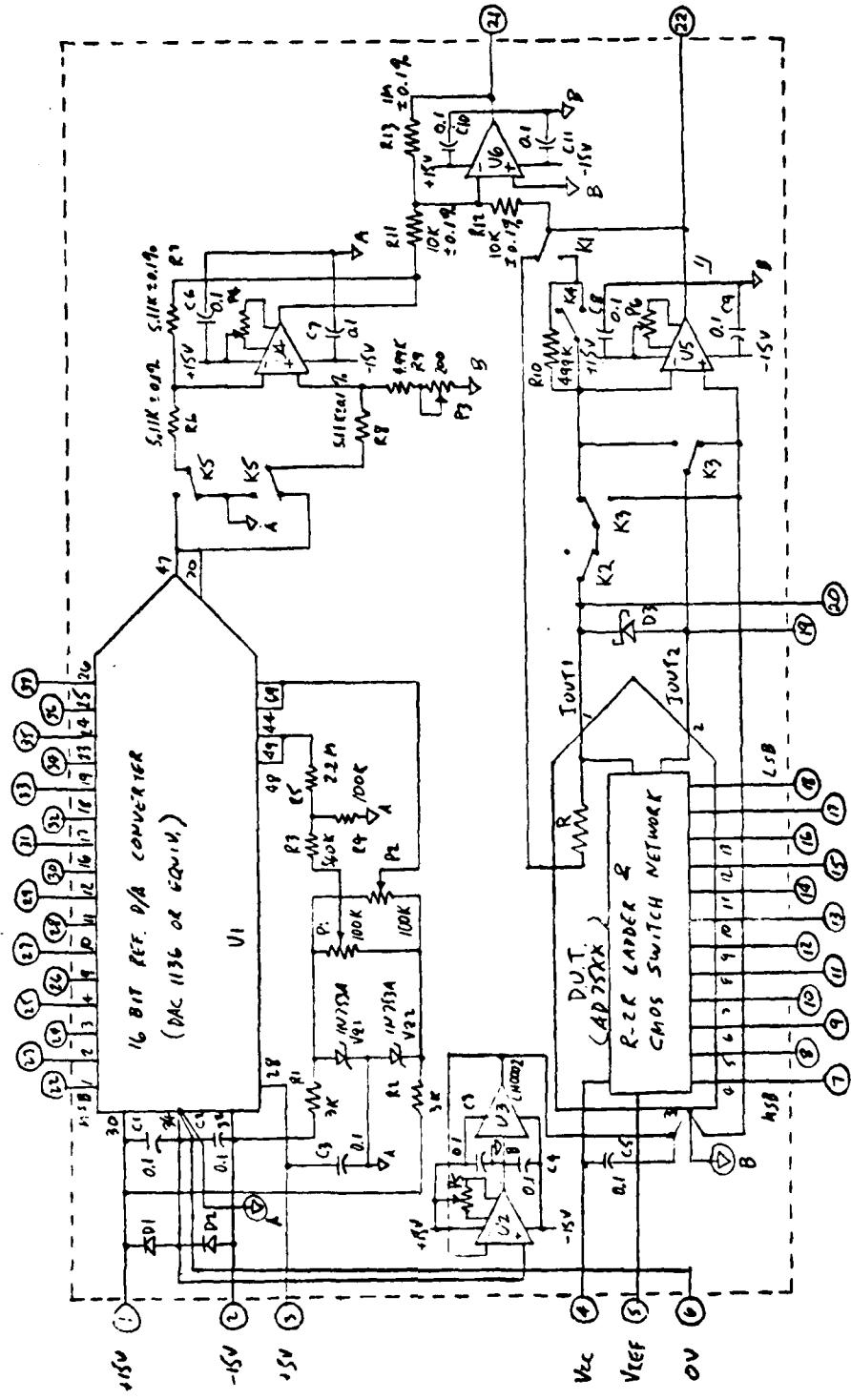
N = decimal equivalent of the input digital code word

B = number of bits

An inspection of the static test circuit shows that if the measured output voltage is positive, EDUT, although negative in polarity, has a greater magnitude than EREF D/A. Consequently, the DUT output has a positive scale error with respect to the Reference D/A.

The imaginary non-inverted value of the DUT D/A can then be written as

$$EDUT' = Eo/100 + 10(N)/2 \exp B$$



Notes: 1/ Op amp offset error ($V_{IO} + I_{IB} R_F$) adds to linearity error since I_{OUT1} and I_{OUT2} must go to 0V. For 10:1 measurement accuracy with a 12 bit DAC, acceptable op amps include the LF155, LF156 and OP-05 with V_{IO} (adj.) and the OP-07 without V_{IO} (adj.).

2/ One millivolt of offset error on 10 VFS causes 0.01% linearity error.

Figure 5-4. Test circuit for static tests.

If a 12 bit MDAC at full scale had a measured adapter output E_o of 0.1 volts,

$$EDUT' = 0.1/100 + 10(4095)/4096$$

$$EDUT' = 0.001 + 9.99756 \text{ V}$$

$$EDUT' = 9.99856 \text{ V}$$

The full-scale error of the device in % can be determined from

$$+dVFS = [(-E_o(FS)/G_1)/9.99756] \times 100\%$$

$$+dVFS = [(E_o(FS)/100)/9.99756] \times 100\%$$

$$+dVFS = 0.1 E_o(FS) \% VFS$$

$$+dVFS = (0.1)(.1) = + 0.01\% VFS$$

In millivolts the full-scale error is $+ dVFS = 0.01\% \text{ of } 10,000 \text{ mV} = 1 \text{ mV}$. The linearity error of the DUT output transfer characteristic from zero scale to full scale is perhaps the most important parameter to be measured. For characterization, GEOS's procedure has been to measure the adapter output error for all digital input codes. Thus for a 12 bit converter 4096 discrete measurements are required. Automatic calculations are then done to determine the deviation of each DUT output point from a straight line between the DUT's zero scale and full scale end points. Figure 5-5 shows the transfer characteristic of a hypothetical poor device compared to an ideal device.

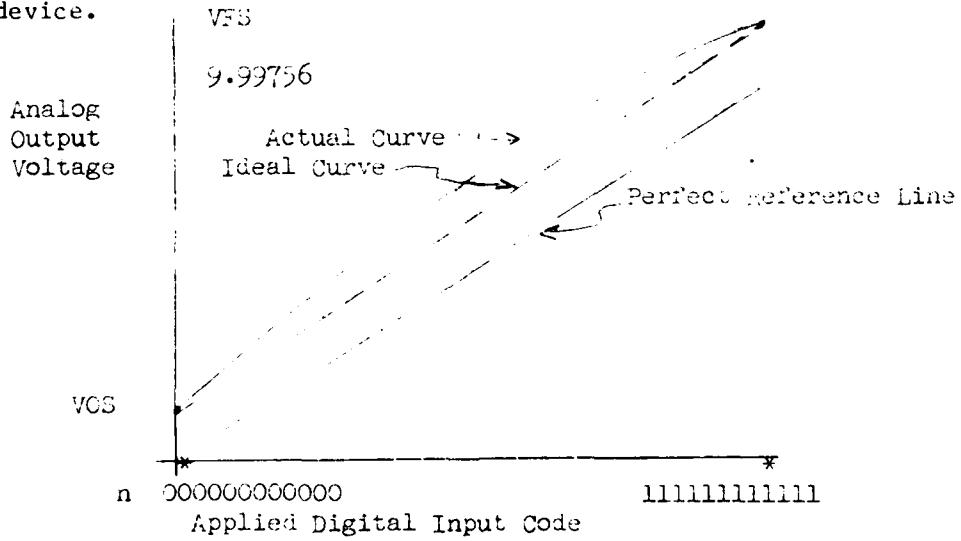
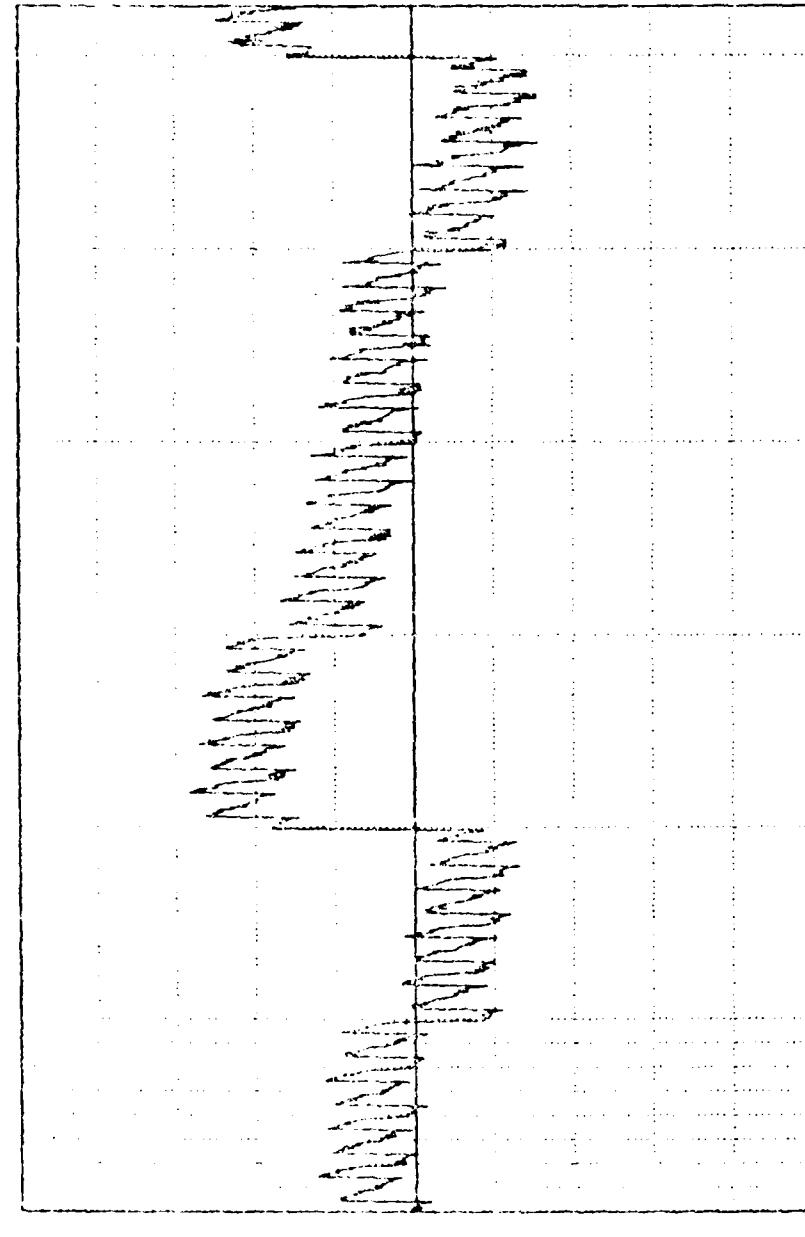


Figure 5-5. CMOS MDAC Transfer Characteristic.

F22 DEVICE S/N 31 AT 25 SEG S
VDD=+15.0 V UREF=10.0 V 03 FEB 81



APPLIED CODE
16 64 128 256 384 512 640 768

LINEARITY ERROR (ALL CODES)

7520-10 BIT D/A CONVERTER

Figure 5-6. Automatic linearity plot.

After the linearity error is determined for each point the data can be automatically plotted as shown in Figure 5-6, or it can be summarized by listing the individual bit errors and the worst case positive and worst case negative bit errors and associated address codes.

By comparison the remaining parameters to be measured with the static test circuit are determined quite easily. Relays K1 and K3 are energized to measure the zero scale currents at I_{OUT1} and I_{OUT2} using U_S as a current to voltage converter. Input reference current, which is a function of the 10V reference and the impedance of the R-2R ladder network is measured directly by energizing K2 with all bits high.

Feedthrough error, settling time and output capacitance were determined with separate test fixtures as shown in Figures 5-7, 5-8 and 5-9.

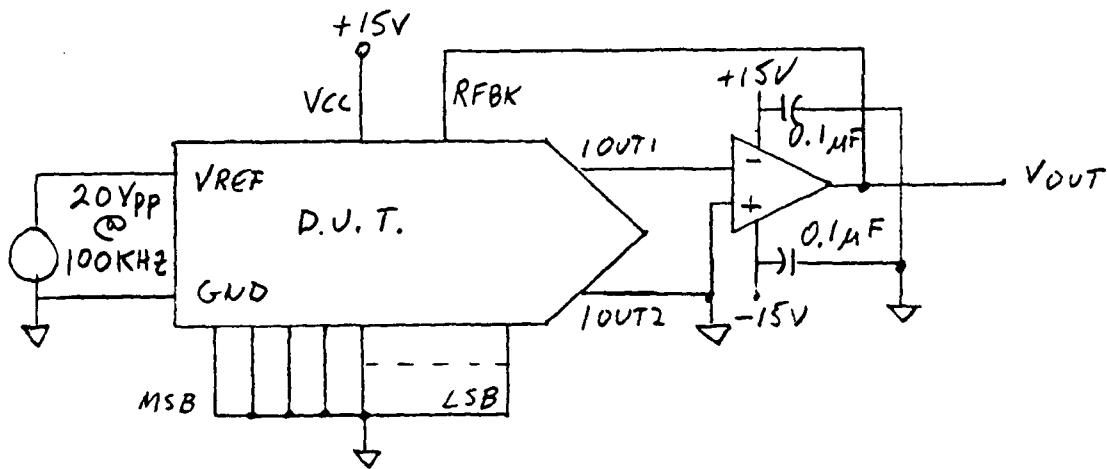


Figure 5-7. Feedthrough Error Test Circuit.

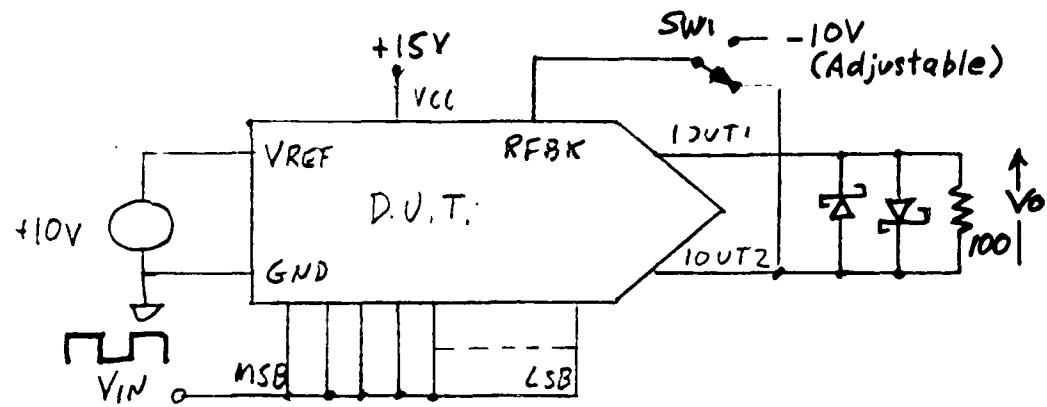
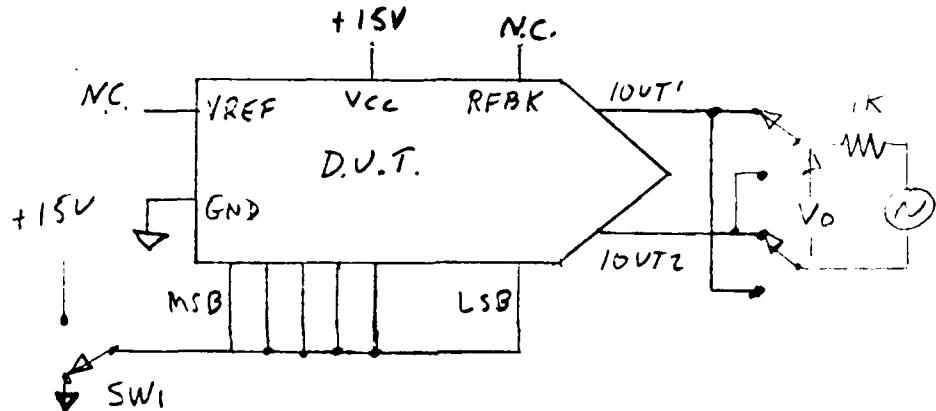


Figure 5-8. Settling Time Test Circuit.



Capacitance Test Circuit.

5.4 Test Results and Data

Characterization data was taken on twenty 10-bit devices from two vendors and fifteen 12-bit devices from three vendors. Each device was sequentially tested for all parameters at 25°C, -55°C and 125°C. The data was recorded in several different forms as follows:

1. A dedicated sheet for each device showing all parameters at all temperatures.
2. A comparison of the parameters of ten devices at one temperature on a sheet.
3. Parameter histograms of all devices at each temperature.
4. Plots of device bit linearity error vs applied digital input code.
5. Individual device histograms of bit linearity error vs frequency of occurrence.

The complete collection of data was published by GEOS in a handbook entitled:

Characterization Data for MIL-R-38510/127 CMOS Multiplying DA Converters (AD7520 & DAC 1020 Series)

Representative data sheets are shown in this report as follows:

- Table 5-4 Typical Mfr. Code A Device Data Sheet
- Table 5-5 Typical Mfr. Code B Device Data Sheet
- Table 5-6 Typical Mfr. Code C Device Data Sheet
- Table 5-7 Mfr. Code A Data (10 devices at 25°C)
- Table 5-8 Mfr. Code B Data (10 devices at 25°C)
- Table 5-9 Mfr. Code C Data (10 devices at 25°C)
- Figure 5-10 Histogram of Gain Error (20 devices)
- Figure 5-11 Linearity Error Distribution Histogram
- Figure 5-12 Linearity Error vs Input Code Plot
- Figure 5-13 Linearity Histogram at $V_{REF} = + 10$ V for S/N 2
- Figure 5-14 Linearity Histogram at $V_{REF} = - 10$ V for S/N 2
- Figure 5-15 Linearity Histogram at $V_{REF} = 1.25$ V for S/N 2
- Figure 5-16 Linearity Plot at $V_{CC} = +10$ V
- Figure 5-17 Linearity Plot at $V_{CC} = -10$ V

5-5 Discussion of Data

The characterization data in all forms was reviewed to see how well it compares to the original limits proposed by the JC-41 Committee. A discussion of this data on a parameter by parameter basis follows:

Power Supply Current (I_{CC})

The power supply current is much less than the indicated 100 μ A limits when the digital inputs are at 0 V or V_{CC} respectively. GEOS' data for these conditions is wrong because in making the measurements, full-scale was set at the 100 μ A recommended limit while the actual current was typically less than 1 μ A. As a consequence the machine accuracy and offset error swamped out the reading to be measured. This data was retaken on the bench and, except for one device, all values were less than 1 μ A. When the digital input levels were set at the 0.8 V to 2.4 V TTL compatible levels the supply current increased significantly, thus indicating more leakage in the OFF transistors of CMOS switches. At -55°C several vendor code B devices just exceeded the 2 mA maximum limit. GEOS recommends that the -55°C limit be raised to 2.5 mA.

Reference Current ($I_{REF(+)$, $I_{REF(-)}$)

All of the data was between 0.8 and 1.3 mA compared to the 0.5 to 2 mA limits. This current reflects the value of the R_{TH} ladder network.

Digital Input Leakage Current (I_{IL} , I_{IH})

The individual device sheets were set up to indicate PASS or FAIL to summarize the results if any of the ten or twelve digital inputs had a failure. No failures were recorded and the histograms indicated a spread between 0 and 43 nanoamperes.

Zero Scale Current (I_{ZS} , $I_{ZS'}$)

Typical device data was much less than the recommended limits of +/- 200 nA. Except for one maverick device which measured -149.5 nA at 125°C, all other data was between -11 nA and 0. GEOS recommends that the limits be reduced to +/- 100 nA. It is believed that the single untypical value could be a measurement error because it does not agree with submitted vendor data.

Zero Scale Current Drift ($dIZS/dT$)

A review of the data indicates that limits of $\pm 400 \text{ pA}/^\circ\text{C}$ would be reasonable. There was no JC-41 recommendation on this parameter.

Full Scale Error (+ dVFS, - dVFS)

The distribution of data between -45.6 mV and 17.6 mV was well within the $\pm 100 \text{ mV}$ recommended limits.

Full Scale Error Drift ($dVFS/dT$)

All of the data is within the $\pm 10 \text{ ppm VFS/V}$ limits.

Power Supply Sensitivity (+ PSS, - PSS)

The distribution of data is very much tighter than the recommended limits of $\pm 100 \text{ ppm VFS/V}$. GEOS recommends that these limits be reduced to $\pm 50 \text{ ppm VFS/V}$.

Linearity Error (LE)

Linearity error is one parameter which cannot be negotiated. The linearity has to be within $1/2 \text{ LSB}$ to meet the stated accuracy requirement. Most of the data is well within the $\pm 1/2 \text{ LSB}$ limits. Figure 5-12 shows how the linearity for a typical device varies with its input code. Figures 5-13, 5-14 and 5-15 show the linearity histograms of one device (S/N 2) with $V_{REF} = +10 \text{ V}$, -10 V and $+1.25 \text{ V}$ respectively. Because of the apparent independence of reference voltage level the specification requirement to test at all three levels may be reduced to testing at $+10 \text{ V}$ only.

Feedthrough Error (FTE)

All of the data for devices from vendors A and B were under 8.5 mVpp . These devices are within their 10 mVpp limit. Vendor Code C devices had feedthrough errors as high as 19 mVpp . These devices satisfy their 25 mVpp limit.

Output Current Settling Time (t_{SLH}, t_{SHL})

All devices had data values within the recommended 1 usec maximum limit.

Output Capacitance (C_o)

All device data satisfies the JC-41 committee's recommended limits.

5.6 Slash Sheet Development

The slash sheet, MIL-M-38510/127, was developed as a joint effort of GEOS and the JC-41 Committee/Subcommittee. The majority of the test parameters were established early in the slash sheet development in a JC-41 Subcommittee meeting. One major change has been the deletion of +5V as a recommended operating supply voltage. All-codes data taken on a 7520 device from vendor A showed excessive linearity errors and differential linearity errors, especially at +125°C. A comparison of one such sample of data taken at two supply voltages is shown in the Appendix, Table 5-16 and Table 5-17. GEOS' recommendation to limit operating voltage to +15 volts was adopted by the JC-41 committee.

A major goal of the characterization was to develop an abbreviated test for linearity. Initial all-codes testing of the 7520 linearity error showed that the abbreviated test used for the 562 12-bit D/A Converter specified in MIL-M-38510/121 was invalid for the 7520, since it did not find the worst case codes having maximum linearity error. The following approach to an abbreviated test was developed by GE and is proposed for the slash sheet:

1. Measure all combinations of the four MSB's with the lower order bits OFF.
2. Measure each of the lower order bits with the four MSB's OFF.
3. Determine the code word with the most positive predictable error based on the above tests, and measure that error. Repeat this measurement but with all lower order bits complemented one at a time.
4. Repeat the third group of tests above, but with the most negative predictable error codes.

This abbreviated test is done in Group A at three temperatures. An all-codes test at three temperatures is also required on a sample basis in the slash sheet.

This device is used as a multiplying DAC in many applications. Therefore, it is also necessary to test its ability to convert digital inputs with a negative reference voltage applied. GE has characterized the 7520 device at three reference voltage levels: +10V, -10V, and +1.25 V. Linearity errors are comparable at all three reference levels, although in many cases the error is slightly greater at minus ten volts than at plus ten volts. In order to guarantee the performance for both polarities, the abbreviated test is also required to be run at both plus and minus 10 volt levels, and at +1.25 volts. This requirement will be further negotiated with the JC-41 committee.

Table I, Electrical Performance Characteristics, MIL-M-38510/127, is included in the following for reference.

5.7 Conclusions and Recommendations

The 7520 10-bit DAC (and the 7523 8-bit DAC which is manufactured using the 7520 chip) has been characterized and is judged suitable for use in military systems when procured via MIL-M 38510/127. Device manufacturers will review the characterization data and proposed slash sheet before the issuance of the final slash sheet.

The 7541 12-bit DACs have not yet been fully characterized at the time of writing of this report. That effort will be completed and integrated into the final released specification.

Table 3-4. Typical Mfr. Data A Device Data Sheet.

PARAMETER	DEVICE TYPE 7520		S/N 1		1 LS0		S.775P0		+125 IEC C	
	LO-LIM	SS DEG C	HI-LIM	LO-LIM	SS DEG C	HI-LIM	LO-LIM	SS DEG C	HI-LIM	LO-LIM
ICC - ALL INPUTS AT 0.0V	0.00	-1.00	100.	0.00	-3.00	100.	0.00	-2.50	100.	0.00
ICC - PLL INPUTS AT 1.0V	0.00	-4.87	100.	0.00	5.00	100.	0.00	5.04	100.	0.00
ICC - ALL INPUTS AT 0.8V	0.00	10.00	2.00	0.00	5.00	2.00	0.00	30.00	2.00	0.00
ICC - ALL INPUTS AT 2.4V	0.00	1.04	2.00	0.00	7.25	2.00	0.00	51.00	2.00	0.00
IREF(+) - ALL INPUTS AT 15U	500.0	915.0	2.00	500.0	940.0	2.00	500.0	965.0	2.00	500.0
IREF(-) - ALL INPUTS AT 15U	-2.00	-940.0	-500.0	-2.00	-960.0	-500.0	-2.00	-985.0	-500.0	-2.00
IIL - ALL INPUTS AT 0.0V	-1.00	PASSED	1.00	-1.00	PASSED	1.00	-1.00	PASSED	1.00	0.00
IIL - ALL INPUTS AT 0.8V	-2.00	PASSED	1.00	-2.00	PASSED	1.00	-2.00	PASSED	1.00	0.00
IIL - ALL INPUTS AT 15U	-1.00	PASSED	1.00	-1.00	PASSED	1.00	-1.00	PASSED	1.00	0.00
IIL - ALL INPUTS AT 2.4V	-1.00	PASSED	1.00	-1.00	PASSED	1.00	-1.00	PASSED	1.00	0.00
I2S - ALL INPUTS AT 0.0V	-2.00	-3.00	200.	-2.00	-2.50	200.	-2.00	-6.50	200.	0.00
I2S - ALL INPUTS AT 2.4V	-2.00	-2.50	200.	-2.00	-2.00	200.	-2.00	-6.50	200.	0.00
dI2S/dT - ALL INPUTS AT 0.0V	-50.0	6.25	50.0	-50.0	6.00	50.0	-50.0	40.0	50.0	PA/GC
dI2S/dT - ALL INPUTS AT 2.4V	-50.0	6.25	50.0	-50.0	6.00	50.0	-50.0	45.0	50.0	PA/GC
GAIN ERROR (UVFS)	-100.	-16.5	100.	-100.	-11.5	100.	-100.	-4.55	100.	0.00
GAIN ERROR (dGFS/dT)	-10.0	-6.39	10.0	-10.0	-6.00	10.0	-10.0	-6.95	10.0	0.00
PSS - VCC+15U TO 16U	-100.	-1.29	100.	-100.	-1.79	100.	-100.	-10.77	100.	0.00
PSS - VCC+15U TO 14U	-100.	-108.0	100.	-100.	-527.0	100.	-100.	-410.0	100.	0.00
BIT LINEARITY ERROR - RSD	-500.0	-4.487	500.0	-500.0	-2.447	500.0	-500.0	35.11	500.0	0.00
BIT LINEARITY ERROR - B2	-500.0	-12.437	500.0	-500.0	-12.437	500.0	-500.0	500.0	500.0	0.00
BIT LINEARITY ERROR - B3	-500.0	8.437	500.0	-500.0	90.37	500.0	-500.0	94.47	500.0	0.00
BIT LINEARITY ERROR - B4	-500.0	141.0	500.0	-500.0	141.0	500.0	-500.0	139.0	500.0	0.00
BIT LINEARITY ERROR - B5	-500.0	31.67	500.0	-500.0	18.27	500.0	-500.0	16.67	500.0	0.00
BIT LINEARITY ERROR - B6	-500.0	27.97	500.0	-500.0	6.38	500.0	-500.0	6.05	500.0	0.00
BIT LINEARITY ERROR - B7	-500.0	11.87	500.0	-500.0	3.47	500.0	-500.0	5.37	500.0	0.00
BIT LINEARITY ERROR - B8	-500.0	47.27	500.0	-500.0	89.07	500.0	-500.0	126.07	500.0	0.00
BIT LINEARITY ERROR - B9	-500.0	49.47	500.0	-500.0	76.17	500.0	-500.0	119.17	500.0	0.00
BIT LINEARITY ERROR - LS0	-500.0	37.27	500.0	-500.0	56.57	500.0	-500.0	84.17	500.0	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	318.0	500.0	0.00	315.0	500.0	0.00	434.0	500.0	0.00
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	0.00	455.0	500.0	0.00	455.0	500.0	0.00	422.0	500.0	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	503.0	500.0	0.00	463.0	500.0	0.00	463.0	500.0	0.00
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	-500.0	-115.0	0.00	-500.0	-182.0	0.00	-500.0	-216.0	0.00	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	956.0	500.0	0.00	1.02K	500.0	0.00	952.0	500.0	0.00
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	-500.0	-67.47	0.00	-500.0	-167.47	0.00	-500.0	-222.47	0.00	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	928.0	0.00	0.00	944.0	0.00	0.00	952.0	0.00	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (TREF=15U)	0.00	397.0	500.0	0.00	344.0	500.0	0.00	437.0	500.0	0.00
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (TREF=15U)	0.00	456.0	500.0	0.00	455.0	500.0	0.00	463.0	500.0	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (TREF=15U)	-500.0	-83.74	0.00	-500.0	-134.74	0.00	-500.0	-216.74	0.00	0.00
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (TREF=15U)	0.00	956.0	0.00	0.00	952.0	0.00	0.00	952.0	0.00	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (TREF=15U)	0.00	214.0	500.0	0.00	264.0	500.0	0.00	358.0	500.0	0.00
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (TREF=15U)	-600.0	-327.0	0.00	-600.0	-327.0	0.00	-600.0	-463.0	0.00	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (TREF=15U)	0.00	-600.0	0.00	0.00	-600.0	0.00	0.00	-600.0	-283.0	0.00
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (TREF=15U)	0.00	-173.0	0.00	0.00	-173.0	0.00	0.00	-173.0	-763.0	0.00

NOTE 1.250 (0) IN LIMITS COLUMN MEANS NO LIMIT. IT CAN BE INTERPRETED AS A DASH (-).

Table 5-5. Typical Mrf. Code B Device Data Sheet.

CROS MULTIPLYING D/A CONVERTER	DEVICE TYPE 7520	S/N 31	1 LSD	9.775MV
PARAMETER	LO-LIN DATA	HI-LIN	LO-LIN DATA	HI-LIN
	25 DEG C	25 DEG C	LO-LIN DATA	HI-LIN
ICC - ALL INPUTS AT 0.8V	0.00	-1.00	100.	0.00
ICC - ALL INPUTS AT 15.8V	0.00	-4.02	100.	0.00
ICC - ALL INPUTS AT 0.8V	0.00	20.0M	100.	0.00
ICC - ALL INPUTS AT 2.4V	0.00	2.06	100.	0.00
IREF(+)-ALL INPUTS AT 15U	500.0M	1.27	500.0M	1.27
IREF(-)-ALL INPUTS AT 15U	-2.00	-1.27	-500.0M	-1.30
IIL - ALL INPUTS AT 0.8V	-1.00	PASSED	1.00	PASSED
IIL - ALL INPUTS AT 0.8V	-200.	PASSED	-200.	PASSED
IIL - ALL INPUTS AT 15.8V	-1.00	PASSED	-1.00	PASSED
IIL - ALL INPUTS AT 2.4V	-1.00	PASSED	100.	PASSED
I2S - ALL INPUTS AT 0.8V	-200.	-2.00	-200.	-2.00
I2S - ALL INPUTS AT 2.4V	-200.	-3.00	-200.	-3.00
D12S/+AT - INPUTS AT 0.8V	-50.0	0.00	-50.0	0.00
D12S/+AT - INPUTS AT 2.4V	-50.0	37.5	-50.0	37.5
GAIN ERROR (UFS)	-100.	-37.7	100.	-100.
GAIN ERROR (dUFS/dT)	-10.0	6.87	10.0	0.00
PSS - UCC-15U TO 15U	-100.	317.0M	100.	155.0M
PSS - UCC-15U TO 14U	-100.	1.27	100.	-311.0M
BIT LINEARITY ERROR - FS8	-500.0M	4.57M	500.0M	-500.0M
BIT LINEARITY ERROR - B2	-500.0M	186.0M	500.0M	-500.0M
BIT LINEARITY ERROR - B3	-500.0M	-84.5M	500.0M	-500.0M
BIT LINEARITY ERROR - B4	-500.0M	12.7M	500.0M	-500.0M
BIT LINEARITY ERROR - B5	-500.0M	21.3M	500.0M	-500.0M
BIT LINEARITY ERROR - B6	-500.0M	29.4M	500.0M	-500.0M
BIT LINEARITY ERROR - B7	-500.0M	76.9M	500.0M	-500.0M
BIT LINEARITY ERROR - B8	-500.0M	-11.3M	500.0M	-500.0M
BIT LINEARITY ERROR - B9	-500.0M	-2.36M	500.0M	-500.0M
BIT LINEARITY ERROR - L5B	-500.0M	866.0U	500.0M	-3.05M
MAX(+) LINEARITY ERROR A	0.00	265.0M	500.0M	0.00
ASSOC ADDRESS (ALL CODES)	0.00	280.0M	500.0M	0.00
MAX(+) LINEARITY ERROR B	0.00	256.0M	500.0M	0.00
ASSOC ADDRESS (ABREU)	0.00	312.0M	500.0M	0.00
MAX(-) LINEARITY ERROR A	-500.0M	-91.0M	0.00	-500.0M
ASSOC ADDRESS (ALL CODES)	-500.0M	759.0M	0.00	-500.0M
MAX(-) LINEARITY ERROR B	-500.0M	-171.0M	0.00	-500.0M
ASSOC ADDRESS (ABREU)	0.00	726.0M	0.00	0.00
MAX(+) LINEARITY ERROR B	0.00	239.0M	500.0M	0.00
ASSOC ADDRESS (UREF+/-16U)	0.00	776.0M	500.0M	0.00
MAX(-) LINEARITY ERROR A	-500.0M	-155.0M	0.00	-500.0M
ASSOC ADDRESS (UREF+/-16U)	0.00	727.0M	0.00	0.00
MAX(+) LINEARITY ERROR A	0.00	852.0M	500.0M	0.00
ASSOC ADDRESS (UREF+/-16U)	0.00	201.0M	500.0M	0.00
MAX(-) LINEARITY ERROR A	-500.0M	-100.0M	0.00	-500.0M
ASSOC ADDRESS (UREF+/-16U)	0.00	759.0M	0.00	0.00

NOTE: 1. ZERO (0) IN LIMITS COLUMN MEANS NO LIMIT. IT CAN BE INTERPRETED AS A DASH (-).

Table 5-6. Typical Mir. Code C Device Data Sheet.

PARAMETER	DEVICE TYPE	1218		S/N 9		1 LSD= 2.4427MV	
		LO-LIM DATA	HI-LIM	LO-LIM	HI-LIM	LO-LIM	HI-LIM
ICC - ALL INPUTS AT 0.8V	0.00	1.69	2.00	0.00	1.25	2.00	0.00
ICC - ALL INPUTS AT 0.8U	0.00	730.0	2.00	0.00	740.0	2.00	0.00
ICC - ALL INPUTS AT 0.8V	0.00	1.76	2.00	0.00	1.29	2.00	0.00
ICC - ALL INPUTS AT 0.8U	0.00	625.0	2.00	0.00	446.0	2.00	0.00
ICC - ALL INPUTS AT 2.4V	0.00	625.0	2.00	0.00	446.0	2.00	0.00
IREF(+)-ALL INPUTS AT 15U	500.0	625.0	2.00	500.0	625.0	2.00	500.0
IREF(-)-ALL INPUTS AT 15U	-2.00	-625.0	-2.00	-2.00	-635.0	-2.00	-2.00
IIL - ALL INPUTS AT 0.8V	-200.	PASSED	1.00	-200.	PASSED	1.00	-200.
IIL - ALL INPUTS AT 0.8U	-200.	PASSED	1.00	-200.	PASSED	1.00	-200.
IIIH - ALL INPUTS AT 15.8V	-200.	PASSED	1.00	-200.	PASSED	1.00	-200.
IIIH - ALL INPUTS AT 2.4V	-1.00	FAILED	1.00	-1.00	PASSED	1.00	-1.00
I2S - ALL INPUTS AT 0.8V	-200.	200.	-200.	-160.	200.	-200.	-4.38K
I2S' - ALL INPUTS AT 2.4U	-200.	-130.	200.	-200.	-135.	-200.	-195.
dI2S/dT - INPUTS AT 0.8V	-50.0	-62.5	50.0	0.00	0.00	-50.0	42.2K
dI2S/dT - INPUTS AT 2.4U	-50.0	-62.5	50.0	0.00	0.00	-50.0	50.0
GAIN ERROR (UVFS)	-100.	-907.0	100.	-100.	-1.97	100.	-100.
GAIN ERROR (dUFS/dT)	-10.0	-1.32	10.0	0.00	0.00	-10.0	-3.66
PSS - UCC-15U TO 16V	-100.	300.0	100.	-100.	300.0	100.	-100.
PSS - UCC-15U TO 14U	-100.	950.0	100.	-100.	-1.05	100.	-100.
BIT LINEARITY ERROR - 16SB	-500.0	41.5K	500.0	-500.0	50.3M	500.0	-500.0
BIT LINEARITY ERROR - B2	-500.0	88.9K	500.0	-500.0	85.6K	500.0	-500.0
BIT LINEARITY ERROR - B3	-500.0	3.67K	500.0	-500.0	-3.00K	500.0	-500.0
BIT LINEARITY ERROR - B4	-500.0	-211.0	500.0	-500.0	-206.0	500.0	-500.0
BIT LINEARITY ERROR - B5	-500.0	79.1K	500.0	-500.0	75.3K	500.0	-500.0
BIT LINEARITY ERROR - B6	-500.0	114.0	500.0	-500.0	121.0	500.0	-500.0
BIT LINEARITY ERROR - B7	-500.0	33.3K	500.0	-500.0	33.4K	500.0	-500.0
BIT LINEARITY ERROR - B8	-500.0	-29.5K	500.0	-500.0	-24.8K	500.0	-500.0
BIT LINEARITY ERROR - B9	-500.0	34.0K	500.0	-500.0	34.0K	500.0	-500.0
BIT LINEARITY ERROR - B10	-500.0	33.8K	500.0	-500.0	28.1K	500.0	-500.0
BIT LINEARITY ERROR - B11	-500.0	43.2K	500.0	-500.0	40.4K	500.0	-500.0
BIT LINEARITY ERROR - LSB	-500.0	50.5K	500.0	-500.0	43.8K	500.0	-500.0
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	308.0	500.0	0.00	328.0	500.0	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	0.00	3.81K	0.00	0.00	3.30K	0.00	0.00
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	298.0	500.0	0.00	328.0	500.0	0.00
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	0.00	3.31K	0.00	0.00	3.30K	0.00	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	0.00	-50.0	0.00	-50.0	-257.0	0.00	-50.0
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	0.00	2.84K	0.00	0.00	79.6	0.00	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	0.00	-500.0	0.00	-500.0	-254.0	0.00	-500.0
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	0.00	-272.0	0.00	0.00	792.0	0.00	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	0.00	784.0	0.00	0.00	784.0	0.00	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (UREF=-16U)	0.00	235.0	500.0	0.00	289.0	500.0	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (UREF=-16U)	0.00	272.0	0.00	0.00	289.0	0.00	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (UREF=-16U)	0.00	-437.0	0.00	-500.0	-507.0	0.00	-500.0
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (UREF=-16U)	0.00	3.82K	0.00	0.00	3.78K	0.00	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (UREF=-16U)	0.00	111.0	500.0	0.00	231.0	500.0	0.00
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (UREF=-16U)	0.00	-876.0	0.00	-500.0	-516.0	0.00	-500.0
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (UREF=-16U)	0.00	2.96K	0.00	0.00	2.83K	0.00	0.00

NOTES: 1. ZERO (0) IN LIMITS COLUMN MEANS NO LIMIT. IT CAN BE INTERPRETED AS A DASH (-).

Table 5-7. Mfr. Code A Data - 25°C
 CROSS MULTIPLYING D/A CONVERTER DEVICE TYPE 7528
 29 JAN 80 10122123 UDD • 15.0 VOLTS

	S/N 1	S/N 2	S/N 3	S/N 4	S/N 5	S/N 6	S/N 7	S/N 8	S/N 9	S/N 10
PARAMETER	LO-LIN									
ICC = ALL INPUTS AT 0.8V	0.00	-3.00	-2.00	-4.50	-1.00	-6.50	-5.00	-2.00	2.00	-500.0
ICC = ALL INPUTS AT 15.0V	0.00	5.00	4.16. x	5.15. x	4.95. x	4.72. x	5.28. x	4.66. x	4.57. x	428. x
ICC = ALL INPUTS AT 0.8V	0.00	5.00	5.00	5.00	5.00	5.00	5.00	5.00	5.00	100.0
ICC = ALL INPUTS AT 2.4V	0.00	7.25.0	7.20.0	6.40.0	6.75.0	6.70.0	6.65.0	6.70.0	6.75.0	2.00
IREF(+) - ALL INPUTS AT 15V	500.0	940.0	865.0	1.00	850.0	885.0	1.05	825.0	1.10	845.0
IREF(-) - ALL INPUTS AT 15V	-2.00	-950.0	-895.0	-1.00	-875.0	-905.0	-1.00	-850.0	-1.12	-890.0
IIL - ALL INPUTS AT 0.8V	-1.00	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS
IIL - ALL INPUTS AT 15.0V	-2.00	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS
IIM - ALL INPUTS AT 2.4V	-1.00	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS
IIM - ALL INPUTS AT 15V	-1.00	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS
ID2S - ALL INPUTS AT 0.8V	-2.00	-2.50	-2.50	-2.50	-2.50	-2.50	-2.50	-2.50	-2.50	-2.50
ID2S - ALL INPUTS AT 2.4V	-2.00	-2.50	-2.50	-2.50	-2.50	-2.50	-2.50	-2.50	-2.50	-2.50
dI2S/dt - INPUTS AT 0.8V	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
dI2S/dt - INPUTS AT 2.4V	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
GAIN ERROR (VFS)	-100.	-11.5	17.6	15.3	-1.12	1.42	5.89	4.93	-8.22	-3.52
GAIN ERROR (dVFS/dt)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
PSS - VCC=15V TO 16V	-100.	-1.79	-684.0	279.0	116.0	-334.0	93.0	0.00	180.0	-457.0
PSS - VCC=15V TO 14V	-100.	527.0	-1.03	1.77	1.39	-1.56	-1.03	-2.15	1.26	0.00
BIT LINEARITY ERROR -	NSB	-500.0	-2.44	372.0	127.0	4.83	116.0	-142.0	-176.0	-157.0
BIT LINEARITY ERROR - B2	-500.0	124.0	379.0	80.0	47.5	220.0	67.5	38.0	40.0	182.0
BIT LINEARITY ERROR - B3	-500.0	96.3	-73.6	87.1	111.0	213.0	110.0	47.5	163.0	189.0
BIT LINEARITY ERROR - B4	-500.0	141.0	72.8	136.0	136.0	242.0	175.0	225.0	216.0	34.7
BIT LINEARITY ERROR - B5	-500.0	18.2	-41.2	12.0	31.9	48.4	61.3	78.1	20.8	116.0
BIT LINEARITY ERROR - B6	-500.0	-6.58	-76.8	-4.80	6.72	22.6	6.65	25.6	34.2	21.6
BIT LINEARITY ERROR - B7	-500.0	34.4	62.7	34.1	31.7	55.7	63.0	45.0	38.7	59.0
BIT LINEARITY ERROR - B8	-500.0	80.0	97.2	92.5	76.3	80.6	103.0	87.3	77.2	18.9
BIT LINEARITY ERROR - B9	-500.0	56.5	59.7	68.3	55.7	54.3	76.7	97.4	112.0	54.2
BIT LINEARITY ERROR - LSB	-500.0									
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	345.0	574.0	365.0	336.0	547.0	498.0	403.0	614.0	525.0
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	---	455	591	583	199	207	591	103	463	335
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	0.00	334.0	81.8	351.0	191.0	537.0	388.0	385.0	556.0	286.0
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	-500.0	-463	183.0	591	623	239	239	239	239	DEC
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	1616	-183.0	-300.0	-186.0	-181.0	-350.0	-241.0	-241.0	-325.0	-325.0
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	-500.0	-167.0	-157.0	-135.0	-152.0	-356.0	-122.0	-122.0	-944	944
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	---	944	944	944	912	784	784	912	944	944
MAX(+) LINEARITY ERROR (UREF=10U)	0.00	344.0	573.0	392.0	320.0	533.0	424.0	394.0	600.0	434.0
MAX(-) LINEARITY ERROR (UREF=1.25U)	---	455	591	583	199	207	583	359	463	335
MAX(-) LINEARITY ERROR (UREF=10U)	-500.0	-134.0	-289.0	-107.0	-111.0	-300.0	-173.0	-231.0	-264.0	-264.0
ASSOC ADDR (UREF=1.25U)	---	952	952	952	916	952	952	952	944	944
MAX(+) LINEARITY ERROR & ASSOC ADDR (UREF=1.25U)	0.00	264.0	491.0	273.0	299.0	516.0	342.0	389.0	492.0	382.0
MAX(-) LINEARITY ERROR & ASSOC ADDR (UREF=1.25U)	-500.0	-207.0	-527.0	-71	199	79	193	463	207	207
MAX(-) LINEARITY ERROR & ASSOC ADDR (UREF=1.25U)	---	668	496	952	816	816	816	816	-435.0	-283.0
MAX(-) LINEARITY ERROR & ASSOC ADDR (UREF=1.25U)	---	668	496	952	816	816	816	816	560	560

NOTE: 1. ZERO (0) IN LIMITS COLUMN MEANS NO LIMIT. IT CAN BE INTERPRETED AS A DEADH (-).

Table 5-b. Mfr. Code B Data at 25°C.
 CROSS MULTIPLYING D/A CONVERTER DEVICE "VPE 7520" UREF = +10V EXCEPT WHERE SPECIFIED
 29 JAN 80 10:23:42 UDD = :5.0 VOLTS TEMPERATURE = +25 DEGREES C

PARAMETER	LO-LIN	S/N31	S/N32	S/N33	S/N34	S/N35	S/N36	S/N37	S/N38	S/N39	S/N40	UNITS
ICC - ALL INPUTS AT 0.0V	0.00	-1.50	-4.50	2.00	-2.00	-2.50	-1.00	-3.50	-6.50	-1.00	-3.00	MI-LIN
ICC - ALL INPUTS AT 15.0V	0.00	794.0	612.0	686.0	652.0	577.0	508.0	576.0	603.0	500.0	608.0	mA
ICC - ALL INPUTS AT 0.8V	0.00	176.0	115.0	75.0	160.0	335.0	80.0	140.0	410.0	25.0	470.0	mA
ICC - ALL INPUTS AT 2.4V	0.00	1.35	1.35	1.32	1.30	1.36	1.36	1.36	1.38	1.38	1.38	mA
IREF(+) - ALL INPUTS AT 15V	500.0	1.27	1.24	1.27	1.20	1.23	0.90	1.04	1.22	1.08	1.29	2.00
IREF(-) - ALL INPUTS AT 15V	-2.00	-1.30	-1.26	-1.30	-1.23	-1.26	-0.95	-1.06	-1.24	-1.10	-1.32	-500.0
IIL - ALL INPUTS AT 0.0V	-1.00	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	mA
IIL - ALL INPUTS AT 0.8V	-2.00	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	mA
IIH - ALL INPUTS AT 15.0V	-1.00	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	mA
IIH - ALL INPUTS AT 2.4V	-1.00	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	PASS	mA
IZS - ALL INPUTS AT 0.0V	-2.00	-3.00	-3.50	-4.50	-3.50	-3.50	-6.00	-3.00	-3.50	-3.50	-3.00	mA
IZS' - ALL INPUTS AT 2.4V	-2.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	mA
dIZS/dT - INPUTS AT 0.0V	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	PA/OC
dIZS /dT - INPUTS AT 2.4V	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	PA/OC
GAIN ERROR (UFS)	-100.	-32.2	-34.0	-28.6	-37.0	-32.3	-41.7	-45.6	-28.4	-40.2	-29.4	MV
GAIN ERROR (dUFS/dT)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	PPM
PSS - VCC=15V TO 16V	-100.	155.0	321.0	959.0	82.0H	644.0	208.0	191.0	978.0	460.0	1.23	100.
PSS - UCC=15V TO 14V	-100.	-311.0	723.0	390.0	-1.07	805.0	936.0	1.05	162.0	1.26	385.0	PPM
BIT LINEARITY ERROR - MSB	500.0	6.23M	280.0	288.0	121.0	16.50	189.0	362.0	74.50	-227.0	263.0	LSB
BIT LINEARITY ERROR - B2	-500.0	189.0	187.0	7.74M	246.0	322.0	280.0	136.0	318.0	27.7M	500.0	LSB
BIT LINEARITY ERROR - B3	-500.0	-90.0	-16.7M	72.8M	-103.0	-42.4M	-32.9M	-168.0	-88.6M	-32.8M	-111.0	LSB
BIT LINEARITY ERROR - B4	-500.0	2.85M	-122.0	121.0	-32.5M	-137.2M	52.6M	-100.0	-15.5M	-26.1M	24.3M	LSB
BIT LINEARITY ERROR - B5	-500.0	16.8M	-71.9M	62.9M	-37.3M	-38.1M	37.6M	-29.8M	7.12M	52.6M	141.0	LSB
BIT LINEARITY ERROR - B6	-500.0	43.9M	-12.8M	116.0	5.53M	14.6M	22.6M	77.6M	79.6M	132.0	71.6M	LSB
BIT LINEARITY ERROR - B7	-500.0	88.4M	67.1M	121.0	75.2M	64.6M	77.9M	56.1M	-13.6M	5.60M	-23.4M	LSB
BIT LINEARITY ERROR - B8	-500.0	-1.48M	-32.9M	-26.6M	-16.1M	-27.9M	-29.9M	-27.6M	-13.6M	-23.8M	-15.3M	LSB
BIT LINEARITY ERROR - B9	-500.0	2.79M	-27.2M	19.4M	-10.6M	-13.6M	-22.5M	-23.8M	399.0	12.4M	366.0	LSB
BIT LINEARITY ERROR - LSB	-500.0	-3.05M	-12.6M	8.93M	-6.87M	-12.1M	4.36M	-10.1M	15.6M	-17.2M	500.0	LSB
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	277.0	451.0	469.0	369.0	377.0	482.0	489.0	413.0	458.0	437.0	LSB
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	0.00	280.0	776	248	776	326	360	777	289	345	776	DEC
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	-500.0	270.0	451.0	6.00	11.4M	39.7M	484.0	484.0	192.0	163.0	328	LSB
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	-500.0	-205.0	776	776	456	776	361	776	793	379	328	DEC
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	-294.0	-394.0	-328.0	-300.0	-284.0	-308.0	-448.0	-334.0	-413.0	-378.0	LSB
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	-500.0	-199.0	-170.0	268.0	239.0	775	268.0	663	247	931	247	LSB
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	243.0	445.0	373.0	356.0	337.0	309.0	323.0	392.0	420.0	427.0	LSB
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	-500.0	-280.0	776	248	776	326	360	777	289	346	776	DEC
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	-185.0	-413.0	-303.0	-330.0	-312.0	-300.0	-461.0	-320.0	-348.0	-397.0	LSB
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABBREV)	-500.0	-741.0	247	517	247	759	685	247	747	931	247	DEC

NOTE: 1. ZERO (0) IN LIMITS COLUMN MEANS NO LIMIT. IT CAN BE INTERPRETED AS A BASH (-).

Table 5-10. NFR. Code C Data at 25°C.
CROS MULTIPLYING D/A CONVERTER
86 NFR 81 14:57:00

		DEVICE TYPE	I218	UREF = +10V EXCEPT WHERE SPECIFIED	1 LSB = 2.44MV				
		UDD = 15.0 VOLTS	TEMPERATURE = +25 DEGREES C						
	PARAMETER	LO-LIN	S/N 4	S/N 5	S/N 7	S/N 8	S/N 9	HI-LIM	UNITS
ICC	- ALL INPUTS AT 0.0V	0.00	800.0	675.0	755.0	730.0	1.25	2.00	NA
ICC	- ALL INPUTS AT 15.0V	0.00	665.0	730.0	505.0	510.0	2.00	2.00	NA
ICC	- ALL INPUTS AT 0.8V	0.00	760.0	710.0	805.0	730.0	1.20	2.00	NA
ICC	- ALL INPUTS AT 2.4V	0.00	375.0	360.0	420.0	390.0	440.0	2.00	NA
IREF(+)-ALL INPUTS AT 15V	IREF(-)-ALL INPUTS AT 15V	500.0	660.0	620.0	645.0	620.0	620.0	2.00	NA
IIL	- ALL INPUTS AT 0.0V	-2.00	-650.0	-620.0	-655.0	-620.0	-635.0	-500.0	NA
IIL	- ALL INPUTS AT 0.8V	-2.00	PASS	PASS	PASS	PASS	1.00	NA	UA
IIL	- ALL INPUTS AT 15.0V	-2.00	PASS	PASS	PASS	PASS	1.00	NA	UA
IIL	- ALL INPUTS AT 2.4V	-1.00	PASS	PASS	PASS	PASS	1.00	NA	UA
IIZS	- ALL INPUTS AT 0.0V	-2.00	-160.	-160.	-160.	-160.	-160.	200.	NA
IIZS	- ALL INPUTS AT 2.4V	-2.00	-130.	-140.	-135.	-135.	-135.	200.	NA
dIIZS/dt - INPUTS AT 0.0V	dIIZS/dt - INPUTS AT 2.4V	0.00	0.00	350.	21.3K	26.0K	0.00	0.00	PA/OC
GAIN ERROR (VFS)	GAIN ERROR (dVFS/dt)	-100.	-1.92	-2.14	-4.25	-2.16	-1.97	100.	MU
PSS	- UCC-15V TO 16V	-100.	-100.0	-100.0	-100.0	-100.0	-100.0	0.00	PPM
PSS	- UCC-15V TO 14V	-100.	-150.0	-50.0	350.0	150.0	300.0	100.	PPM
BIT LINEARITY ERROR	- MSB	-500.0	179.0	36.6K	197.0	98.3K	50.3K	500.0	LSB
BIT LINEARITY ERROR	- B3	-500.0	-48.2K	-13.1K	129.0	126.3K	126.3K	500.0	LSB
BIT LINEARITY ERROR	- B4	-500.0	-126.0	-177.0	-149.0	-121.0	-259.0	-3.00E-06	LSB
BIT LINEARITY ERROR	- B5	-500.0	-3.95M	-1.95M	-1.84M	-1.72M	-1.72M	75.3K	LSB
BIT LINEARITY ERROR	- B6	-500.0	-7.59M	-2.76M	-2.76M	-7.70M	-6.5K	121.0	LSB
BIT LINEARITY ERROR	- B7	-500.0	-27.9K	-20.6K	-8.97K	-16.9K	-16.9K	33.4K	LSB
BIT LINEARITY ERROR	- B8	-500.0	-105.0	-91.0	-55.0	-111.0	-111.0	-24.8K	LSB
BIT LINEARITY ERROR	- B9	-500.0	5.99M	-3.00M	-1.3M	-1.3M	-1.3M	-13.5K	LSB
BIT LINEARITY ERROR	- B10	-500.0	-500.0	-33.3K	-33.3K	-28.1K	-22.3K	28.1K	LSB
BIT LINEARITY ERROR	- B11	-500.0	-39.1K	-45.0K	-42.0K	-42.0K	-42.0K	500.0	LSB
BIT LINEARITY ERROR	- LS0	-500.0	38.9K	42.4K	42.4K	42.4K	43.8K	500.0	LSB
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	350.0	276.0	492.0	394.0	328.0	500.0	---	LSB
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ABREU)	0.00	209.0	219.0	368.0	327.0	330.0	---	---	DEC
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	322.0	238.0	390.0	381.0	328.0	500.0	---	LSB
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABREU)	0.00	322.0	322.0	395.0	322.0	329.0	---	---	DEC
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	-500.0	-369.0	-367.0	-385.0	-386.0	-257.0	0.00	---	LSB
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABREU)	-500.0	-199.0	-394.5	160.0	872.0	796.0	---	---	DEC
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (ALL CODES)	0.00	188.0	-268.0	-272.0	-390.0	-254.0	0.00	---	LSB
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (ABREU)	0.00	188.0	346.0	266.8	872.0	792.0	---	---	DEC
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (LUREF=-10V)	0.00	0.00	0.00	0.00	0.00	0.00	500.0	---	LSB
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (LUREF=-10V)	0.00	202.5	360.0	160.0	877.0	280.0	---	---	DEC
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (LUREF=-10V)	-500.0	-461.0	-461.0	-631.0	-585.0	-517.0	0.00	---	LSB
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (LUREF=-10V)	-500.0	-267.0	271.0	368.0	321.0	378.0	---	---	DEC
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (LUREF=+1.25V)	0.00	218.0	249.0	294.0	231.0	500.0	---	---	LSB
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (LUREF=+1.25V)	0.00	218.0	183.0	307.0	117.0	71.0	---	---	DEC
MAX(+) LINEARITY ERROR & ASSOC ADDRESS (LUREF=+1.25V)	-500.0	-467.0	-443.0	-589.0	-552.0	-516.0	0.00	---	LSB
MAX(-) LINEARITY ERROR & ASSOC ADDRESS (LUREF=+1.25V)	-500.0	-198.0	342.0	100.0	241.0	813.0	---	---	DEC

NOTE: (1) ZERO (0) IN LIMITS COLUMN MEANS NO LIMIT. IT CAN BE INTERPRETED AS A DASH (-).

VALUE AT 4 FROM ALL752.LOG:752 11:31:18 03 FEB 81
GAIN ERROR (UFS) DEVICE TYPES MIL/127-02

LIMIT

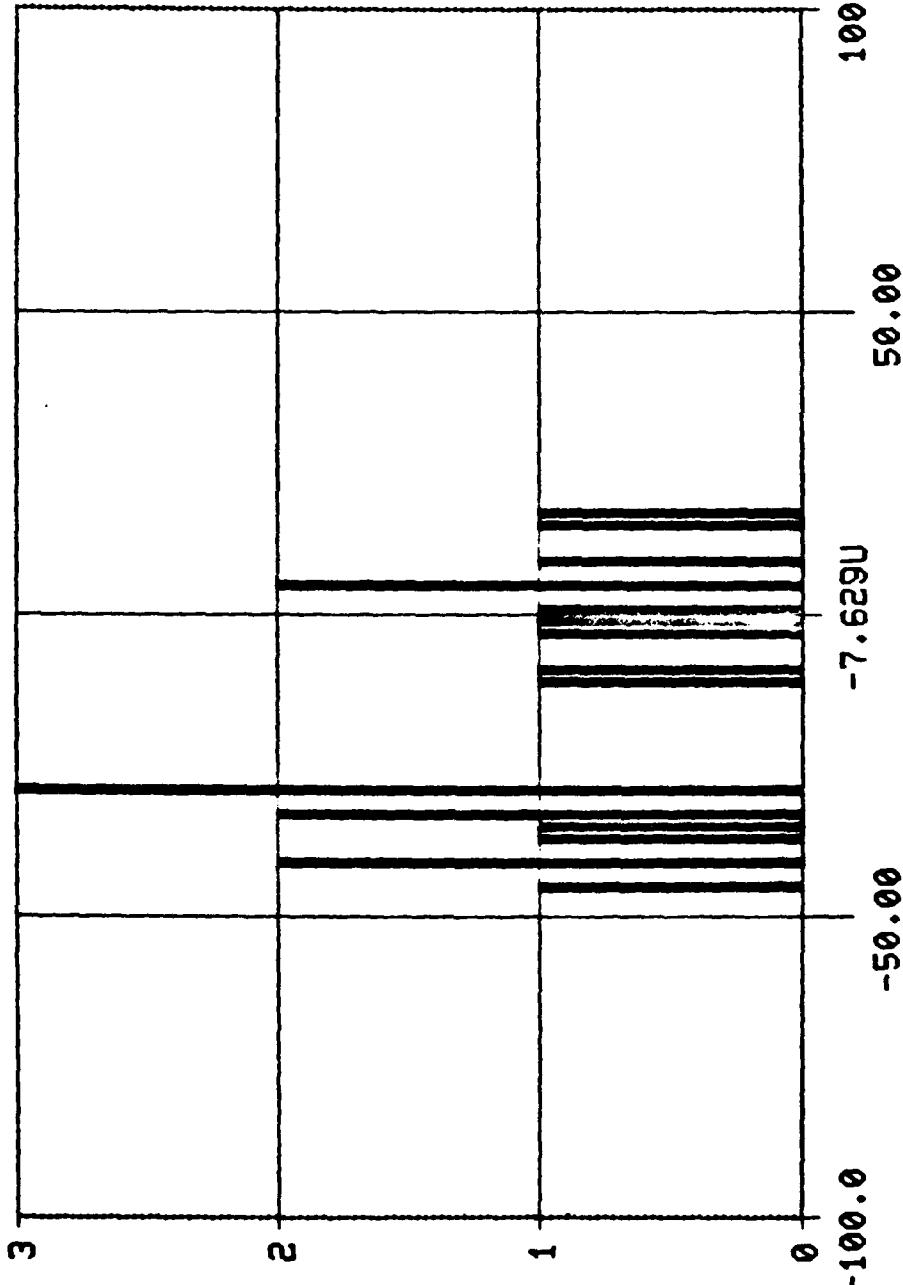
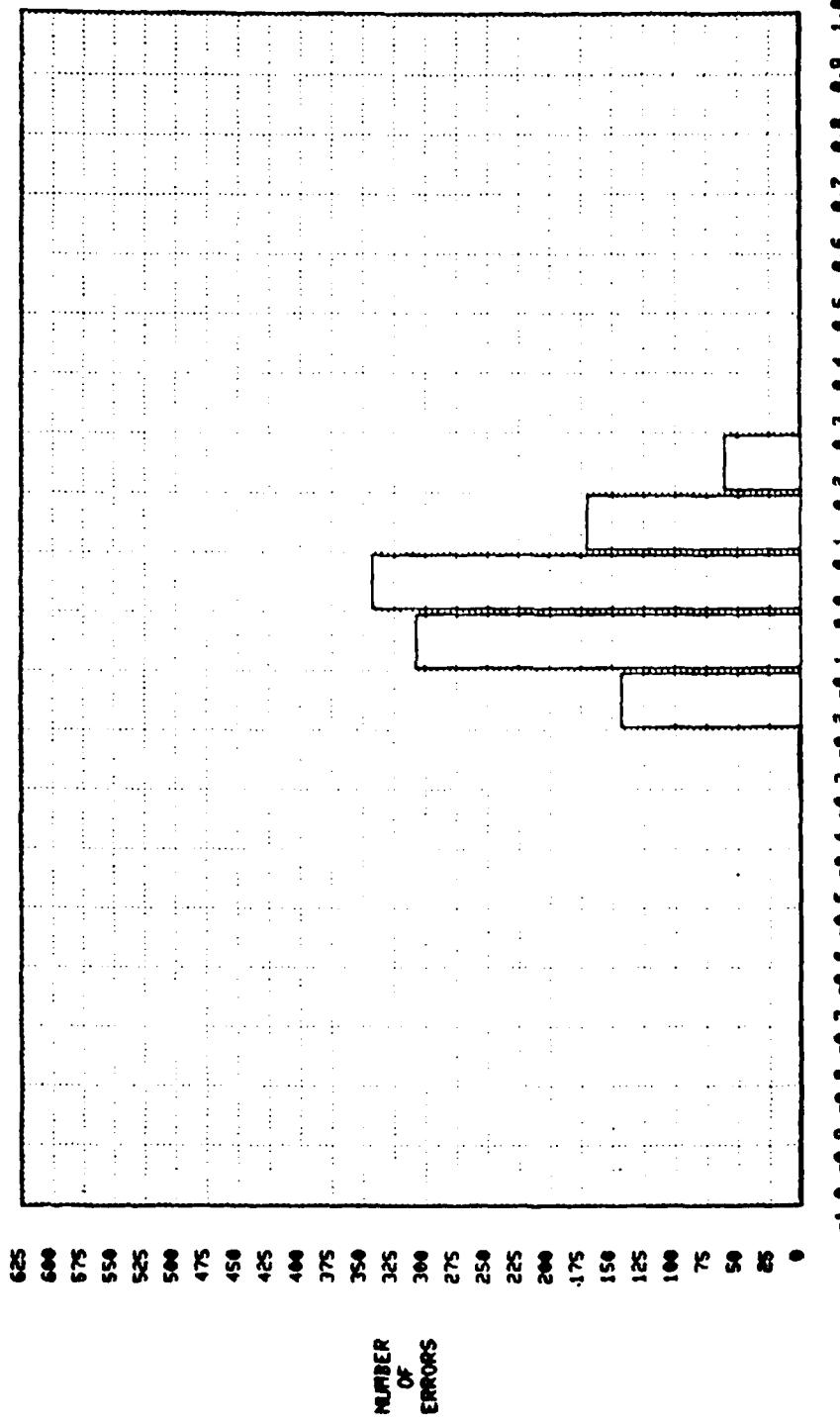


Figure 5-10. Histogram of Gain Error.

FOR DEVICE S/N 31 AT 25 DEG C
VDD=+15.0 VREF=10.0
30 JAN 81

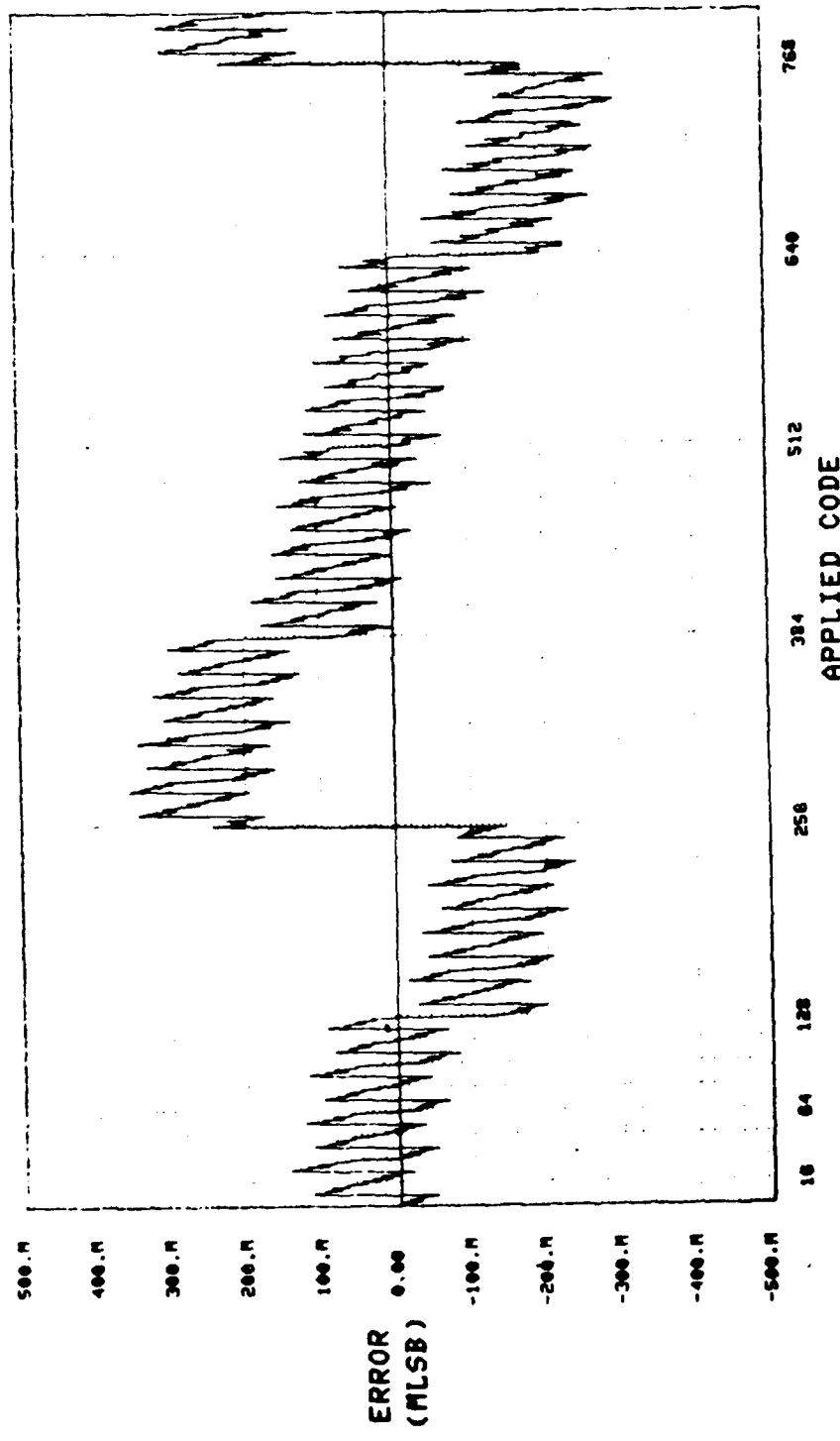


LINEARITY ERROR DISTRIBUTION

7520-10 BIT CMOS D/A CONVERTER

Figure 5-11. Linearity Error Histogram.

FOR DEVICE S/N 31 AT 25 DEG C
VDD=+15.0 V UREF=10.0 V
02 FEB 81

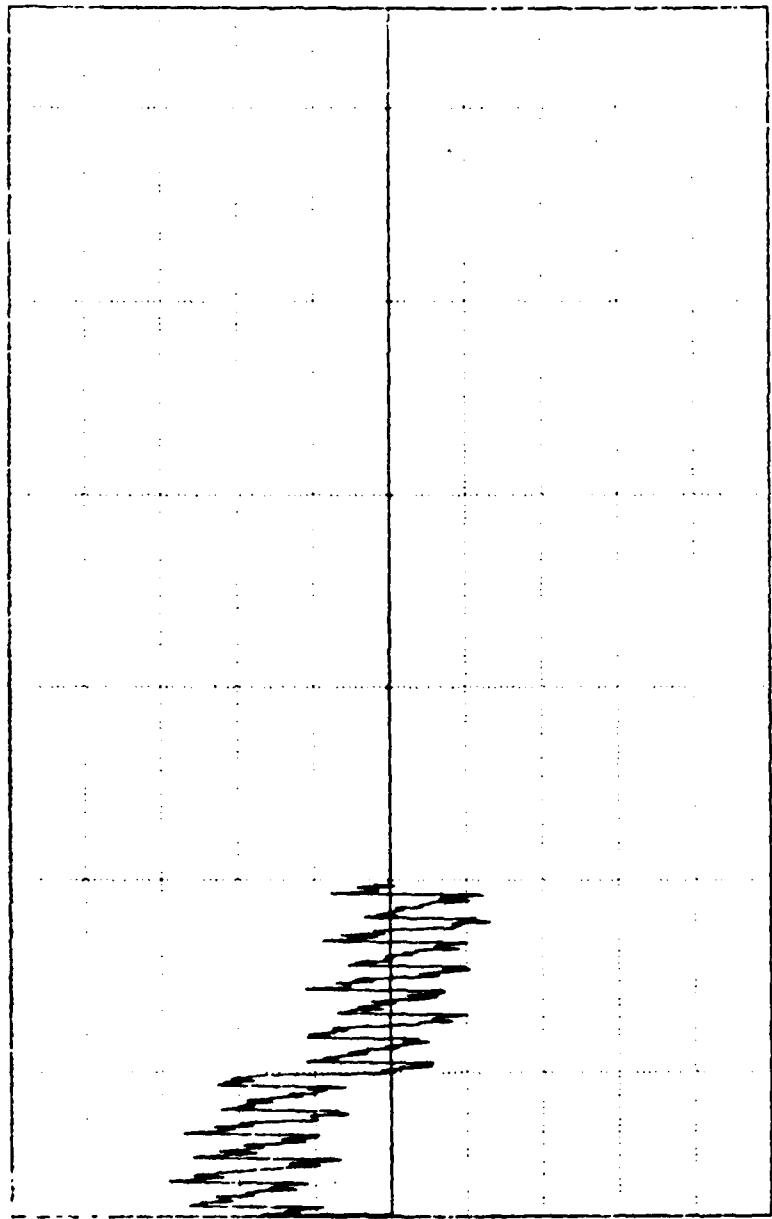


LINEARITY ERROR (ALL CODES)

7520-10 BIT D/A CONVERTER

Figure 5-12. Linearity Error vs Input Code.

FOR DEVICE S/N 31 AT 25 DEG C
VDD=+15.0 V UREF=10.0 V 02 FEB 81



1024 1152 1280 1408 1536

PAGE 2 WORST CASE NEGATIVE BIT ERROR.
WORST CASE POSITIVE BIT ERROR.
-304.5MLSB @ ADDRESS 280
354.8MLSB @ ADDRESS 743

Figure 5-12. Linearity Error vs Input Code. (cont.)

FOR DEVICE S/N 2 AT 25 DEG C
VDD=+15.0 VREF=10.0
02 FEB 81

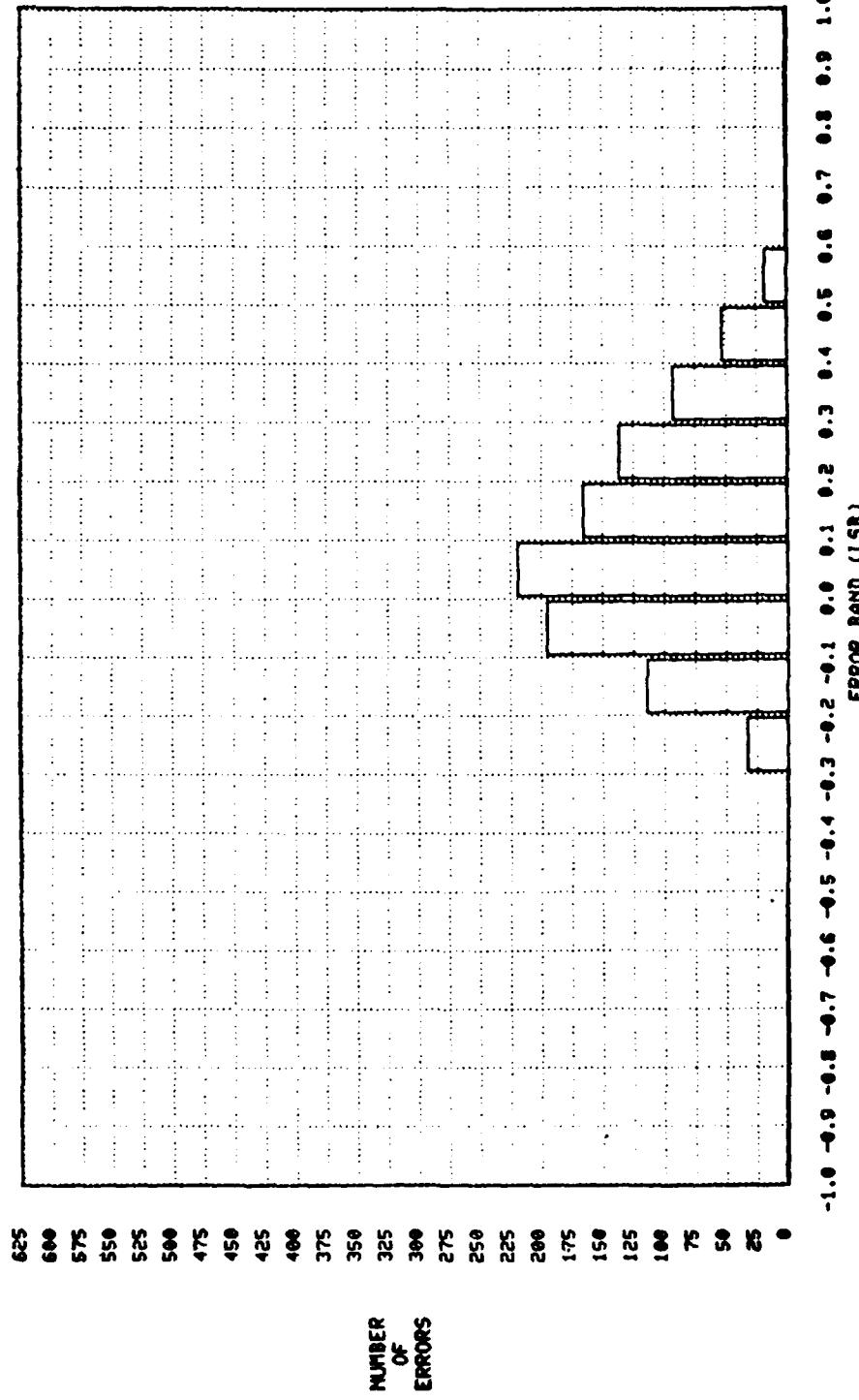
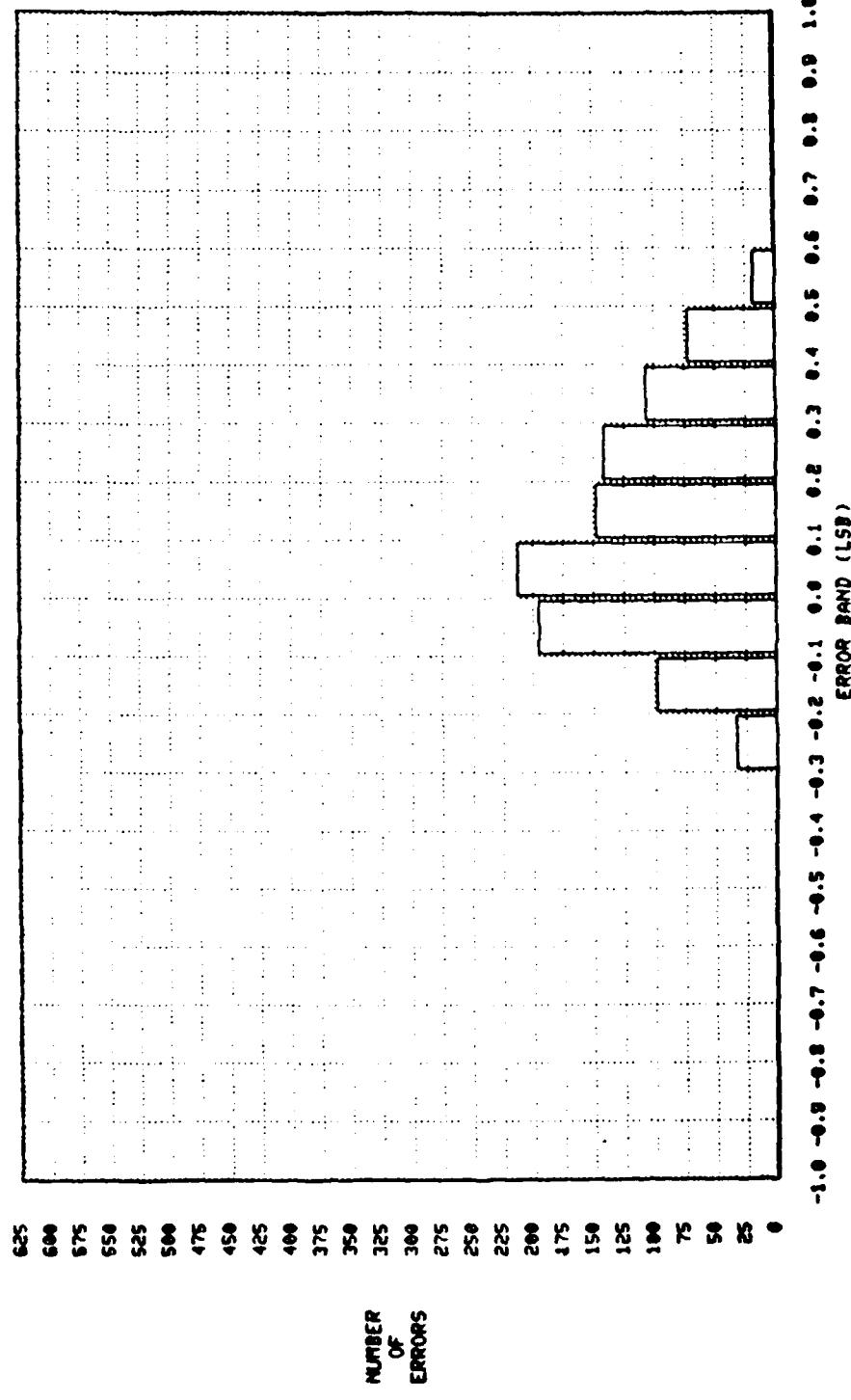


Figure 5-13. Linearity Histogram at VREF = + 10 V.

FOR DEVICE S/N 2 AT 25 DEG C
UDD=+15.0 UREF=-10.0
02 FEB 81



LINEARITY ERROR DISTRIBUTION

7520-10 BIT CMOS D/A CONVERTER

Figure 5-14. Linearity Histogram at VREF = -10 V.

FOR DEVICE S/N 2 AT 25 DEG C
UDD=+15.0 VREF=1.25 02 FEB 81

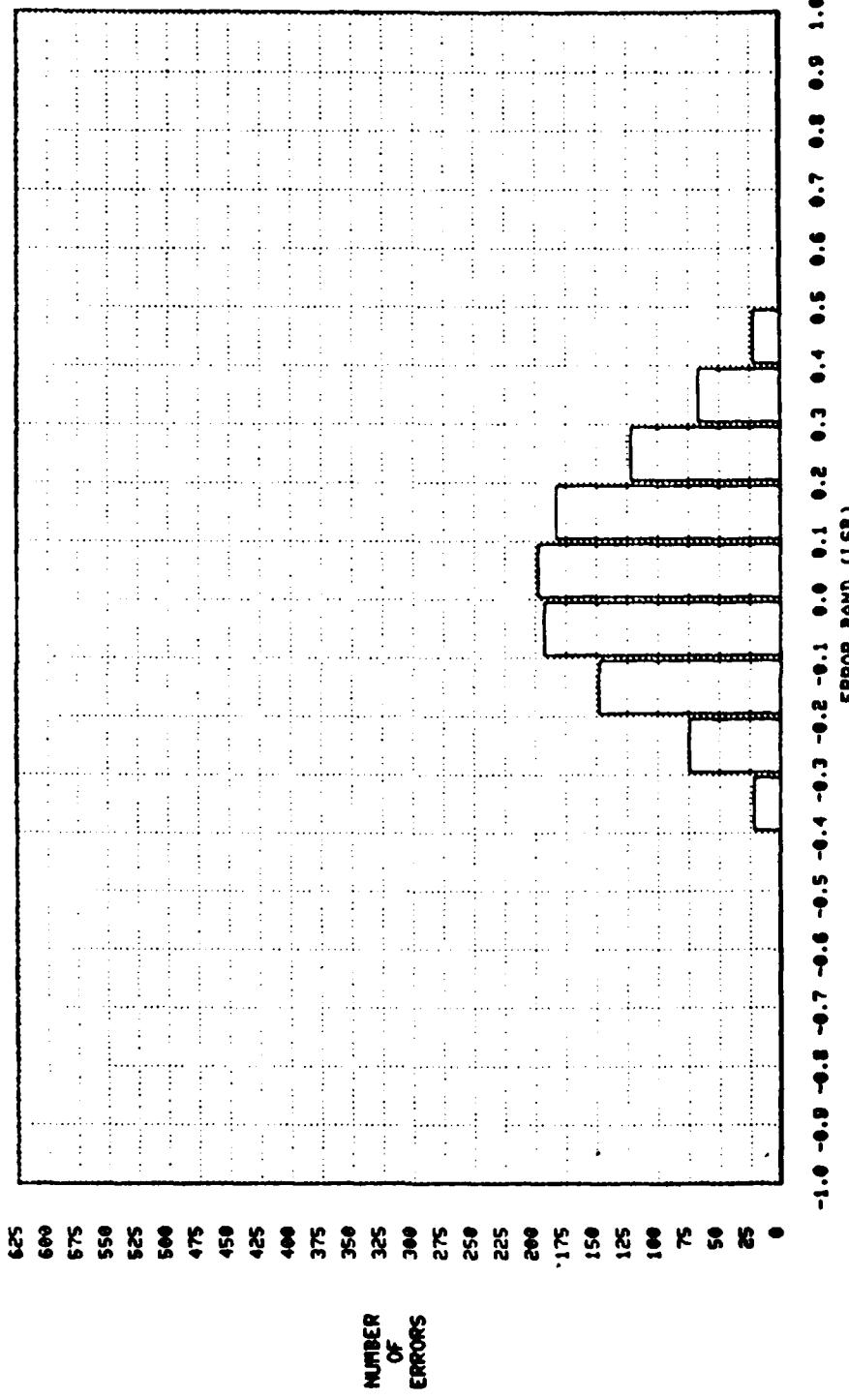
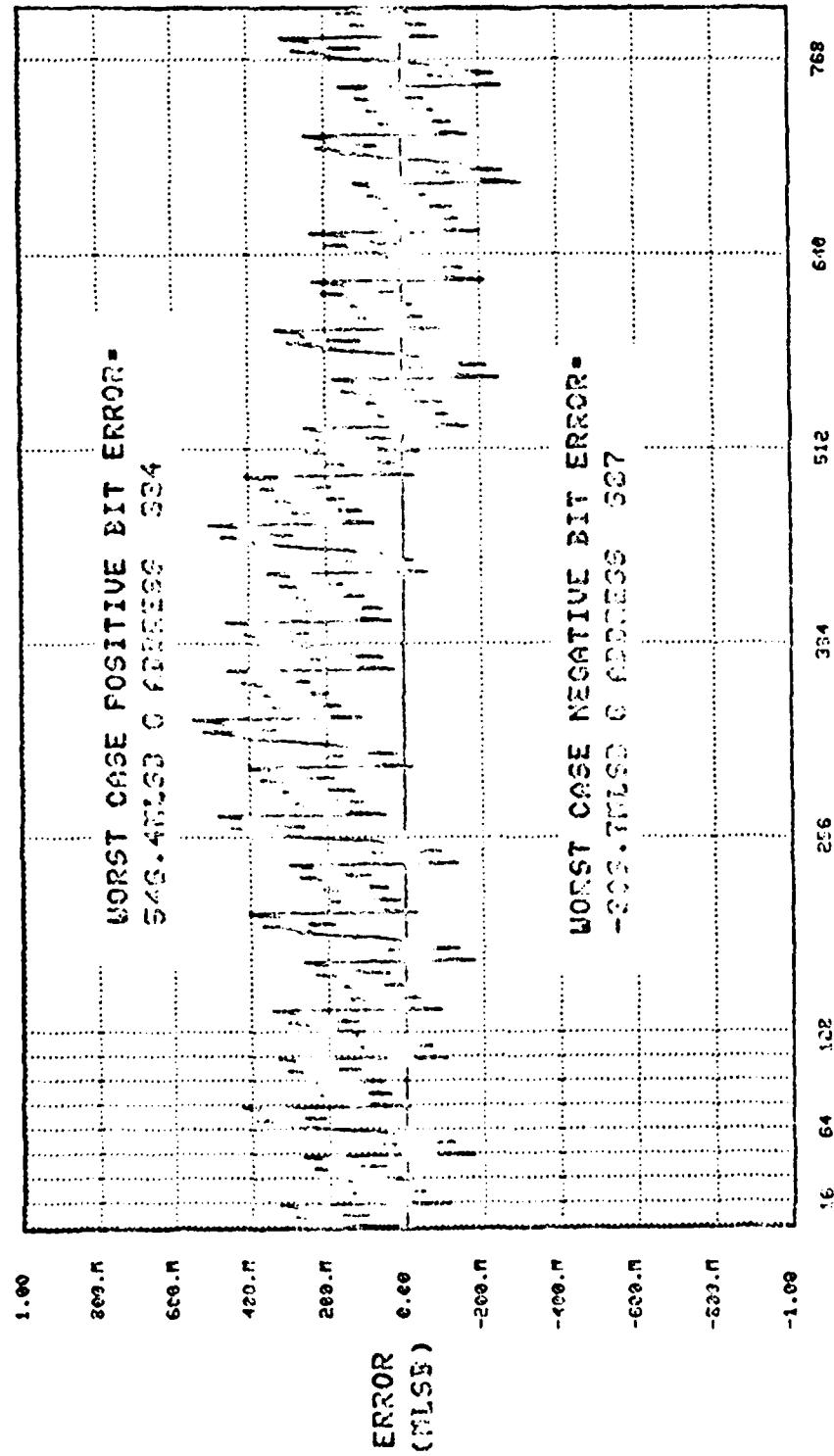


Figure 5-15. Linearity Histogram at V_{REF} = 1.25 V.

FOR DEVICE S/N 10 AT 125 DEG C
VDD=+15.0 V
06 OCT 80



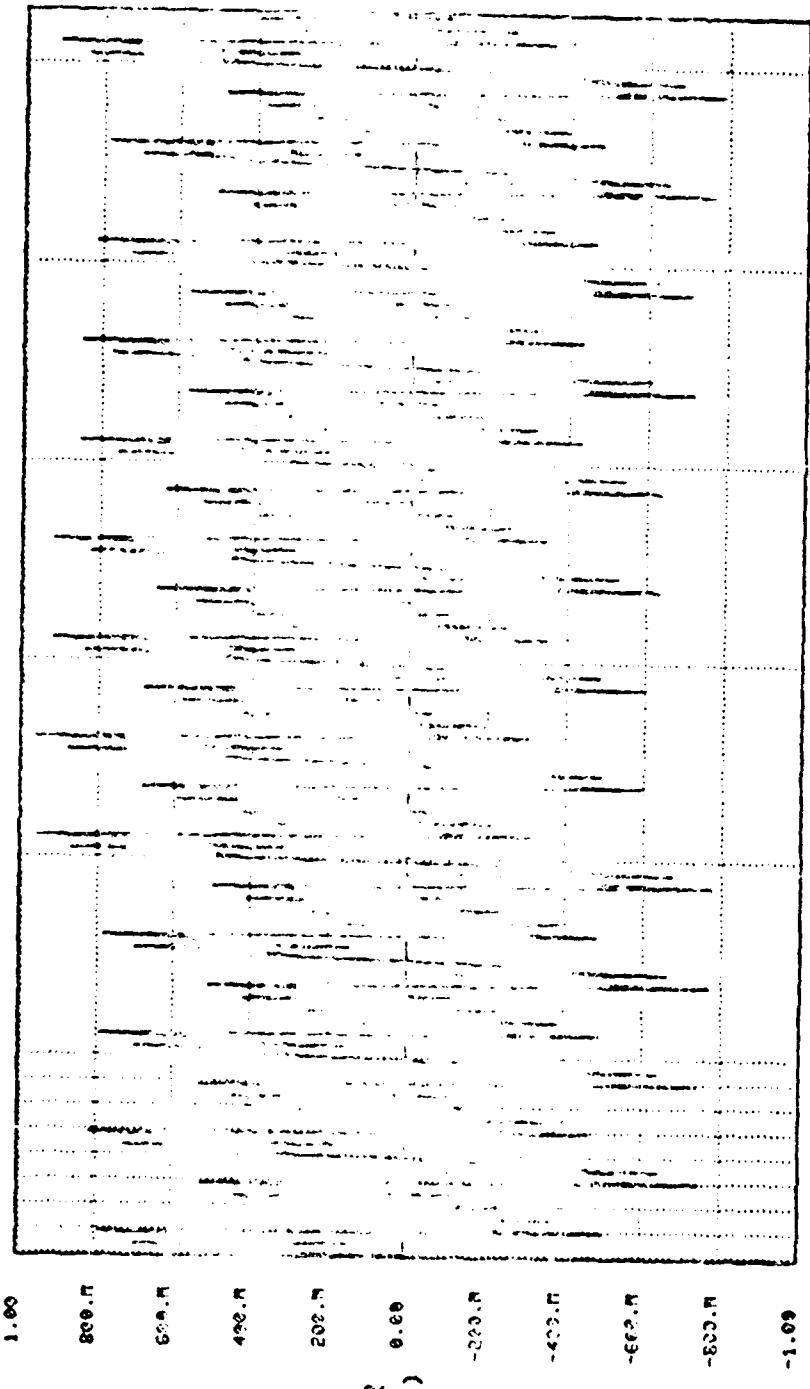
LINEARITY ERROR (ALL CODES)

7520-10 BIT D/A CONVERTER

Figure 5-16. Linearity Plot at $V_{CC} = + 15$ V and $T_A = 125^\circ C$ for S/N 10.

FOR DEVICE S/N 13 AT 125 DEG C
VDD = +5.00 V

06 OCT 80



WORST CASE POSITIVE BIT ERROR =
SG5.211LC0 ADDRESS 334

WORST CASE NEGATIVE BIT ERROR =
-791.9MSB @ ADDRESS 751

APPLIED CODE

LINEARITY ERROR (ALL CODES)

7520-10 BIT D/A CONVERTER

Figure 5-17. Linearity Plot at $V_{CC} = +5$ V and $T_A = 125^\circ C$ for S/N 10.

MIL-M-38510/127
REV - ORIG.
DATE - 1/26/81

Table I. Electrical performance characteristics. 1/

Characteristic	Symbol	Conditions:				Device Type	Limits	Units
		Vcc = + 15V, Vref = + 10V, paragraph 3.4 and Figure 7.	All	Min	Max			
Supply current from Vcc	Icc	All digital inputs at OV	All	-	100	uA		
		All digital inputs at Vcc	All	-	100	uA		
		All digital inputs at 0.8V	All	-	2	mA		
		All digital inputs at 2.4V	All	-	2	mA		
Reference input current	Iref	All digital inputs Vref= 10V at Vcc	All	0.5	2	mA		
		IOUT1 and IOUT2 Vref= -10V grounded	All	-2	-0.5	mA		
Digital input leakage current	IIL	All digital inputs at OV	01-05	-1.0	1.0	uA		
		All digital inputs at 0.8V	06-09	-200	1.0	uA		
	IIL	All digital inputs at Vcc	01-05	-1.0	1.0	uA		
		All digital inputs at 2.4V	06-09	-1.0	100	uA		
Zero scale current	Izs	All digital inputs at 0.8V	All	-200	200	nA		
	Izs'	All digital inputs at 2.4V	All	-200	200	nA		
Zero scale current drift	dIzs/dT	All digital inputs at 0.8V	All	(later) pA/°C				
Full scale error	+dVFS	All digital inputs at Vcc, IOUT2 at OV. Vref = +10V	All	-1	1	%VFS		
	-dVFS	As above with Vref = -10V	All	-1	1	%VFS		
Full scale error drift	dVFS/dT	Change in +dVFS from -25°C to 125°C and from 25°C to -55°C	All	-10	10	ppm VFS/°C		
Power supply sensitivity at full scale from Vcc.	+PSS, -PSS	All digital inputs at Vcc; IOUT2 at OV VCC = + 14V to +16V Measured at IOUT1 and Rf	All	-100	100	ppm VFS/V		

MIL-M-38510/127
REV - ORIG.
DATE - 1/26/81

Table I. Electrical performance characteristics. 1/ (continued)

Characteristic	Symbol	Vcc = + 15V, Vref = + 10V, paragraph 3.4 and Figure 7.	Conditions:			Device Type	Limits	Units
			Min	Max				
Linearity error (end point)	LE	Measure the following: <u>2/</u>	01	-0.2	0.2	%VFS		
		1. All combinations of the most significant four bits with the lower order bits turned off.	02	-.05	.05	%VFS		
		2. The individual lower bits with the most significant four bits turned off.	03	-.05	.05	%VFS		
		3. The code word with the most positive combination of bits in groups 1 & 2 above.	04	-.012	.012	%VFS		
		4. The code words derived from group 3 with all lower order bits complemented one at a time.	05	-.012	.012	%VFS		
		5. The code word with the most negative combination of bits in groups 1 and 2.	06	-.05	.05	%VFS		
		6. The code words derived from group 5 with all lower order bits complemented one at a time.	07	-.05	.05	%VFS		
		7. Groups 1 through 6 with Vref = -10V.	08	-.012	.012	%VFS		
		8. Group 1 through 6 with Vref = 1.25V.	09	-.012	.012	%VFS		
		9. Group A sample - all code combinations of the digital input bits.						
Bit linearity errors (best fit)	LE (BF)	If any end point linearity tests fail, certain devices may be tested to a best fit criteria. The vendor shall specify the criteria (i.e. 3/4 or 7/8 scale adjustment) and repeat all of the linearity tests.	05	-.012	.012	%VFS	09	

Table I. Electrical performance characteristics. 1/ (continued)

Characteristic	Symbol	Conditions:		Device Type	Limits	Units
		Vcc = + 15V, Vref = + 10V, paragraph 3.4 and Figure 7.			Min	Max
Major carry errors (differential linearity)	MCE	The difference between adjacent codes at all major transitions. (i.e. from 0111111 to 10000000)		01	-0.4	0.4 %VFS
				02,03	-0.1	0.1 %VFS
				06,07		
				04,05	-.025	.025 %VFS
				08,09		
Feedthrough error	FTE	Vref=20Vpp, 100kHz and all digital inputs low. TA=25°C, Group D only. See Figure 8.	01-05	-	10	mVpp
			06-09	-	25	mVpp
Output current settling time (to 1/2 LSB)	tSLH	All inputs switched simul- taneously, low to high and	All	-	1	usec
	tSHL	high to low . TA=25°C. See Figure 9. 3/	All	-	1	usec
Output capacitance	Co	All digital inputs at Vcc See Figure 10. Co at IOUT1	All	-	200	pF
		TA = 25°C Co at IOUT2	All	-	75	pF
Output capacitance	Co	All digital inputs at 0V See Figure 10. Co at IOUT1	All	-	75	pF
		TA = 25°C Co at IOUT2	All	-	200	pF
Noise	en	The single source of noise is the resistor network, which characteristically has Johnson or thermal noise. 4/	All	6.5	40	Kohm

Notes:

- 1/ See definitions as described in 6.5.
- 2/ Linearity is specified to be within +/- 1/2 LSB. Thus
an 8 bit device with a 10V reference must have end point
linearity to within 1/2 of $(100\%VFS/2^{exp}8) = 0.195 \%VFS$ or 0.2 %VFS.
- 3/ For each device type, output current settling time is the duration
from the digital input transition until the output for a 10V analog
input transition is within 1/2 LSB of final value.
- 4/ The R-2R resistor network has Johnson or thermal noise. Noise at
the DUT output is related to the noise resistance value according to
 $en = SQR(4KTRn(BW))$
where K = Boltzmann's constant = 1.38×10^{-23} joules/ $^{\circ}\text{K}$
T = Absolute temperature in $^{\circ}\text{K}$
Rn = $Rf(1+Rf/Ro)$ changes with Ro and the digital code word
BW = Bandwidth in Hertz.

MISSION
of
Rome Air Development Center

RADC plans and executes research, development, test and selected acquisition programs in support of Command, Control Communications and Intelligence (C³I) activities. Technical and engineering support within areas of technical competence is provided to ESD Program Offices (POs) and other ESD elements. The principal technical mission areas are communications, electromagnetic guidance and control, surveillance of ground and aerospace objects, intelligence data collection and handling, information system technology, ionospheric propagation, solid state sciences, microwave physics and electronic reliability, maintainability and compatibility.

